

★ Impulses & Delta Functions

I. Delta Functions:

Motivation — impulsive force — acts during a short time

- e.g. — bat striking a ball
- surge of voltage

The effect depends on:

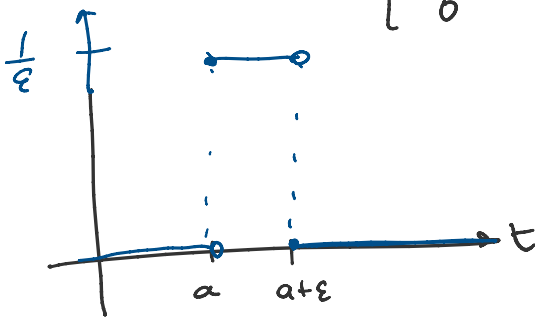
$$p = \int_a^b f(t) dt$$

the impulse of the force $f(t)$ over the interval $[a, b]$

Q: How do we model this?

Def: The unit impulse $d_{a, \epsilon}(t)$ is

$$d_{a, \epsilon}(t) = \begin{cases} \frac{1}{\epsilon} & \text{if } a \leq t < a + \epsilon \\ 0 & \text{otherwise} \end{cases}$$



as $\epsilon \rightarrow 0$
 $\frac{1}{\epsilon} \rightarrow \infty$

$$p = \int_0^{\infty} d_{a, \epsilon}(t) dt = \int_a^{a+\epsilon} \frac{1}{\epsilon} dt = \epsilon \cdot \frac{1}{\epsilon} = 1$$

Q: What about instantaneous

$$\delta_a(t) = \lim_{\epsilon \rightarrow 0} d_{a, \epsilon}(t) = \lim_{\epsilon \rightarrow 0} \begin{cases} 1/\epsilon & a \leq t < a + \epsilon \\ 0 & \text{else} \end{cases}$$

$$\delta_a(t) = \begin{cases} +\infty & \text{if } t = a \\ 0 & \text{if } t \neq a \end{cases}$$

$$\delta_a(t) = \begin{cases} \infty & \text{if } t = a \\ 0 & \text{if } t \neq a \end{cases}$$

$$P = \int_0^{\infty} \delta_a(t) dt = \lim_{\epsilon \rightarrow 0} \int_0^{\infty} \mathcal{A}_{a,\epsilon}(t) dt = \lim_{\epsilon \rightarrow 0} 1 = 1$$

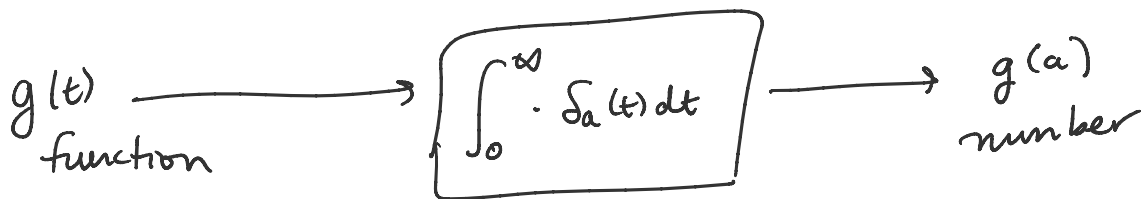
Def: The Dirac delta function is $\delta_a(t)$

$$\delta_a(t) = \begin{cases} \infty & \text{if } t = a \\ 0 & \text{if } t \neq a \end{cases} \text{ and } \int_0^{\infty} \delta_a(t) dt = 1$$

Think of it as an operator

$$\int_0^{\infty} g(t) \delta_a(t) dt = g(a)$$

↑
picks out the value at $t = a$



Ex: $\int_0^{\infty} e^{-st} \delta_a(t) dt = e^{-as}$

~~~~~  
this is definition of the L.T.

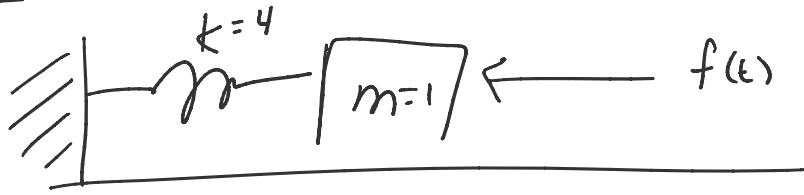
$$\boxed{\mathcal{L}\{\delta_a(t)\} = e^{-as} \quad a > 0}$$

Note: we call  $\delta(t) = \delta_0(t)$  the Dirac delta at 0

$$\mathcal{L}\{\delta(t)\} = e^{-0 \cdot s} = 1$$

$$\boxed{\mathcal{L}\{\delta(t)\} = 1}$$

Ex: Mass on a Spring



at  $t=2\pi$   
the mass is struck  
by a hammer  
impulse  $p=8$

$$x'' + 4x = 8 \delta_{2\pi}(t) = 8 \delta(t-2\pi) \quad x(0)=3 \quad x'(0)=0$$

Take the L.T. of both sides

$$(s^2 X - 3s - 0) + 4X = 8 \mathcal{L}\{\delta_{2\pi}(t)\} = 8e^{-2\pi s}$$

$$(s^2 + 4)X - 3s = 8e^{-2\pi s}$$

$$(s^2 + 4)X = 3s + 8e^{-2\pi s}$$

$$X(s) = \frac{3s}{s^2+4} + \frac{8e^{-2\pi s}}{s^2+4}$$

$$x(t) = \mathcal{L}^{-1}\left\{\frac{3s}{s^2+4}\right\} + \mathcal{L}^{-1}\left\{\frac{8e^{-2\pi s}}{s^2+4}\right\} \quad f(s) = \frac{2}{s^2+4}$$

$$f(t) = \sin(2t)$$

$$= 3 \mathcal{L}^{-1}\left\{\frac{s}{s^2+4}\right\} + 4 \mathcal{L}^{-1}\left\{\left(\frac{2}{s^2+4}\right) e^{-2\pi s}\right\}$$

$F(s) e^{-2\pi s} \leftarrow$  translation on the  $t$ -axis

$$= 3 \cos(2t) + 4 u(t-2\pi) \sin(2(t-2\pi))$$

$$= 3 \cos(2t) + 4 u(t-2\pi) \sin(2t)$$

$$= \begin{cases} 3 \cos(2t) & t < 2\pi \\ 3 \cos(2t) + 4 \sin(2t) & t \geq 2\pi \end{cases}$$

We can simplify the 2nd term

$$3 \cos(2t) + 4 \sin(2t) = R \cos(2t - \alpha)$$

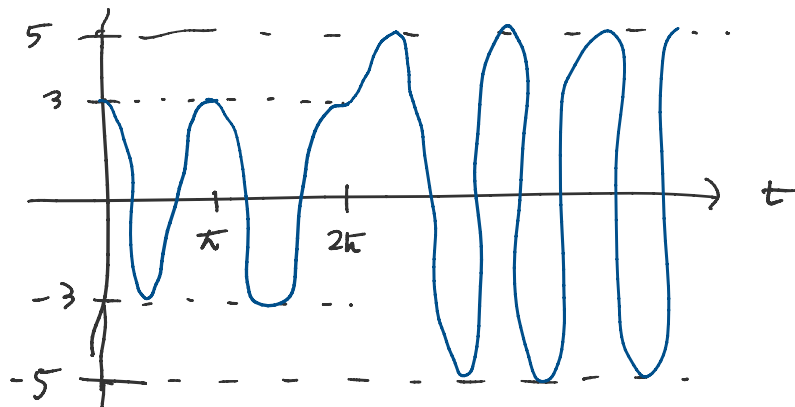
$$R = \sqrt{3^2 + 4^2} = 5$$

$$\dots -1, 2, 1 \sim n. 9273$$

$$R = \sqrt{3^2 + 4^2} = 5$$

$$\alpha = \tan^{-1}(4/3) \approx 0.9273$$

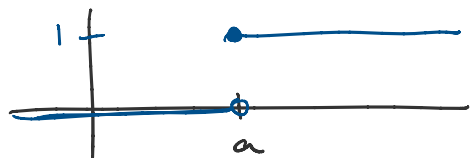
$$x(t) = \begin{cases} 3 \cos(2t) & t < 2\pi \\ 5 \cos(2t - \alpha) & t \geq 2\pi \end{cases}$$



@  $t = 2\pi$   
Instantaneously  
the amplitude  
increases  
from 3 to 5.

Note:  $\frac{d}{dt} u_a(t) = \begin{cases} 0 & t < a \\ \infty & t = a \\ 0 & t > a \end{cases} = \delta_a(t)$

$$u_a(t) = \begin{cases} 0 & t < a \\ 1 & t \geq a \end{cases}$$



$\delta_a(t)$  is the derivative of  $u_a(t)$

Ex: RLC circuit in Lecture 13

$$L \frac{di}{dt} + Ri + \frac{1}{C} q = e(t)$$

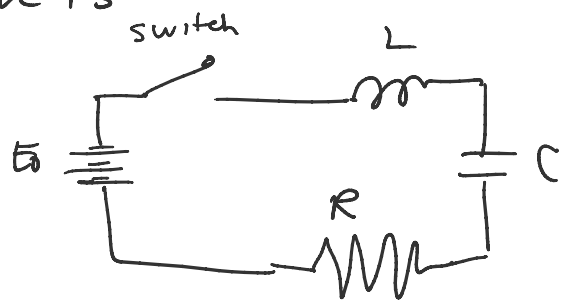
$$i = \frac{dq}{dt}$$

$$L \frac{d^2i}{dt^2} + R \frac{di}{dt} + \frac{1}{C} i = e'(t)$$

$$L = 1 \quad R = 110 \quad C = 0.001$$

$$e(t) = 90 - 90 u(t-1)$$

$$e'(t) = -90 \frac{d}{dt} u(t-1) = -90 \delta_1(t)$$



$$e(t) = \dots$$

$$e'(t) = -90 \frac{d}{dt} u(t-1) = -90 \delta_1(t)$$

Now:  $i'' + 110i' + 1000i = -90 \delta_1(t) \quad i(0)=0 \quad i'(0)=90$

Take L.T. of both sides

$$(s^2 I - 0 \cdot s - 90) + 110(sI - 0) + 1000I = -90e^{-s}$$

$$(s^2 + 110s + 1000)I - 90 = -90e^{-s}$$

$$I(s) = \frac{90(1 - e^{-s})}{(s+10)(s+100)}$$

this is the same as in Lec 13

## II. Duhamel's Principle

Consider a physical system

$$ax'' + bx' + cx = f(t)$$

$$x(0) = x'(0) = 0$$

$x(t)$  — output or response

$f(t)$  — input

Take L.T. of both sides

$$as^2 X + bsX + cX = F(s)$$

$$X(s) = \frac{F(s)}{as^2 + bs + c} = W(s)F(s)$$

$$W(s) = \frac{1}{as^2 + bs + c} \quad \text{transfer function of the system}$$

$$w(t) = \mathcal{L}^{-1}\{W(s)\} \quad \text{weight function}$$

use convolution property

use convolution.

$$x(t) = \mathcal{L}^{-1} \{ W(s) F(s) \} = w(t) * f(t)$$

$$x(t) = \int_0^t w(\tau) f(t-\tau) d\tau$$

Duhamel's Principle

key step:  $w(t) = \mathcal{L}^{-1} \{ W(s) \}$

Ex:  $x'' + 6x' + 10x = f(t)$        $x(0) = x'(0) = 0$

$$s^2 X + 6sX + 10X = F(s)$$

$$X(s) = \frac{F(s)}{s^2 + 6s + 10}$$

$$W(s) = \frac{1}{s^2 + 6s + 10} = \frac{1}{(s+3)^2 + 1}$$

$$w(t) = \mathcal{L}^{-1} \{ W(s) \} = e^{-3t} \sin(t)$$

So, By Duhamel's Principle

$$x(t) = \int_0^t e^{-3\tau} \sin(\tau) f(t-\tau) d\tau$$