

§14.2 Calculus of Vector-Valued Functions

* To integrate and differentiate vector-valued functions, we integrate and differentiate the component functions as we did in previous calc courses.

Ex.1 Differentiate $\vec{r}(t) = \left\langle \frac{te^{-t}}{x(t)}, \frac{\ln(t^2+1)}{y(t)}, \frac{\sin t}{z(t)} \right\rangle$.

$$\vec{r}'(t) = \frac{d}{dt} [\vec{r}(t)] = \langle x'(t), y'(t), z'(t) \rangle$$

$$x'(t) = \frac{d}{dt} [te^{-t}] = \frac{d}{dt} [t] \cdot e^{-t} + t \cdot \frac{d}{dt} [e^{-t}]$$

Product Rule Chain Rule

$$= (1)e^{-t} + t(-e^{-t}) = e^{-t} - te^{-t}$$

$$y'(t) = \frac{d}{dt} [\ln(t^2+1)] = \frac{2t}{t^2+1}$$

Chain Rule

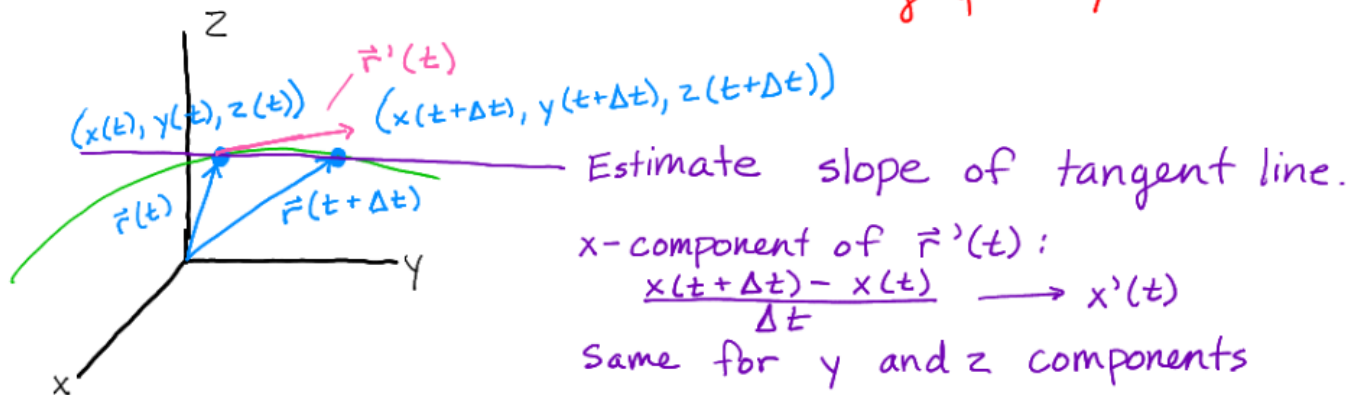
$$z'(t) = \frac{d}{dt} \left[\frac{\sin t}{t} \right] \quad \left(= \frac{d}{dt} [t^{-1} \cdot \sin t] \right)$$

Quotient Rule Product Rule

$$= \frac{\frac{d}{dt} [\sin t] \cdot t - \sin t \cdot \frac{d}{dt} [t]}{t^2}$$
$$= \frac{t \cos t - \sin t}{t^2}$$

$$\vec{r}'(t) = \left\langle e^{-t} - te^{-t}, \frac{2t}{t^2+1}, \frac{t \cos t - \sin t}{t^2} \right\rangle$$

Derivatives of vector-valued functions graphically:



Def. $\vec{r}(t)$ is differentiable where its component functions are differentiable.

If $\vec{r}'(t) \neq 0$, then $\vec{r}'(t)$ is a tangent vector corresponding to $\vec{r}(t)$.

The unit tangent vector is

$$\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$

Ex.2 Find the unit tangent vector at $t = -1$ for $\vec{r}(t) = \langle \ln(t+2), t^2, e^{t+1} \rangle$, $-2 < t$.

① $\vec{r}'(t) = \langle \frac{1}{t+2}, 2t, e^{t+1} \rangle$ Defined for these values of the parameter.

② Compute general $\vec{T}(t)$ in terms of t ,
OR evaluate $\vec{r}'(-1)$ and find specific $\vec{T}(-1)$.

$$\vec{r}'(-1) = \langle \frac{1}{-1+2}, -2, e^0 \rangle = \langle 1, -2, 1 \rangle$$

$$|\vec{r}'(-1)| = \sqrt{1+4+1} = \sqrt{6}$$

③ $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{\langle 1, -2, 1 \rangle}{\sqrt{6}} = \langle \frac{1}{\sqrt{6}}, -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}} \rangle$

Ex. 3 Find the line tangent to the curve
 $\vec{r}(t) = \langle t^2 + 7, 4\cos t, 1 - \sin t \rangle$ at $t=0$.

To write the equation of a line, we need a point on the line and a direction. Since the line is tangent to the curve, the direction will be $\vec{r}'(0)$, and the position vector for a point on the curve and the tangent line is $\vec{r}(0)$.

① Find point on line.

$$\vec{r}_0 = \vec{r}(0) = \langle 7, 4, 1 \rangle, \text{ so } P_0(7, 4, 1)$$

② Find the direction.

$$\vec{v} = \vec{r}'(t) = \langle 2t, -4\sin t, -\cos t \rangle$$

$$\vec{v} = \vec{r}'(0) = \langle 0, 0, -1 \rangle$$

③ Write vector or parametric equations for line.

$$\vec{r}_l = \vec{r}_0 + t\vec{v} = \langle 7, 4, 1 \rangle + t\langle 0, 0, -1 \rangle = \vec{r}_l$$

$$\begin{cases} x = 7 \\ y = 4 \\ z = 1 - t \end{cases}$$

Thm 14.1 Derivative Rules

\vec{u}, \vec{v} are vector-valued functions.

f is a scalar-valued function.

\vec{c} is a constant vector

$$\textcircled{1} \frac{d}{dt} [\vec{c}] = 0$$

$$\textcircled{2} \frac{d}{dt} [\vec{u}(t) + \vec{v}(t)] = \vec{u}'(t) + \vec{v}'(t)$$

$$\textcircled{3} \frac{d}{dt} [f(t) \vec{u}(t)] = f'(t) \vec{u}(t) + f(t) \vec{u}'(t)$$

$$\textcircled{4} \frac{d}{dt} [\vec{u}(f(t))] = f'(t) \vec{u}'(f(t))$$

$$\textcircled{5} \frac{d}{dt} [\vec{u}(t) \cdot \vec{v}(t)] = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$$

$$\textcircled{6} \frac{d}{dt} [\vec{u}(t) \times \vec{v}(t)] = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$$

Ex. 4 Compute $\frac{d}{dt} [\vec{u}(t^2+1)]$ where $\vec{u}(t) = \langle t^3+t, \sin(t) \rangle$.

Note: If you write $\vec{u}(t^2+1)$ explicitly,

$\vec{u}(t^2+1) = \langle (t^2+1)^3 + t^2+1, \sin(t^2+1) \rangle$,
you will have to do multiple chain rules.

Using $\textcircled{4}$ from Thm 14.1:

$$\frac{d}{dt} [\vec{u}(t^2+1)] = \frac{d}{dt} [t^2+1] \vec{u}'(t^2+1)$$

$$= 2t \vec{u}'(t^2+1)$$

$$(\vec{u}'(t) = \langle 3t^2 + 1, \cos t \rangle)$$
$$= 2t \langle 3(t^2+1)^2 + 1, \cos(t^2+1) \rangle$$

$$= \langle 6t(t^2+1)^2 + 2t, 2t \cos(t^2+1) \rangle$$

Def. Indefinite Integration of $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

$$\int \vec{r}(t) dt = \langle \int f(t) dt, \int g(t) dt, \int h(t) dt \rangle + \vec{C}$$

where $\vec{C} = \langle C_1, C_2, C_3 \rangle$ is a constant vector.

Definite Integration

$$\int_a^b \vec{r}(t) dt = \langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \rangle$$

Ex.5 Evaluate $\int_0^2 e^t (t\vec{i} + 2\vec{j} - e^t\vec{k}) dt$.

Need to compute

① $\int_0^2 te^t dt$

Integration by parts

$$u=t \quad dv=e^t dt$$

$$du=dt \quad v=e^t$$

$$= uv|_0^2 - \int_0^2 v du$$

$$= te^t|_0^2 - \int_0^2 e^t dt$$

$$= te^t - e^t|_0^2$$

$$= 2e^2 - e^2 - (0 - e^0)$$

$$= 2e^2 - e^2 + 1$$

$$= e^2 + 1$$

② $\int_0^2 2e^t dt$

$$= 2e^t|_0^2$$

$$= 2e^2 - 2e^0 = 1$$

$$= 2e^2 - 2$$

③ $\int_0^2 -e^t e^t dt$

$$= -\int_0^2 e^{2t} dt$$

Substitution

$$u=2t$$

$$du=2dt$$

$$= -\int_0^2 e^u \frac{du}{2}$$

$$= -\frac{1}{2} \int_0^2 e^u du$$

$$= -\frac{1}{2} e^u|_0^2$$

$$= -\frac{1}{2} e^{2t}|_0^2$$

$$= -\frac{1}{2} [e^4 - e^0]$$

$$= -\frac{1}{2} [e^4 - 1]$$

$$\int_0^2 e^t (t\vec{i} + 2\vec{j} - e^t\vec{k}) dt$$

$$= (e^2 + 1)\vec{i} + (2e^2 - 2)\vec{j} - \frac{1}{2}(e^4 - 1)\vec{k}$$

§14.3 Motion in Space

Def. If $\vec{r}(t)$ is a position function, then we

can find: velocity $\vec{v}(t) = \vec{r}'(t)$

$s(t)$ is the arclength function we'll use later. speed $\frac{ds}{dt} = |\vec{v}(t)| = |\vec{r}'(t)|$

acceleration $\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t)$

where $t \geq 0$.

Given an acceleration $\vec{a}(t)$, we have

$$\vec{v}(t) = \int \vec{a}(t) dt$$

$$\frac{ds}{dt} = \left| \int \vec{a}(t) dt \right|$$

$$\vec{r}(t) = \int \vec{v}(t) dt$$

Note: These are indefinite integrals, so we will need to be given values to solve for the constant \vec{C} .

Ex.6 Given position function $\vec{r}(t) = \langle t \sin t, t^2, t \cos t \rangle$, $t \geq 0$, find (a) velocity, (b) speed, and (c) acceleration.

$$\begin{aligned} \text{(a)} \quad \vec{v}(t) &= \vec{r}'(t) = \left\langle \frac{d}{dt} [t \sin t], \frac{d}{dt} [t^2], \frac{d}{dt} [t \cos t] \right\rangle \\ &= \left\langle \sin t + t \cos t, 2t, \cos t - t \sin t \right\rangle \end{aligned}$$

$$\begin{aligned} \text{(b)} \quad \frac{ds}{dt} &= |\vec{v}(t)| = \sqrt{(\sin t + t \cos t)^2 + (2t)^2 + (\cos t - t \sin t)^2} \\ &= \sqrt{(\sin^2 t + 2t \sin t \cos t + t^2 \cos^2 t) + (4t^2) + (\cos^2 t - 2t \cos t \sin t + t^2 \sin^2 t)} \\ &= \sqrt{\underbrace{\sin^2 t + \cos^2 t}_{=1} + t^2 (\underbrace{\cos^2 t + \sin^2 t}_{=1}) + 4t^2} \\ &= \sqrt{1 + t^2 + 4t^2} \\ &= \sqrt{1 + 5t^2} \end{aligned}$$

$$\begin{aligned}
 \text{(c) } \vec{a}(t) = \vec{v}'(t) &= \left\langle \frac{d}{dt} \left[\underbrace{\sin t + \frac{t \cos t}{\text{Product}}}, \frac{d}{dt} [2t], \frac{d}{dt} \left[\underbrace{\cos t - \frac{t \sin t}{\text{Product}}} \right] \right\rangle \\
 &= \langle \cos t + \cos t - t \sin t, 2, -\sin t - \sin t - t \cos t \rangle \\
 &= \boxed{\langle 2 \cos t - t \sin t, 2, -2 \sin t - t \cos t \rangle}
 \end{aligned}$$

Ex. 7 Let $\vec{a}(t) = t\vec{i} - t^3\vec{j} + 3t^5\vec{k}$, $\vec{r}(0) = \vec{i} - \vec{j}$ and $\vec{v}(0) = \vec{i}$.
Find (a) $\vec{v}(t)$ and (b) $\vec{r}(t)$.

$$\begin{aligned}
 \text{(a) } \vec{v}(t) &= \int \vec{a}(t) dt = (\int t dt)\vec{i} - (\int t^3 dt)\vec{j} + (\int 3t^5 dt)\vec{k} \\
 &= \left(\frac{1}{2}t^2 + C_1\right)\vec{i} - \left(\frac{1}{4}t^4 + C_2\right)\vec{j} + \left(\frac{3}{6}t^6 + C_3\right)\vec{k} \\
 &\quad \underline{\text{OR:}} \quad \langle \frac{1}{2}t^2, -\frac{1}{4}t^4, \frac{1}{2}t^6 \rangle + \vec{C} \quad \text{where } \vec{C} = \langle C_1, C_2, C_3 \rangle
 \end{aligned}$$

Use $\vec{v}(0) = \vec{i}$ to find \vec{C}

$$\begin{aligned}
 \vec{i} = \vec{v}(0) &= \underbrace{(0 + C_1)}_{=1}\vec{i} - \underbrace{(0 + C_2)}_{=0}\vec{j} + \underbrace{(0 + C_3)}_{=0}\vec{k} \\
 &\Rightarrow C_1 = 1 \quad \Rightarrow C_2 = 0 \quad \Rightarrow C_3 = 0
 \end{aligned}$$

$$\begin{aligned}
 \underline{\text{OR}} \quad \langle 1, 0, 0 \rangle &= \langle 0, 0, 0 \rangle + \vec{C} \\
 \langle 1, 0, 0 \rangle &= \vec{C}
 \end{aligned}$$

Either way, $\boxed{\vec{v}(t) = \left(\frac{1}{2}t^2 + 1\right)\vec{i} - \frac{1}{4}t^4\vec{j} + \frac{1}{2}t^6\vec{k}}$

$$\begin{aligned}
 \text{(b) } \vec{r}(t) &= \int \vec{v}(t) dt \\
 &= (\int (\frac{1}{2}t^2 + 1) dt)\vec{i} - (\int \frac{1}{4}t^4 dt)\vec{j} + (\int \frac{1}{2}t^6 dt)\vec{k} \\
 &= \left(\frac{1}{6}t^3 + t + C_1\right)\vec{i} - \left(\frac{1}{20}t^5 + C_2\right)\vec{j} + \left(\frac{1}{14}t^7 + C_3\right)\vec{k}
 \end{aligned}$$

Use $\vec{r}(0) = \vec{i} - \vec{j}$ to find \vec{C} .

$$\begin{aligned}
 \vec{i} - \vec{j} &= \vec{r}(0) \\
 &= \underbrace{(C_1)}_{=1}\vec{i} - \underbrace{(C_2)}_{=1}\vec{j} + \underbrace{(C_3)}_{=0}\vec{k} \\
 &\Rightarrow C_1 = 1 \quad \Rightarrow C_2 = 1 \quad \Rightarrow C_3 = 0
 \end{aligned}$$

$$\boxed{\vec{r}(t) = \left(\frac{1}{6}t^3 + t + 1\right)\vec{i} - \left(\frac{1}{20}t^5 + 1\right)\vec{j} + \left(\frac{1}{14}t^7\right)\vec{k}}$$

Ex. 8 Let $\vec{r}(t) = \langle 6t, 3t^2, t^3 \rangle$. At what value(s) of t does the speed equal 18?

① First, find $\frac{ds}{dt} = |\vec{v}(t)| = |\vec{r}'(t)|$.

$$\vec{r}'(t) = \langle 6, 6t, 3t^2 \rangle$$

$$\begin{aligned} |\vec{r}'(t)| &= \sqrt{6^2 + (6t)^2 + (3t^2)^2} \\ &= \sqrt{36 + 36t^2 + 9t^4} \\ &= \sqrt{9(t^4 + 4t^2 + 4)} \\ &= \sqrt{9(t^2 + 2)^2} \\ &= 3(t^2 + 2) \end{aligned}$$

② Set $\frac{ds}{dt} = 18$ and solve for t .

$$18 = 3(t^2 + 2)$$

$$6 = t^2 + 2$$

$$4 = t^2$$

$$\boxed{\pm 2 = t}$$

Ex. 9 Given $\vec{r}(t) = \langle t^{\frac{3}{2}}, 2t+1, t^2-8t \rangle$, at what t -value(s) does the minimum speed occur?

① Again, need to find $\frac{ds}{dt} = |\vec{r}'(t)|$.

$$\vec{r}'(t) = \langle \frac{3}{2}t^{1/2}, 2, 2t-8 \rangle$$

$$|\vec{r}'(t)| = \sqrt{\frac{9}{4}t + 4 + (2t-8)^2} = \sqrt{4t^2 - \frac{11}{2}t + 68}$$

② A min or max occurs when $\frac{d}{dt} [|\vec{r}'(t)|] = 0$.

Must have numerator = 0.

$$\frac{d}{dt} [|\vec{r}'(t)|] = \frac{8t - \frac{11}{2}}{2(4t^2 - \frac{11}{2}t + 68)^{1/2}} = 0$$

$$0 = 8t - \frac{11}{2}$$

$$\frac{11}{2} = 8t$$

$$\Rightarrow \boxed{t = \frac{11}{16}}$$

Should use 1st or 2nd Derivative Test to check if min or max.

