

5.4

Eigenvectors of linear transformations

①

\vee vector space $T : V \rightarrow V$ linear transformation

Def'n \bar{x} in V is eigenvector for T if
 $\bar{x} \neq \bar{0}$ and $T(\bar{x}) = \lambda \bar{x}$ for some λ in \mathbb{R} .

λ in \mathbb{R} is eigenvalue for T if there is \bar{x} in V
s.t. $\bar{x} \neq \bar{0}$ and $T(\bar{x}) = \lambda \bar{x}$.

Ex 1 If A $n \times n$ square matrix and
 $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ $T(\bar{x}) = A\bar{x}$ then the
eigenvalues and eigenvectors of A are
eigenvalues and eigenvectors of T .

Ex 2 $V = \{ \text{differentiable functions on } \mathbb{R} \}$
 $T : V \rightarrow V$ $T(x) = x' = \frac{dx}{dt}$

$$x(t) = e^{2t} \quad x'(t) = 2e^{2t}$$

$$T(e^{2t}) = 2e^{2t}$$

$$T(e^{\lambda t}) = \lambda e^{\lambda t}$$

$x(t) = e^{2t}$ is eigenvector
with eigenvalue 2

$$(e^{\lambda t})' = \lambda e^{\lambda t} \quad (e^t)' = e^t$$

$x=0?$

comment T linear?
 $(x+y)' = x'+y'$
 $(cx)' = c x'$
 $x(t) = t^7 \quad T(x) = \frac{d}{dt}(t^7)$

Coordinates in a vector space V with basis
 $B = \{\bar{b}_1, \dots, \bar{b}_m\}$. Each \bar{x} in V is written
uniquely as $\bar{x} = r_1 \bar{b}_1 + \dots + r_m \bar{b}_m$ with r_i in \mathbb{R}

 \mathbb{R}^2

Thus \bar{x} is given by
 $\varepsilon = \left[\begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \right], \left[\begin{smallmatrix} 0 \\ 1 \end{smallmatrix} \right]$

$$\bar{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$[\bar{x}]_B = \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix} \in \mathbb{R}^n$$

$$\bar{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$[\bar{x}]_\varepsilon = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$[\bar{x}]_\varepsilon = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

The matrix of a linear transformation $T: V \rightarrow V$
 for a finite dimensional vector space V
 with basis $B = \{\bar{b}_1, \dots, \bar{b}_n\}$ is the $n \times n$
 square matrix $M = [T]_B$ with the property
 that

$$[T(\bar{x})]_B = M [\bar{x}]_B.$$

$$\begin{aligned} \bar{x} &\mapsto T(\bar{x}) \\ [\bar{x}]_B &\mapsto [T(\bar{x})]_B \\ \text{in } \mathbb{R}^n &\quad \text{in } \mathbb{R}^n \end{aligned}$$

IMPORTANT OBSERVATION:

$$M = \left[[T(\bar{b}_1)]_B, \dots, [T(\bar{b}_n)]_B \right]_{n \times n}$$

[Ex 3]

Say $\dim(V) = 2$ with basis $\{\bar{b}_1, \bar{b}_2\}$
 and $T: V \rightarrow V$ linear

$$\begin{aligned} T(\bar{b}_1) &= 4\bar{b}_1 + 3\bar{b}_2 \\ T(\bar{b}_2) &= \bar{b}_1 - 13\bar{b}_2 \end{aligned}$$

Find $[T]_B = M = ?$

Answer: $[T(b_1)]_B = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$ $[T(b_2)]_B = \begin{pmatrix} 1 \\ -13 \end{pmatrix}$

$$M = \begin{pmatrix} 4 & 1 \\ 3 & -13 \end{pmatrix}$$

- $T(\bar{b}_1 + \bar{b}_2) = T(\bar{b}_1) + T(\bar{b}_2) = 4\bar{b}_1 + 3\bar{b}_2 + \bar{b}_1 - 13\bar{b}_2 =$
- $\begin{pmatrix} 4 & 1 \\ 3 & -13 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ -10 \end{pmatrix}$

$$\begin{pmatrix} \bar{b}_1 \\ \bar{b}_2 \end{pmatrix}_B = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (\bar{b}_1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$(\bar{b}_2) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

[Ex 4]

$$T: \mathbb{P}_3 \rightarrow \mathbb{P}_3$$

$$B = \underbrace{\{1, t, t^2, t^3\}}_{\text{basis}}$$

p in \mathbb{P}_3

$$T(p) = p' \quad \text{linear}$$

$$[T]_B = ?$$

$$\begin{aligned} p(t) &= a_0 + a_1 t + a_2 t^2 + a_3 t^3 \\ [p]_B &= \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix} \end{aligned}$$

(3)

Auswer: $[T]_B = M = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

$$M \begin{bmatrix} z_0 \\ z_1 \\ z_2 \\ z_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} z_0 \\ z_1 \\ z_2 \\ z_3 \end{bmatrix} = \begin{bmatrix} z_1 \\ 2z_2 \\ 3z_3 \\ 0 \end{bmatrix} = \underbrace{[z_1 + 2z_2 + 3z_3 t^2]}_{p(t)} \quad \text{B}$$

$$T(z_0 + z_1 t + z_2 t^2 + z_3 t^3) = z_1 + 2z_2 t + 3z_3 t^2$$

$$[T(1)]_B = [0]_B = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad [T(t^2)]_B = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$$

E5 $T: \mathbb{R}^n \rightarrow \mathbb{R}^n \quad T(\bar{x}) = A\bar{x} \quad \text{where}$

A is $n \times n$ square matrix
 $e_i = \{e_1, \dots, e_n\}$ $e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad e_n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$

$$[T]_E = A = [Te_1, Te_2, \dots, Te_n]$$

E6 $T: \mathbb{R}^n \rightarrow \mathbb{R}^n \quad T(\bar{x}) = A\bar{x} \quad A \text{ } n \times n$

Suppose $B = \{\vec{b}_1, \dots, \vec{b}_n\}$ basis of eigenvectors
 $\lambda_1, \dots, \lambda_n$ with eigenvalues $T(\vec{b}_1) = \lambda_1 \vec{b}_1$ $T(\vec{b}_2) = \lambda_2 \vec{b}_2$ \dots $T(\vec{b}_n) = \lambda_n \vec{b}_n$

$$[T]_B = ? \quad T(\vec{b}_1) = \lambda_1 \vec{b}_1$$

$$\frac{T(\vec{b}_1) = \lambda_1 \vec{b}_1}{\lambda_1 \vec{b}_1 = \lambda_1 \vec{b}_1 + \dots + 0 \cdot \vec{b}_n} = \boxed{[\lambda_1 \vec{b}_1]_B = }$$

Answer:

$$T(\vec{b}_1) = A(\vec{b}_1) = \lambda_1 \vec{b}_1$$

$$[T(\vec{b}_1)]_B = [\lambda_1 \vec{b}_1]_B = \boxed{\begin{bmatrix} \lambda_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}}$$

$$[T]_B = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix} = D.$$

Theorem

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$T(\vec{x}) = A \vec{x}$$

A $n \times n$ square matrix

Let $B = \{\vec{b}_1, \dots, \vec{b}_n\}$ basis of \mathbb{R}^n

Note

Let $P = [\vec{b}_1, \dots, \vec{b}_n]$. Then

$$[T]_E = A$$

$$[T]_B = P^{-1} A P$$

Proof: If \vec{x} in \mathbb{R}^n then $P[\vec{x}]_B = \vec{x}$
 by definition of P and $[\vec{x}]_B$. Thus $[\vec{x}]_B = P^{-1} \vec{x}$

$$\begin{aligned} [T]_B &= [[T(\vec{b}_1)], \dots, [T(\vec{b}_n)]]_B && \leftarrow \text{def'n of } [T]_B \\ &= [[A \vec{b}_1], \dots, [A \vec{b}_n]]_B && \leftarrow \text{since } T(\vec{b}) = A \vec{b} \\ &= [P^{-1} A \vec{b}_1, \dots, P^{-1} A \vec{b}_n] && \leftarrow \text{by } [\vec{x}]_B = P^{-1} \vec{x} \\ &= P^{-1} A [\vec{b}_1, \dots, \vec{b}_n] && \leftarrow \text{by matrix multiplication} \\ &= P^{-1} A P \end{aligned}$$

Ex 7 $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $T(\bar{x}) = A\bar{x}$

where $A = \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix}$

Let $B = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$.

Find $[T]_B$.

Sol'n (1st) $P = \begin{bmatrix} 1 & 1 \\ -2 & 1 \end{bmatrix}$ $P^{-1} = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix}$

$$[T]_B = P^{-1}AP = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix}$$

$$= \begin{bmatrix} 13 & -11 \\ 20 & -17 \end{bmatrix}.$$

(2nd) "low tech" solution

Need to compute $[T(\bar{b}_1)]_B$ and $[T(\bar{b}_2)]_B$

$$T(\bar{b}_1) = \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 7 \\ -6 \end{bmatrix} = c\bar{b}_1 + d\bar{b}_2$$

$$T(\bar{b}_2) = \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -6 \\ 5 \end{bmatrix} = c'\bar{b}_1 + d'\bar{b}_2$$

$$[T]_B = \begin{bmatrix} c & c' \\ d & d' \end{bmatrix} \quad \begin{bmatrix} 7 \\ -6 \end{bmatrix} = c \begin{bmatrix} 1 \\ -2 \end{bmatrix} + d \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -6 \\ 5 \end{bmatrix} = c \begin{bmatrix} 1 \\ -2 \end{bmatrix} + d \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

solve $c' = -11$
 $d' = -17$

$$[T]_B = \begin{bmatrix} 13 & -11 \\ 20 & -17 \end{bmatrix}$$

-END OF CLASS-

REMARK

$$\begin{bmatrix} 7 \\ -6 \end{bmatrix} = c \bar{b}_1 + d \bar{b}_2 \quad \leftarrow \text{can solve this using matrices}$$

$$\begin{bmatrix} 7 \\ -6 \end{bmatrix} = [\bar{b}_1, \bar{b}_2] \begin{bmatrix} c \\ d \end{bmatrix} = P \begin{bmatrix} c \\ d \end{bmatrix}$$

$$\begin{bmatrix} c \\ d \end{bmatrix} = P^{-1} \begin{bmatrix} 7 \\ -6 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ -6 \end{bmatrix} = \begin{bmatrix} 13 \\ 70 \end{bmatrix}$$

$$\begin{bmatrix} -6 \\ 5 \end{bmatrix} = c' \bar{b}_1 + d' \bar{b}_2 \quad \begin{bmatrix} -6 \\ 5 \end{bmatrix} = P \begin{bmatrix} c' \\ d' \end{bmatrix}$$

$$\begin{bmatrix} c' \\ d' \end{bmatrix} = P^{-1} \begin{bmatrix} -6 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} -6 \\ 5 \end{bmatrix} = \begin{bmatrix} -11 \\ -17 \end{bmatrix}$$

$$\begin{bmatrix} c & c' \\ d & d' \end{bmatrix} = \overbrace{\bar{P}^{-1} \begin{bmatrix} 7 & -6 \\ -6 & 5 \end{bmatrix}}^{\bar{A}^{-1} P} = \bar{P}^{-1} A P$$

$$\begin{array}{c} \bar{A}^{-1} P \\ (\bar{A} \bar{b}_1, \bar{A} \bar{b}_2) \\ \bar{A} \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \bar{A} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{array}$$

$$\text{Explain } [T]_{\mathcal{B}} = [T(\bar{b}_1)]_{\mathcal{B}}, \dots, [T(\bar{b}_n)]_{\mathcal{B}}$$

$$x = r_1 \bar{b}_1 + \dots + r_n \bar{b}_n \Leftrightarrow [x]_{\mathcal{B}} = \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix}$$

↓

$$T(x) = r_1 T(\bar{b}_1) + \dots + r_n T(\bar{b}_n)$$

$$[T(x)]_{\mathcal{B}} = r_1 [T(\bar{b}_1)]_{\mathcal{B}} + \dots + r_n [T(\bar{b}_n)]_{\mathcal{B}} \Rightarrow \underbrace{[T(\bar{b}_1) \dots T(\bar{b}_n)]}_{M} \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix} = \overbrace{[T(x)]_{\mathcal{B}}}$$