

## MA 266 Lecture 20

### Section 3.7 Mechanic and Electrical Vibrations (contd)

**Review** For undamped free vibrations, the governing equation is

$$m u'' + k u = 0$$

**Example 1. (Problem 6)** A mass of 100 g stretches a spring 5cm. If the mass is set in motion from its equilibrium position with a downward velocity of 10 cm/s, and if there is no damping, determine the position  $u$  of the mass at any time  $t$ . When does the mass first return to its equilibrium position?

$$\text{mass : } m = 100g = 0.1 \text{ kg}$$

$$\text{Spring constant : } k = \frac{mg}{L} = \frac{0.1 \text{ kg} \cdot 9.8 \text{ m/s}^2}{0.05 \text{ m}} = 19.6 \text{ kg/s}^2$$

$$\gamma = 0$$

$$\text{no external force, } F(t) = 0$$

$$\text{I.V.P : } 0.1 u'' + 19.6 u = 0$$

$$u(0) = 0$$

$$u'(0) = 10 \text{ cm/s} = 0.1 \text{ m/s}$$

$$\text{C.E : } \cancel{0.1 r^2} + 19.6 = 0 \Rightarrow \boxed{r = \pm 14i}$$

$$u(t) = A \cos(14t) + B \sin(14t)$$

$$\text{I.C.} \Rightarrow A = 0, B = \frac{1}{140}, \Rightarrow u(t) = \frac{1}{140} \sin(14t)$$

Period =  $T = \frac{2\pi}{14} = \frac{\pi}{7}$ ; After half period  $\frac{\pi}{14}$ , it returns to equilibrium position.

## Damped Free Vibrations

If we include the effect of damping, the differential equation the motion becomes

$$m u'' + \gamma u' + k u = 0.$$

$$\text{C.E.: } m\tau^2 + \gamma\tau + k = 0.$$

$$\tau_{1,2} = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m}$$

Depending the sign of  $\gamma^2 - 4km$  the solution  $u$  has one of the following forms

- if  $\gamma^2 - 4km > 0$  two real distinct roots,  $r_1$  and,  $r_2$

$$u = A e^{r_1 t} + B e^{r_2 t}$$

- if  $\gamma^2 - 4km = 0$  two real repeated roots,  $r_1 = r_2 = -\frac{\gamma}{2m}$

$$u = (A + Bt) e^{-\frac{\gamma t}{2m}}$$

- if  $\gamma^2 - 4km < 0$

two complex roots,

$$u(t) = e^{-\frac{\gamma t}{2m}} (A \cos(\mu t) + B \sin(\mu t)), \quad \mu = \frac{\sqrt{4km - \gamma^2}}{2m}$$

Remark

The solution  $u$  tends to zero, as  $t \rightarrow \infty$ , because of damping.

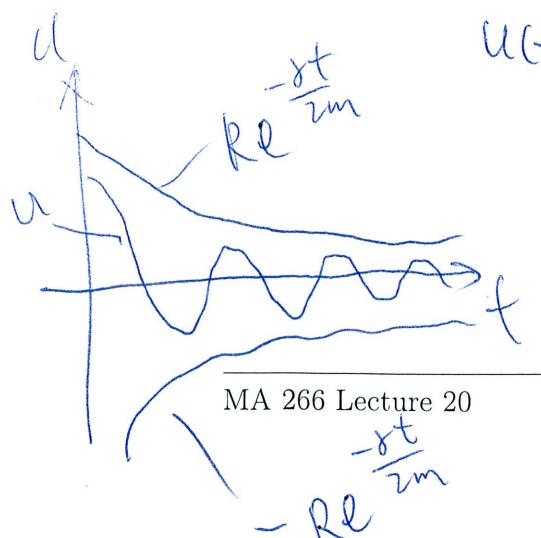
The case where  $\gamma^2 - 4km < 0$  is of most interest. The solution can be written as

$$u(t) = R \cdot e^{-\frac{\gamma t}{2m}} \cos(\mu t - \delta)$$

$$|u(t)| \leq R e^{-\frac{\gamma t}{2m}}$$

Displacement  $u(t)$  lies between two curves

$$u = \pm R e^{-\frac{\gamma t}{2m}}$$



**Example 2. (Problem 10)** A mass weighing 16lb stretches a spring 3in. The mass is attached to a viscous damper with a damping constant of 2 lb·s/ft. If the mass is set in motion from its equilibrium position with a downward velocity of 3 in/s, find its position  $u$  at any time  $t$ . Determine when the mass first returns to its equilibrium position.

$$\text{mass, } m = \frac{w}{g} = \frac{16 \text{ lb}}{32 \text{ ft/s}^2} = \frac{1}{2} \text{ lb s}^2/\text{ft}$$

$$\text{damping, } \gamma = 2 \text{ lb s/ft}$$

$$\text{Spring constant, } k = \frac{mg}{L} = \frac{16 \text{ lb}}{3 \text{ in}} = \frac{16 \text{ lb}}{3 \cdot \frac{1}{12} \text{ ft}} = 64 \text{ lb/ft}$$

$$\text{ODE: } \frac{1}{2}u'' + 2u' + 64u = 0$$

$$\text{I.C.: } u(0) = 0, \quad u'(0) = 3 \text{ in/s} = 3 \cdot \frac{1}{12} \text{ ft/s}$$

$$= \frac{1}{4} \text{ ft/s.}$$

$$\text{C.E.: } r^2 + 4r + 128 = 0$$

$$r = -2 \pm 2\sqrt{31}i$$

The general solution is:

$$u = e^{-2t} (A \cos(2\sqrt{31}t) + B \sin(2\sqrt{31}t))$$

$$\text{I.C.: } \Rightarrow A = 0, \quad B = \frac{1}{8\sqrt{31}}, \quad \boxed{u = \frac{1}{8\sqrt{31}} e^{-2t} \sin(2\sqrt{31}t)}$$

$$u = 0 \Rightarrow \sin(2\sqrt{31}t) = 0 \Rightarrow 2\sqrt{31}t = n\pi, \quad n = 0, 1, 2, \dots$$

$$\text{Let } n = 1,$$

$$\boxed{t = \frac{\pi}{2\sqrt{31}}}$$