

# ★ Multiple Eigenvalues:

Warm up: Find the eigenvalues of the matrix

$$\underline{A} = \begin{bmatrix} 2 & 0 \\ 7 & 2 \end{bmatrix}$$

Ans:  $\det(\underline{A} - \lambda \underline{I}) = 0$

$$\begin{vmatrix} 2-\lambda & 0 \\ 7 & 2-\lambda \end{vmatrix} = (2-\lambda)^2 - 0 \cdot 7 = 0$$

$$\lambda = 2$$

multiplicity  $k=2$

## I. Multiple Eigenvalue Solutions:

In Chap 3, we solved,

$$y'' - 6y' + 9y = 0$$

We can convert to a system of ODE

$$x_1 = y \quad x_2 = y'$$

$$\begin{cases} x_1' = x_2 \\ x_2' = 6x_2 - 9x_1 \end{cases}$$

matrix form:

$$\underline{x}' = \begin{bmatrix} 0 & 1 \\ -9 & 6 \end{bmatrix} \underline{x}$$

these 2 ODEs are equivalent

1D

2D

eqn:  $y'' - 6y' + 9y = 0$

$$\underline{x}' = \begin{bmatrix} 0 & 1 \\ -9 & 6 \end{bmatrix} \underline{x}$$

char eqn

$$r^2 - 6r + 9 = 0$$

$$\begin{vmatrix} -\lambda & 1 \\ -9 & 6-\lambda \end{vmatrix} = 0$$

$$\lambda^2 - 6\lambda + 9 = 0$$

-+5/

$$(r-3)^2 = 0$$

$$(\lambda-3)^2 = 0$$

roots/  
eigenvalues

$$(r-3)^2 = 0$$
$$r = 3$$

multiplicity  $k=2$   
(repeated root)

$$(\lambda-3)^2 = 0$$

$$\lambda = 3$$

algebraic multiplicity  $k=2$   
(repeated eigenvalue)

fundamental  
solns:

$$y_1 = e^{3t}$$

Need a 2nd lin.  
indep soln

→ multiply by  $t$

$$y_2 = te^{3t}$$

$$\lambda = 3$$

$$(\underline{A} - 3\underline{I})\underline{v} = \underline{0}$$

$$\begin{bmatrix} -3 & 1 \\ -9 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-3v_1 + v_2 = 0 \rightarrow v_2 = 3v_1$$

$$\underline{v}^{(1)} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

\* only 1 eigenvector  
geometric multiplicity = 1

Need to find a 2nd  
lin. indep vector  $\underline{u}$

NOTE: when:

geometric  
multiplicity

(# of  
eigenvectors  
corr.  $\lambda$ )

<

algebraic  
multiplicity

(# times  $\lambda$  is  
repeated in char eqn)

We say that the eigenvalue  $\lambda$  is defective

2D example:

one fundamental soln:  $\underline{x}^{(1)} = e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$

Need to find a generalized eigenvector  $\underline{u}$

Need to find a generalized eigenvector  $\underline{u}$

$$\text{Solve: } (\underline{A} - \lambda \underline{I}) \underline{u} = \underline{v}$$

NOTE: this means also solves:

$$(\underline{A} - \lambda \underline{I})^2 \underline{u} = \underline{0}$$

$$(\underline{A} - \lambda \underline{I})^2 \underline{u} = (\underline{A} - \lambda \underline{I}) \underbrace{(\underline{A} - \lambda \underline{I}) \underline{u}}_{=\underline{v}} = (\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}$$

want to solve:

$$(\underline{A} - 3 \underline{I}) \underline{u} = \underline{v}$$

$$\begin{bmatrix} -3 & 1 \\ -9 & 3 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$-3u_1 + u_2 = 1 \rightarrow u_2 = 1 + 3u_1$$

here,  $u_1$  is a free variable

choose  $u_1 = 1$

$$\underline{u} = \begin{bmatrix} u_1 \\ 1 + 3u_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

generalized eigenvector.

Second fundamental solution

$$\underline{x}^{(2)} = e^{3t} (\underline{v}t + \underline{u})$$

$$= e^{3t} \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix} t + \begin{bmatrix} 1 \\ 4 \end{bmatrix} \right\} = e^{3t} \begin{bmatrix} t+1 \\ 3t+4 \end{bmatrix}$$

General solution:

$$\underline{x}(t) = c_1 e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 e^{3t} \begin{bmatrix} t+1 \\ 3t+4 \end{bmatrix}$$

... is a case:

Compare this to 1D case:

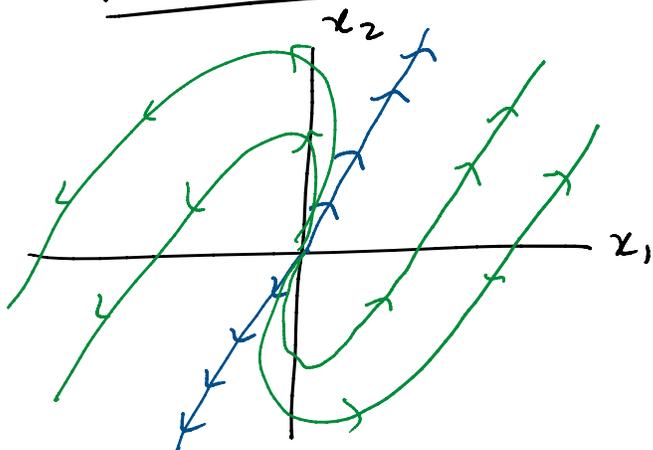
$$y(t) = C_1 e^{3t} + C_2 t e^{3t}$$

$$x_1 = y = B_1 e^{3t} + B_2 (t+1) e^{3t}$$

$$= (B_1 + B_2) e^{3t} + B_2 t e^{3t}$$

equivalent solutions

phase portrait:



improper node

1. Draw eigenvector  
 $\underline{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$

2.  $\lambda = 3 > 0$   
 arrows point out

3. As  $t \rightarrow \infty$   
 $e^{3t} t \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  dominates  
 goes parallel to  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$

II. 3x3 Example:

$$\underline{x}' = \begin{bmatrix} 1 & 3 & -1 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \underline{x}$$

eigen values:  $\det(\underline{A} - \lambda \underline{I}) = 0$

$$\begin{vmatrix} 1-\lambda & 3 & -1 \\ 0 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} - (3) \begin{vmatrix} 0 & 0 \\ 0 & 2-\lambda \end{vmatrix} + (-1) \begin{vmatrix} 0 & 2-\lambda \\ 0 & 0 \end{vmatrix}$$

$$\dots = (1-\lambda) \begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} + (-1) \begin{vmatrix} 0 & 0 \\ 0 & 0 \end{vmatrix}$$

$$= (1-\lambda)[(2-\lambda)^2 - 0] - 3[0-0] + (-1)[0-0]$$

$$= (1-\lambda)(2-\lambda)^2 = 0$$

$\lambda = 1$	alg. mult	$k = 1$
$\lambda = 2$	alg. mult	$k = 2$

eigenvectors:

$$\lambda_1 = 1$$

$$(\underline{A} - \underline{I}) \underline{v} = \underline{0}$$

$$\begin{bmatrix} 0 & 3 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{array}{l} 3v_2 - v_3 = 0 \\ v_2 = 0 \\ v_3 = 0 \end{array}$$

$v_1$  is a free variable, choose  $v_1 = 1$

$$\underline{v}^{(1)} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\lambda_2 = 2$$

$$(\underline{A} - 2\underline{I}) \underline{v} = \underline{0}$$

$$\begin{bmatrix} -1 & 3 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

1 eqn, 3 unknowns  
 $\downarrow$   
 2 free variables

$$-v_1 + 3v_2 - v_3 = 0$$

$$v_1 = 3v_2 - v_3$$

$v_2$  and  $v_3$  are free variables

$$\underline{v} = \begin{bmatrix} 3v_2 - v_3 \\ v_2 \\ v_3 \end{bmatrix}$$

choose  $v_2 = 1, v_3 = 0$

$$\underline{v}^{(2)} = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$$

choose  $v_2 = 0, v_3 = 1$

$$\underline{v}^{(3)} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\underline{v}^{(2)} = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} \quad \longleftrightarrow \quad \underline{v}^{(3)} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

these are linearly indep.

2 linearly indep eigenvectors for  $\lambda_2 = 2$

geometric multiplicity = 2 = algebraic multiplicity

Then the eigenvalue  $\lambda = 2$  is called complete

Do NOT need to find a generalized eigenvector  $\underline{h}$

General solution:

$$\underline{x}(t) = c_1 e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{2t} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

### III Summary: Repeated eigenvalues

$k$  = algebraic mult. = # of times  $\lambda$  is repeated

$p$  = geometric mult = # of lin. indep eigenvectors

case 1	case 2
$p = k$	$p < k$ <span style="float: right;">(<math>k=2</math>)</span>
	is defective

$\lambda$  is complete

eigenvectors  
 $\underline{v}_1, \dots, \underline{v}_p$

gen soln:

$$\underline{x}(t) = c_1 e^{\lambda t} \underline{v}_1 + \dots + c_p e^{\lambda t} \underline{v}_p$$

$\lambda$  is defective

eigen vector  $\underline{v}$   
generalized eigen vector  $\underline{u}$

$$\underline{x}(t) = c_1 e^{\lambda t} \underline{v} + c_2 e^{\lambda t} (t\underline{v} + \underline{u})$$