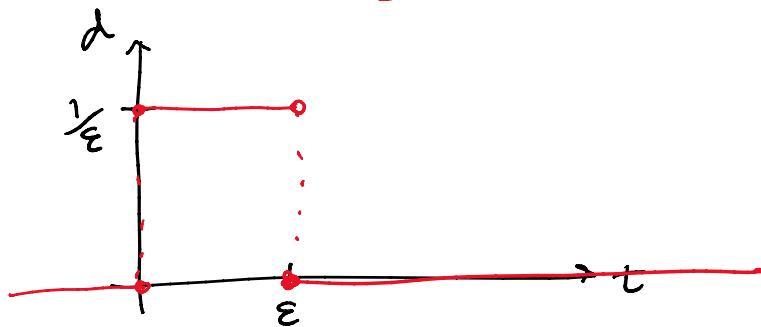


*Impulses & Delta Functions

Warm up: Plot the piecewise continuous function

$$d_\varepsilon(t) = \frac{1}{\varepsilon} [u(t) - u(t-\varepsilon)]$$



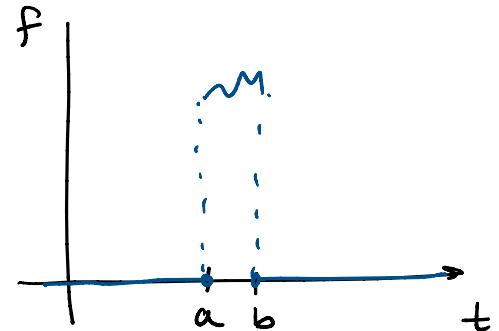
I. Delta Function :

Motivation:

impulsive force

acts on a short time

- e.g. - bat striking a ball
- surge of voltage



The effect depends on the impulse p of the function $f(t)$ over the interval $[a, b]$

$$p = \int_a^b f(t) dt$$

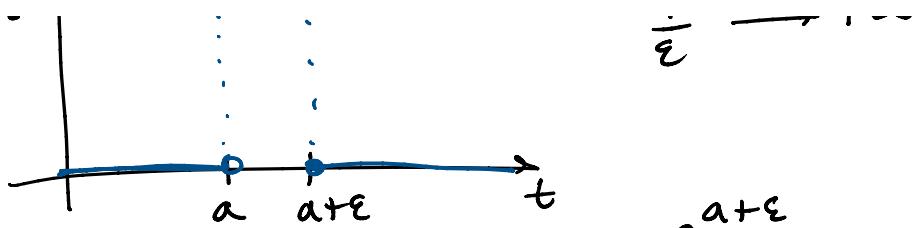
Q: How do we model this?

Def: The unit impulse $d_{a,\varepsilon}(t)$ is defined

$$d_{a,\varepsilon}(t) = \begin{cases} \frac{1}{\varepsilon} & \text{if } a \leq t < a + \varepsilon \\ 0 & \text{otherwise} \end{cases}$$



as $\varepsilon \rightarrow 0$
 $\frac{1}{\varepsilon} \rightarrow +\infty$



$$\text{impulse: } P = \int_0^\infty da, \varepsilon(t) dt = \int_a^{a+\varepsilon} \frac{1}{\varepsilon} dt = \left[\frac{t}{\varepsilon} \right]_a^{a+\varepsilon} = \frac{a+\varepsilon}{\varepsilon} - \frac{a}{\varepsilon} = \frac{\varepsilon}{\varepsilon} = 1$$

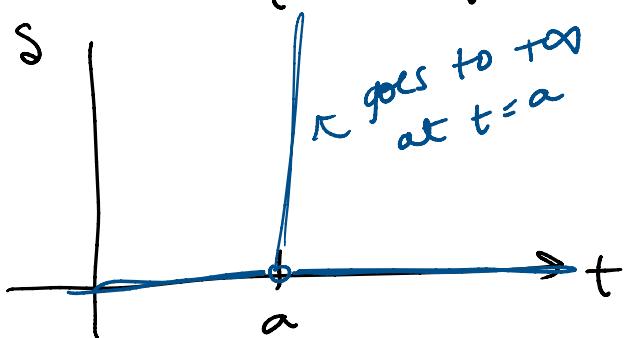
Q: What happens as $\varepsilon \rightarrow 0$?

$$\lim_{\varepsilon \rightarrow 0} da, \varepsilon(t) = \lim_{\varepsilon \rightarrow 0} \begin{cases} 1/\varepsilon & a \leq t < a+\varepsilon \\ 0 & \text{otherwise} \end{cases} = \begin{cases} +\infty & t=a \\ 0 & \text{otherwise} \end{cases} = \delta(t-a)$$

$$\text{impulse } P = \int_0^\infty \delta(t-a) dt = \lim_{\varepsilon \rightarrow 0} \int_0^\infty da, \varepsilon(t) dt = \lim_{\varepsilon \rightarrow 0} 1 = 1$$

Def: The Dirac delta function is $\delta(t-a)$

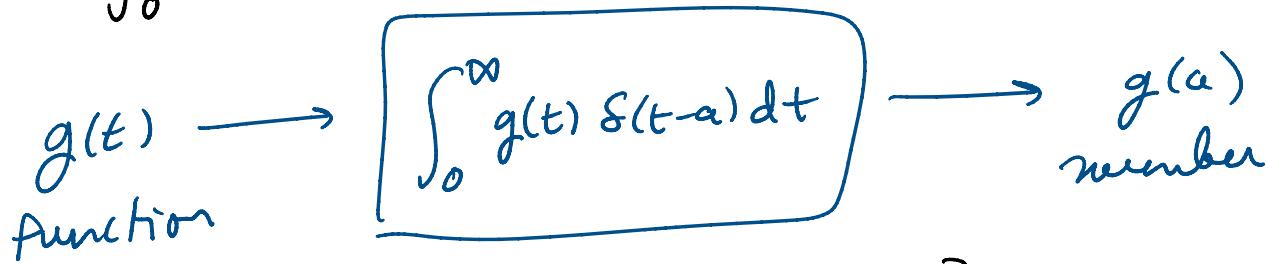
$$\delta(t-a) = \begin{cases} +\infty & \text{if } t=a \\ 0 & \text{if } t \neq a \end{cases} \text{ and } \int_0^\infty \delta(t-a) dt = 1$$



NOTE: $\delta(t-a)$ is not really a function because of

NOTE: $\delta(t-a)$ is not really a function
but it is a useful idea because of
the following property

$$\int_0^\infty g(t) \delta(t-a) dt = g(a) \quad \text{picks out the value of } g \text{ at } t=a$$



Q: What is $\mathcal{L}\{\delta(t-a)\} = ?$

plugging in def:

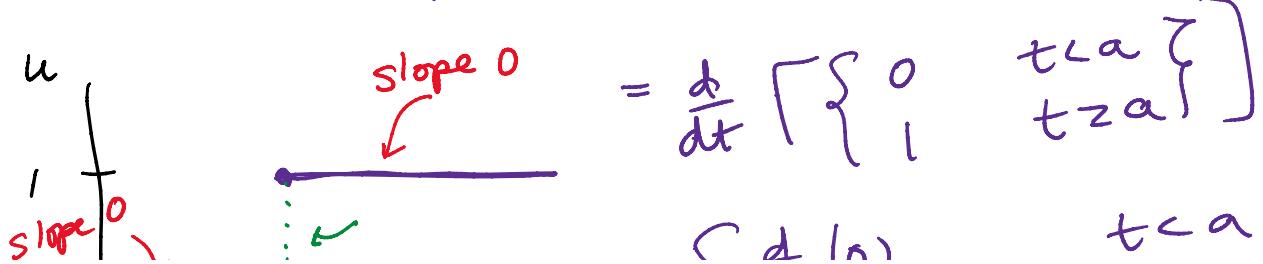
$$\mathcal{L}\{\delta(t-a)\} = \int_0^\infty e^{-st} \delta(t-a) dt = \left[e^{-st} \right] \Big|_{t=a}$$

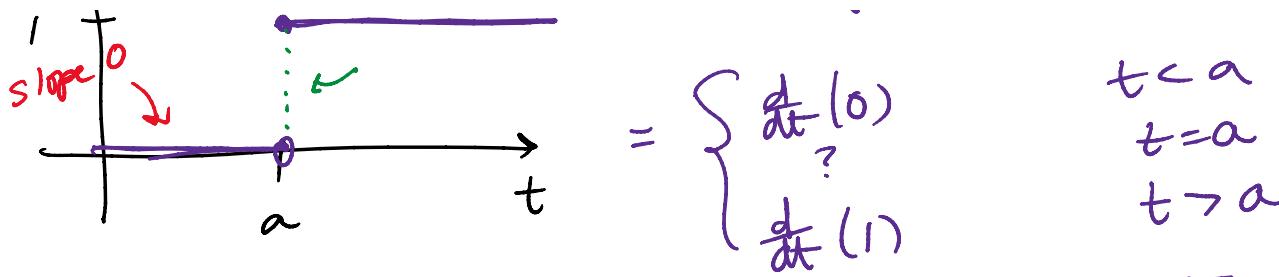
$$= e^{-as}$$

$$\boxed{\mathcal{L}\{\delta(t-a)\} = e^{-as}}$$

NOTE: We can also think of the Dirac delta as the derivative of the unit step function

$$\delta(t-a) = \left\{ \begin{array}{ll} +\infty & t=a \\ 0 & t \neq a \end{array} \right\} = \frac{d}{dt} [u(t-a)]$$





$$\lim_{h \rightarrow 0} \frac{s(a+h) - s(a-h)}{2h}$$

$$\lim_{h \rightarrow 0} \frac{1-0}{2h} = +\infty$$

$$\begin{aligned} &= \begin{cases} 0 & t < a \\ +\infty & t = a \\ 0 & t > a \end{cases} \\ &= \begin{cases} +\infty & t = a \\ 0 & t \neq a \end{cases} = \delta(t-a) \end{aligned}$$

use the fact $\delta(t-a) = \frac{d}{dt} [u(t-a)]$

$$\begin{aligned} \mathcal{L}\{\delta(t-a)\} &= \mathcal{L}\left\{\frac{d}{dt}[u(t-a)]\right\} \\ &= s \mathcal{L}\{u(t-a)\} - u(0)^{\cancel{0}} \\ &= s \left[\frac{e^{-as}}{s} \right] = e^{-as} \quad \checkmark \end{aligned}$$

II. IVPs:

GOAL: solve IVPs w/ forcing terms that are Dirac delta functions

Ex: $x'' + 4x = \delta(t-\pi)$ $x(0) = x'(0) = 0$

@ $t=\pi$ there's an impulse

1. Take the L.T. of both sides

$$\mathcal{L}\{x''\} + 4\mathcal{L}\{x\} = \mathcal{L}\{\delta(t-\pi)\}_{-\pi s}$$

$$[s^2 X(s) - 0 \cdot s - 0] + 4X(s) = e$$

2. Solve for $X(s)$

$$(s^2 + 4) X(s) = e^{-\pi s}$$

$$X(s) = \frac{e^{-\pi s}}{s^2 + 4}$$

exponentially
→ a unit step func

3. Take the inverse L.T.

$$\mathcal{L}^{-1}\{X(s)\} = \mathcal{L}^{-1}\left\{e^{-\pi s} \left(\frac{1}{s^2+4}\right)\right\}$$

$$= \frac{1}{2} \mathcal{L}^{-1}\left\{e^{-\pi s} \left(\frac{2}{s^2+4}\right)\right\}$$

$\underbrace{G(s)}_{g(t) = \sin(2t)}$

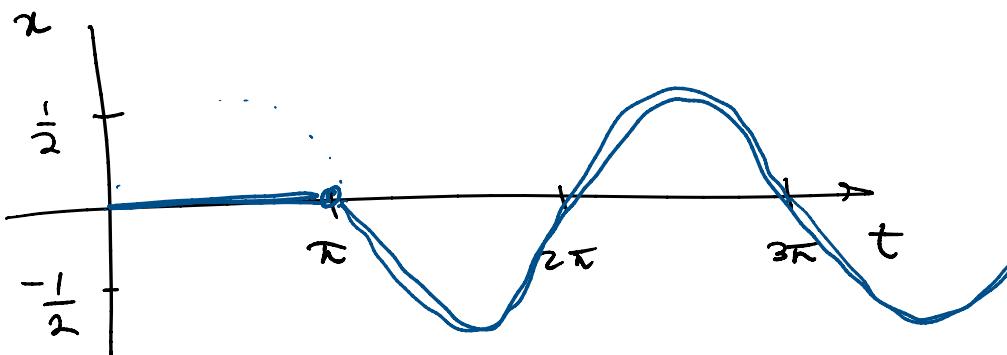
$$= \frac{1}{2} u(t-\pi) g(t-\pi)$$

$$= \frac{1}{2} \sin(2(t-\pi)) u(t-\pi)$$

$$= \frac{1}{2} \sin(2t-2\pi) u(t-\pi)$$

because
 $\sin(2t)$ is
periodic

$$x(t) = \boxed{\frac{1}{2} \sin(2t) u(t-\pi)}$$



III. Duhamel's Principle:

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III. Duhamel's Principle:

Consider a physical system by ODE:

$$ax'' + bx' + cx = f(t) \quad x(0) = x'(0) = 0$$

$x(t)$ — output or response
 $f(t)$ — input

1. Take the L.T. of both sides

$$a[s^2 X(s) - 0 \cdot s - 0] + b[s X(s) - 0] + c X(s) = F(s)$$

$$(as^2 + bs + c) X(s) = F(s)$$

2. Solve for $X(s)$

$$X(s) = \frac{F(s)}{as^2 + bs + c} = F(s) \left(\frac{1}{as^2 + bs + c} \right)$$

$\underbrace{\qquad\qquad\qquad}_{W(s)}$

$$X(s) = F(s) W(s)$$

$$W(s) = \frac{1}{as^2 + bs + c}$$

transfer function
of the system

$$w(t) = \mathcal{L}^{-1}\{W(s)\}$$

weight function

3. Take the inverse L.T.

→ use the convolution property

$$x(t) = \mathcal{L}^{-1}\{W(s)F(s)\} = (w * f)(t)$$

$\boxed{x(t) = \int_0^t w(\tau) f(t-\tau) d\tau}$

$$\tilde{x}(t) = \int_0^t w(\tau) f(t-\tau) d\tau$$

This is called Duhamel's Principle

Key step to solving the IVP: is finding

$$w(t) = \mathcal{L}^{-1} \{ W(s) \} = \mathcal{L}^{-1} \left\{ \frac{1}{as^2 + bs + c} \right\}$$

Ex: Apply Duhamel's Principle to write an integral formula for solution to the IVP

$$x'' + 6x' + 10 = f(t) \quad x(0) = x'(0) = 0$$

1. Take the L.T.

$$s^2 X + 6sX + 10X = F(s)$$

2. Solve for $X(s)$

$$(s^2 + 6s + 10) X(s) = F(s)$$

$$X(s) = F(s) \left(\frac{1}{s^2 + 6s + 10} \right)$$

$$\text{here } W(s) = \frac{1}{s^2 + 6s + 10} = \frac{1}{(s+3)^2 + 1}$$

3. Take the inverse L.T.

$$w(t) = \mathcal{L}^{-1} \left\{ \frac{1}{(s+3)^2 + 1} \right\} \leftarrow \begin{array}{l} \text{Translation} \\ \text{on } s\text{-axis} \\ \text{Then} \end{array}$$

$$= e^{-3t} \mathcal{L}^{-1} \left\{ \frac{1}{s^2+1} \right\}$$

$$w(t) = e^{-3t} \sin(t)$$

So, by Duhamel's Principle

$$x(t) = \mathcal{L}^{-1} \{ f(s) w(s) \} = (w * f)(t)$$

$$x(t) = \int_0^t e^{-3\tau} \sin(\tau) f(t-\tau) d\tau$$

IV. Final Exam Archives

Fall 2008: #13

Find the solution of the IVP
 $y'' - 3y' + 2y = \delta(t-2)$, $y(0)=0$, $y'(0)=1$

1. Take the L.T. of both sides

$$\mathcal{L}\{y''\} - 3\mathcal{L}\{y'\} + 2\mathcal{L}\{y\} = \mathcal{L}\{\delta(t-2)\}$$

$$[s^2 Y - s y(0) - y'(0)] - 3[sY - y(0)] + 2Y = e^{-2s}$$

$$[s^2 Y - 1] - 3(sY) + 2Y = e^{-2s}$$

$$(s^2 - 3s + 2) Y(s) - 1 = e^{-2s}$$

2. Solve for $Y(s)$

$$(s^2 - 3s + 2) Y(s) = 1 + e^{-2s}$$

$$Y(s) = \frac{1 + e^{-2s}}{s^2 - 3s + 2}$$

$$Y(s) = \frac{1 + e^{-s}}{s^2 - 3s + 2}$$

3. Take $\mathcal{L}^{-1}\{ \cdot \}$

$$y(t) = \mathcal{L}^{-1} \left\{ \frac{1 + e^{-2s}}{(s-2)(s-1)} \right\} \leftarrow \begin{matrix} \text{factor} \\ \text{denom.} \end{matrix}$$

$$\text{linearity} = \mathcal{L}^{-1} \left\{ \underbrace{\frac{1}{(s-2)(s-1)}}_{G(s)} \right\} + \mathcal{L}^{-1} \left\{ e^{-2s} \left(\underbrace{\frac{1}{(s-2)(s-1)}}_{G(s)} \right) \right\}$$

$$G(s) = \frac{1}{(s-2)(s-1)}$$

$$g(t) = \mathcal{L}^{-1} \{ G(s) \}$$

$$\text{then } y(t) = g(t) + u(t-2) g(t-2)$$

could use partial fractions

$$g(t) = \mathcal{L}^{-1} \left\{ \frac{1}{(s-2)(s-1)} \right\}$$

use convolution property

$$\frac{1}{(s-2)(s-1)} = H(s) K(s)$$

$$H(s) = \frac{1}{s-2} \quad h(t) = e^{2t}$$

$$K(s) = \frac{1}{s-1} \quad k(t) = e^t$$

$$g(t) = \mathcal{L}^{-1} \left\{ H(s) K(s) \right\} = (h * k)(t) \quad \leftarrow \text{convolution property}$$

$$= \int_0^t e^{2\tau} e^{t-\tau} d\tau = e^t \int_0^t e^{2\tau-t} d\tau$$

$$= e^t \int_0^t e^\tau d\tau = e^t [e^\tau]_0^t = e^t [e^t - 1]$$

$$g(t) = e^{2t} - e^t$$

$$g(t) = e^{2t} - e^t$$

$$y(t) = g(t) + u(t-2)g(t-2)$$

$$= e^{2t} - e^t + u(t-2)[e^{2(t-2)} - e^{t-2}]$$

$$\boxed{y(t) = e^{2t} - e^t + u(t-2)[e^{2t-4} - e^{t-2}]} \quad (D)$$