

# Final Exam Review

Types of functions, equations, and operations :

Type	Input	Output
single variable function $f(x)$	scalar	scalar
function of several variables $f(x,y,z)$	point / vector	scalar
vector-valued function $\vec{r}(t)$	scalar	point / vector
vector field $\vec{F}(x,y,z)$	point / vector	point / vector
dot product	two vectors	scalar
cross product	two vectors	vector
gradient $\text{grad } f = \nabla f$	function of sev. var.	vector field
divergence $\text{div } \vec{F} = \nabla \cdot \vec{F}$	vector field	function of sev. var
curl $\text{curl } \vec{F} = \nabla \times \vec{F}$	vector field	vector field
* $\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\rangle$ or $\left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$		

## Types of Integrals:

- $\int_{x=a}^{x=b} f(x) dx$  - Calc 1 integral
- $\int \vec{v}(t) dt$  - The **ONLY** time you should integrate a vector!  
(position, velocity, acceleration)
- $\int_C f ds$  - Line integral over curve C.  
-  $f$  is scalar-valued ( $f(x,y)$  or  $f(x,y,z)$ )

How to compute:

Parameterize  $C$  with  $\vec{r}(t)$  for  $a \leq t \leq b$ .

Since  $ds = |\vec{r}'(t)| dt$ , you can compute:

$$\int_a^b f(\vec{r}(t)) |\vec{r}'(t)| dt$$

- $\int_C \vec{F} \cdot d\vec{r}$
- |  |   |
|--|---|
| $= \int_C \vec{F} \cdot \vec{T} ds$                                    | - Line integral over curve $C$ .  |
| $\quad \quad \quad \text{z unit tangent}$                              | - $\vec{F}$ is a vector field ( $\vec{F}(x,y) = \langle f_1, g_1 \rangle$ or $\vec{F}(x,y,z) = \langle f_1, g_1, h_1 \rangle$ ) |
| $= \int_C f dx + g dy$   | - If $C$ is <u>closed</u> , $\oint_C \vec{F} \cdot d\vec{r} = \oint_C \vec{F} \cdot \vec{T} ds$                                 |
| $\quad \quad \quad \text{if } \vec{F} = \langle f_1, g_1 \rangle$      | is called the <u>circulation</u> .  |
| $= \int_C f dx + g dy + h dz$  |   |
| $\quad \quad \quad \text{if } \vec{F} = \langle f_1, g_1, h_1 \rangle$ |   |

How to compute:

- If  $\vec{F}$  is conservative and  $C$  starts at  $A$  and ends at  $B$ , you can find a potential function  $\varphi$  such that  $\vec{F} = \nabla \varphi$ . Then the Fundamental Theorem of Line Integrals says:

$$\textcircled{1} \quad \int_C \vec{F} \cdot d\vec{r} = \varphi(B) - \varphi(A) \rightarrow \text{path independent!}$$



- If  $C$  is closed and  $\vec{F} = \langle f(x,y), g(x,y), h(x,y,z) \rangle$ , use Green's Theorem:

$$\textcircled{2} \quad \oint_C \vec{F} \cdot d\vec{r} = \iint_R (g_x - f_y) dA$$

( $C$  encloses region  $R$ ;  $g_x - f_y$  is 2D-curl)

- If  $C$  is closed and  $\vec{F} = \langle f(x,y,z), g(x,y,z), h(x,y,z) \rangle$ , use Stokes' Theorem:

$$\textcircled{3} \quad \oint_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot d\vec{S}$$

( $C$  is the boundary curve of  $S$ )

\* If  $\vec{F}$  is conservative and  $C$  is closed, ①, ②, or ③ will give you  $\oint_C \vec{F} \cdot d\vec{r} = 0$ .

- If  $\vec{F}$  is not conservative and  $C$  is not closed, compute directly. Parameterize  $C$  with  $\vec{r}(t)$  for  $a \leq t \leq b$ .

$$\int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \vec{T} ds = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

$\downarrow$  unit tangent  $\frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$

If  $\vec{F} = \langle f, g \rangle$ :

$$\int_C f dx + g dy = \int_a^b f(\vec{r}(t)) x'(t) dt + g(\vec{r}(t)) y'(t) dt$$

↖ No do f  
Product and ↗  
no abs. values

If  $\vec{F} = \langle f, g, h \rangle$ :

$$\begin{aligned} \int_C f dx + g dy + h dz \\ = \int_a^b f(\vec{r}(t)) x'(t) dt + g(\vec{r}(t)) y'(t) dt + h(\vec{r}(t)) z'(t) dt \end{aligned}$$

- $\int_C \vec{F} \cdot \vec{n} ds$  - Flux across a curve.  
-  $\vec{F}$  is a vector field.

How to compute:

- If  $C$  is not closed and  $\vec{F} = \langle f, g \rangle$ ,

$$\int_C \vec{F} \cdot \vec{n} ds = \int_C f dy - g dx$$

- If  $C$  is closed and  $\vec{F} = \langle f, g \rangle$ ,

use Green's Theorem:

$$\int_C \vec{F} \cdot \vec{n} ds = \iint_R (f_x + g_y) dA$$

( $f_x + g_y$  is 2D-divergence)

- We did not discuss the cases for

- closed  $C$  and  $\vec{F} = \langle f, g, h \rangle$

- not closed  $C$  and  $\vec{F} = \langle f, g, h \rangle$

(We use surface integrals instead.)

- $\iint_S f \, dS$ 
  - Surface integral over  $S$
  - $f$  is scalar-valued

How to compute:

Parameterize  $S$  with  $\vec{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$  over a region  $R$  in the  $uv$ -plane.

Since  $dS = |\vec{r}_u \times \vec{r}_v| \, dA$ , you can compute:

$$\iint_R f(\vec{r}(u,v)) |\vec{r}_u \times \vec{r}_v| \, dA$$

- For an explicitly defined surface, we can write  $u=x$ ,  $v=y$  and  $z=g(x,y)$  which always gives  $|\vec{r}_u \times \vec{r}_v| = |\vec{r}_x \times \vec{r}_y| = \sqrt{1 + (g_x)^2 + (g_y)^2}$ . Then:

$$\iint_S f \, dS = \iint_R f(\vec{r}(x,y)) \sqrt{1 + (g_x)^2 + (g_y)^2} \, dA$$

- $\iint_S \vec{F} \cdot d\vec{S}$ 
  - Flux and surface integral over oriented surfaces
  - $= \iint_S \vec{F} \cdot \vec{n} \, dS$ 
    - ↑ unit normal
  - measures the net amount of  $\vec{F}$  passing through the surface  $S$  in the direction of the normal to  $S$

How to compute:

- Parameterize surface  $S$  with  $\vec{r}(u,v)$  over a region  $R$  in the  $uv$ -plane.

Find  $\vec{r}_u \times \vec{r}_v$ .

$\vec{n}$  will point in the direction of  $\vec{r}_u \times \vec{r}_v$  or in the direction  $-(\vec{r}_u \times \vec{r}_v)$  based on the orientation of  $S$

$$\iint_S \vec{F} \cdot \vec{n} \, dS = \iint_S \vec{F}(\vec{r}(u,v)) \cdot (\stackrel{\pm}{\vec{r}_u \times \vec{r}_v}) \, dA$$

$\vec{n} = \frac{\pm (\vec{r}_u \times \vec{r}_v)}{|\vec{r}_u \times \vec{r}_v|}$        $dS = |\vec{r}_u \times \vec{r}_v| \, dA$       Based on orientation.

- If  $S$  is a surface bounding a solid region  $D$  (i.e.  $(x,y,z) \in D$ ), use Divergence Theorem:

$$\iint_S \vec{F} \cdot \vec{n} \, dS = \iiint_D \operatorname{div} \vec{F} \, dV$$

Limits:  $\lim_{(x,y) \rightarrow (a,b)} f(x,y) = ?$

Step 1: Evaluate  $f(a,b)$ .

If  $f(a,b)$  is defined:  $\lim_{(x,y) \rightarrow (a,b)} f(x,y) = f(a,b)$   
(and  $f$  is continuous at  $(a,b)$ )

If  $f(a,b)$  is not defined,  $f$  is not continuous at  $(a,b)$ , but the limit might exist. Proceed to Step 2.

Step 2: Rationalize or simplify  $f(x,y)$  to get  $\tilde{f}(x,y)$ .

$$(\text{Ex. } f(x,y) = \frac{x-y}{x^2-y^2} = \frac{x-y}{(x-y)(x+y)} = \frac{1}{x+y}, \\ \text{so } \tilde{f}(x,y) = \frac{1}{x+y})$$

Evaluate  $\tilde{f}(a,b)$ .

If  $\tilde{f}(a,b)$  is defined, then  $\lim_{(x,y) \rightarrow (a,b)} f(x,y) = \tilde{f}(a,b)$ .

If  $\tilde{f}(a,b)$  is not defined, proceed to Step 3.

Step 3: In this course, the only remaining option for the limit to exist is to graph  $f(x,y)$ .

To show the limit does not exist, evaluate the limit along different curves:

$$\begin{array}{ccc} \lim_{(x,\textcolor{green}{b}) \rightarrow (a,b)} f(x,\textcolor{green}{b}) & \xrightarrow{\hspace{1cm}} & \text{At least two of} \\ \lim_{(\textcolor{green}{a},y) \rightarrow (a,b)} f(\textcolor{green}{a},y) & \xrightarrow{\hspace{1cm}} & \text{these five limits} \\ \lim_{(x,\textcolor{green}{mx}) \rightarrow (a,b)} f(x,\textcolor{green}{mx}) & \xrightarrow{\hspace{1cm}} & \text{should be different which} \\ \lim_{(x,\textcolor{green}{mx^2}) \rightarrow (a,b)} f(x,\textcolor{green}{mx^2}) & \xrightarrow{\hspace{1cm}} & \text{means} \\ \lim_{(\textcolor{green}{my^2},y) \rightarrow (a,b)} f(\textcolor{green}{my^2},y) & \xrightarrow{\hspace{1cm}} & \lim_{(x,y) \rightarrow (a,b)} f(x,y) \\ & & \text{does not exist.} \end{array}$$