

HW + A1 due Today @ 11:59pm  
Office Hours Today @ 2:30-3:30pm

★ Section 6.2 - Part 1  
Linear & Almost Linear Systems

Warm up:

Recall the Taylor Series of a function  $f(x)$  at the point  $x=0$  is defined by:

$$f(x) \approx f(0) + x f'(0) + \frac{1}{2} x^2 f''(0) + \dots + \frac{x^n}{n!} f^{(n)}(0) + \dots$$

Find the first 3 terms of the Taylor Series of  
 $f(x) = x^2 + 3e^x$

Ans:  $f(x) \approx f(0) + x f'(0) + \frac{1}{2} x^2 f''(0)$

$$f(0) = [x^2 + 3e^x] \Big|_{x=0} = 0 + 3e^0 = 3$$

$$f'(0) = [2x + 3e^x] \Big|_{x=0} = 3$$

$$f''(0) = [2 + 3e^x] \Big|_{x=0} = 5$$

$$f(x) \approx \boxed{3 + 3x + \frac{5}{2}x^2}$$

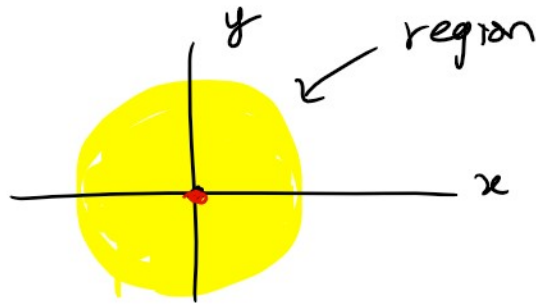
I, Stability of Linear Systems:

$$\begin{bmatrix} x \\ y \end{bmatrix}' = \underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_{\underline{A}} \begin{bmatrix} x \\ y \end{bmatrix}$$

- the origin  $(0,0)$  is always a critical point
- If  $\det(\underline{A}) = ad - bc \neq 0$ , then the origin

- If  $\det(\underline{A}) = ad - bc \neq 0$ , then the origin is an isolated critical point

there is a small region around  $(0,0)$  where it is the only c.p.



The characteristic eqn:  $\det(\underline{A} - \lambda \underline{I}) = 0$   
 $\lambda^2 - T\lambda + D = 0$

$$T = \text{trace}(\underline{A}) = a + d$$

$$D = \det(\underline{A})$$

The eigenvalues

$$\lambda = \frac{T}{2} \pm \frac{1}{2} \sqrt{T^2 - 4D}$$

We can classify the critical point  $(0,0)$

$\lambda$	Type of c.p.	stable?
real, distinct same sign	improper node	yes if both $\lambda < 0$ (asymp. stable)
real, distinct opposite sign	saddle point	NO
real, equal	proper or improper node	Yes, if $\lambda < 0$ (asymp. stable)

complex conjugate $a \pm bi$	spiral point	yes if $\text{Re}(\lambda) < 0$ (asympt. stable)
pure imaginary $\pm bi$	center	yes
$\lambda_1 = 0, \lambda_2 \neq 0$	parallel lines	yes if $\lambda_2 < 0$

Thm: (Stability of Linear Systems)

Let  $\lambda_1$  and  $\lambda_2$  be the eigenvalues of  
 $\underline{x}' = \underline{A}\underline{x}$  where  $\det(\underline{A}) \neq 0$

Then, the critical point  $(0,0)$  is:

1. Asymptotically stable if  $\text{Re}(\lambda) < 0$
2. stable if  $\text{Re}(\lambda) = 0$
3. unstable otherwise

By looking at the eigenvalues  $\lambda$ , we can assess the stability of  $(0,0)$

Ex: 
$$\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & -1 \\ 6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$D = \det(\underline{A}) = (-1)(2) - 6(-1) = 4$$

$D \neq 0$  so  $(0,0)$  is an isolated c.p.

$$T = \text{trace}(\underline{A}) = -1 + 2 = 1$$

Char. eqn. 
$$\lambda^2 - T\lambda + D = 0$$
  

$$\lambda^2 - \lambda + 4 = 0$$

char. eqn.

$$\lambda^2 - \lambda + 4 = 0$$

$$\lambda = \frac{1}{2} \pm \frac{1}{2} \sqrt{(-1)^2 - 4 \cdot 1 \cdot 4} = \frac{1}{2} \pm \frac{\sqrt{15}}{2} i$$

$$\operatorname{Re}(\lambda) = \operatorname{Re}\left(\frac{1}{2} \pm \frac{\sqrt{15}}{2} i\right) = \frac{1}{2} > 0 \quad \text{unstable}$$

and  $(0,0)$  is a spiral source

Ex: 
$$\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -4 & 1 \\ -6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$D = \det(A) = -4(2) - 1(-6) = -2$$

$D \neq 0$  so  $(0,0)$  is isolated

$$T = \operatorname{trace}(A) = -4 + 2 = -2$$

char. eqn.

$$\lambda^2 - T\lambda + D = 0$$

$$\lambda^2 + 2\lambda - 2 = 0$$

$$\lambda = \frac{-2}{2} \pm \frac{1}{2} \sqrt{2^2 - 4 \cdot (-2)}$$

$$= -1 \pm \frac{1}{2} \sqrt{12} = -1 \pm \sqrt{3}$$

$$\lambda_1 = -1 + \sqrt{3} > 0$$

$$\lambda_2 = -1 - \sqrt{3} < 0$$

$\operatorname{Re}(\lambda_1) > 0 \rightarrow$  unstable  
saddle point.

## II, Small Perturbations:

Q: What happens if we perturb a system by a little bit  $\varepsilon$ ? (assume  $\varepsilon \ll 1$ )

Ex:  $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & -1+\epsilon \\ 6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

still linear

$$D = \det(\underline{A}) = (-1)(2) - 6(-1+\epsilon) = -2 + 6 - 6\epsilon = 4 - 6\epsilon \neq 0 \quad \text{so } (0,0) \text{ is isolated}$$

$$T = \text{trace}(\underline{A}) = -1 + 2 = 1$$

Char. eqn:  $\lambda^2 - T\lambda + D = 0$

$$\lambda^2 - \lambda + 4 - 6\epsilon = 0$$

$$\begin{aligned} \lambda &= \frac{1}{2} \pm \frac{1}{2} \sqrt{(-1)^2 - 4 \cdot 1 \cdot (4 - 6\epsilon)} \\ &= \frac{1}{2} \pm \frac{1}{2} \sqrt{1 - 16 + 24\epsilon} \\ &= \frac{1}{2} \pm \frac{1}{2} \sqrt{-15 + 24\epsilon} \end{aligned}$$

Q: is  $-15 + 24\epsilon > 0$

$$24\epsilon > 15$$

$$\epsilon > \frac{15}{24} = \frac{5}{8}$$

but  $\epsilon \ll 1 \Rightarrow \Leftarrow$

No,  $-15 + 24\epsilon < 0$

eigenvalues  $\lambda = \frac{1}{2} \pm bi$

so  $(0,0)$  is unstable and spiral source

remains

...  $\epsilon \gg 1$

$\epsilon \ll 1$   
if  $\epsilon < \frac{1}{10}$

remains  
even after the perturbation  $\epsilon \gg 1$

NOTE: In most cases, a small perturbation of  $\Delta$  will NOT change the stability of the system

However, a perturbation can change the type of critical point (see A2)

### III, Almost Linear Systems:

The Taylor series expansion of a function of two variables  $f(x, y)$  at a point  $(x_0, y_0)$  is defined

$$f(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) + r(x - x_0, y - y_0)$$

$$\text{where } f_x(x_0, y_0) = \left. \frac{\partial f}{\partial x} \right|_{(x_0, y_0)}$$

$$f_y(x_0, y_0) = \left. \frac{\partial f}{\partial y} \right|_{(x_0, y_0)}$$

and  $r(x, y)$  is called the remainder  
 $r(x, y) \sim O(x^2 + y^2)$

If  $x$  and  $y$  are small, then  $r(x, y)$  is an order of magnitude smaller

$$\text{So } f(x, y) \approx f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

Ex: Find the Taylor series at  $(0,0)$  of  
 $f(x,y) = x^3y - \sin(2x) + e^y$

Ans:  $f(0,0) = 0 - \sin(0) + e^0 = 1$

$$\frac{\partial f}{\partial x}(0,0) = \left[ 3x^2y - 2\cos(2x) \right] \Big|_{(0,0)} = -2$$

$$\frac{\partial f}{\partial y}(0,0) = \left[ x^3 + e^y \right] \Big|_{(0,0)} = 1$$

so  $f(x,y) \approx 1 + (-2)(x-0) + (1)(y-0)$   
 $\approx 1 - 2x + y$

*these terms are now linear*

GOAL: Use Taylor series to linearize a nonlinear system around a critical point.

Ex:  $x' = F(x,y)$       let  $(x_*, y_*)$  is a critical point of the system  
 $y' = G(x,y)$

By definition  $F(x_*, y_*) = 0$   
 $G(x_*, y_*) = 0$

Now, let's Taylor expand  $F$  and  $G$  around  $(x_*, y_*)$

$$x' = F(x,y) = F(x_*, y_*) + F_x(x_*, y_*)(x-x_*) + F_y(x_*, y_*)(y-y_*) + r(x,y)$$

$$y' = G(x,y) = G(x_*, y_*) + G_x(x_*, y_*)(x-x_*) + G_y(x_*, y_*)(y-y_*) + s(x,y)$$

*b/c  $(x_*, y_*)$  is a critical point*

*small if  $x-x_* < 1$   
 ...*

b/c  $(x_*, y_*)$  is a critical point

small if  $x - x_* < \epsilon$   
 $y - y_* < \epsilon$

In matrix form:

$$(*) \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} F_x(x_*, y_*) & F_y(x_*, y_*) \\ G_x(x_*, y_*) & G_y(x_*, y_*) \end{bmatrix} \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix} + \begin{bmatrix} r(x, y) \\ s(x, y) \end{bmatrix}$$

J - Jacobian matrix

very small near  $(x_*, y_*)$

This is called the almost linear system  
 let  $x_1 = x - x_*$  and  $x_2 = y - y_*$   
 $x_1' = x'$                        $x_2' = y'$

$$(D) \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} \underline{J} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

we call this the associated linear system

We can consider the almost linear system (\*) is a perturbation of the linear system (D)

Q: What can the linear system (D) tell us about the almost linear system (\*)?

Thm: The almost linear system (\*) will have the same type of critical point and the same stability as the linear system (D)

UNLESS     $\lambda_1 = \lambda_2$     or     $\lambda = \pm bi$

★ Summary!



## ★ Summary!

- a nonlinear system

$$x' = F(x, y)$$

$$y' = G(x, y)$$

has a critical point  $(x_*, y_*)$  when

$$F(x_*, y_*) = 0 = G(x_*, y_*)$$

- Use Taylor series to get the almost linear system

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \underbrace{\begin{bmatrix} F_x(x_*, y_*) & F_y(x_*, y_*) \\ G_x(x_*, y_*) & G_y(x_*, y_*) \end{bmatrix}}_{\underline{\underline{J}} - \text{Jacobian matrix}} \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix} + \begin{bmatrix} r(x, y) \\ s(x, y) \end{bmatrix}$$

- Find the associated linear system and evaluate the type and stability of the c.p.

$$\underline{\underline{x}}' = \underline{\underline{J}} \underline{\underline{x}}$$

$$\text{where } \underline{\underline{x}} = \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix}$$