

Plan for today:

Finish 2.2

Start 2.3

Learning goals for the day:

1. Be able to construct a bifurcation diagram for a differential equation depending on a parameter
2. Be able to set up and solve a differential equation for the motion of a body under the influence of air resistance.

Reminders-Announcements

1. Ungraded Quiz 1.5 on Monday.
2. Quiz 2 on Thursday
3. Future quizzes are open book, see syllabus update
4. Read the textbook!

Last time: critical pts of an autonomous eqn.

$$\frac{dx}{dt} = f(x)$$

c critical: $f(c) = 0$

Logistic Model w/ harvesting

fish in a lake following a logistic model, harvest h every year.

$$\frac{dx}{dt} = \underbrace{x(100-x)}_{\text{logistic part}} - h$$

autonomous

$x(t) \rightarrow$ # of fish
in year t

depends on parameter

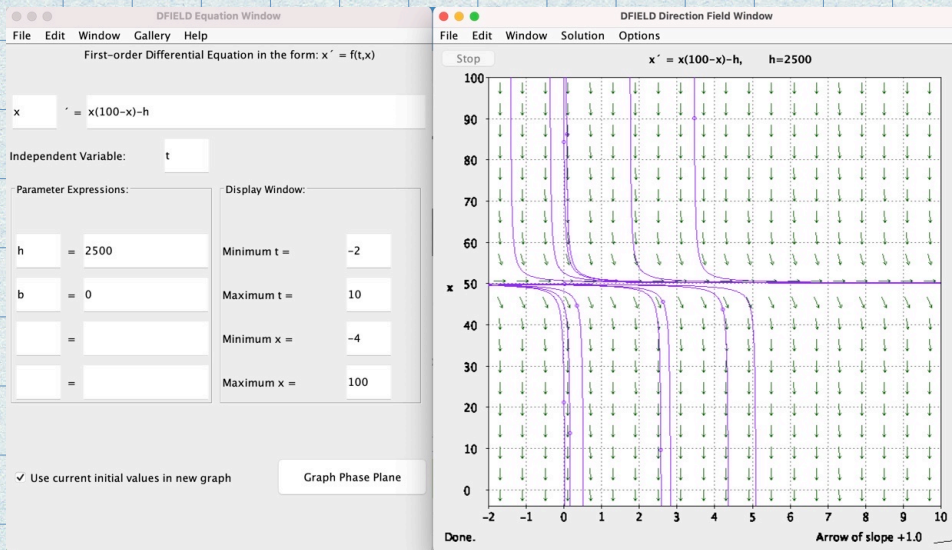
Crit pts? When is $x(100-x) - h = 0$?

$$-x^2 + 100x - h = 0$$

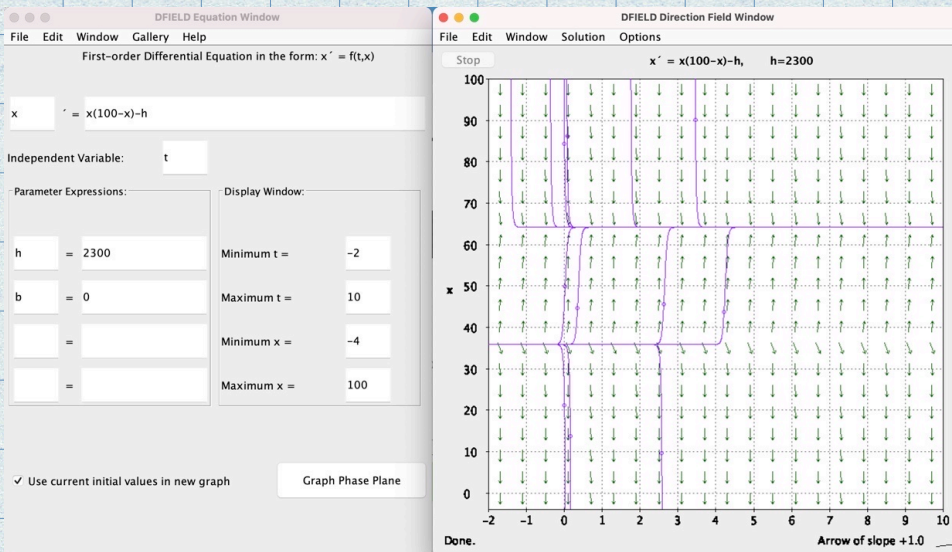
$$\Rightarrow x = \frac{100 \pm \sqrt{10,000 - 4h}}{2} = \triangle$$

of critical pts depends on h .

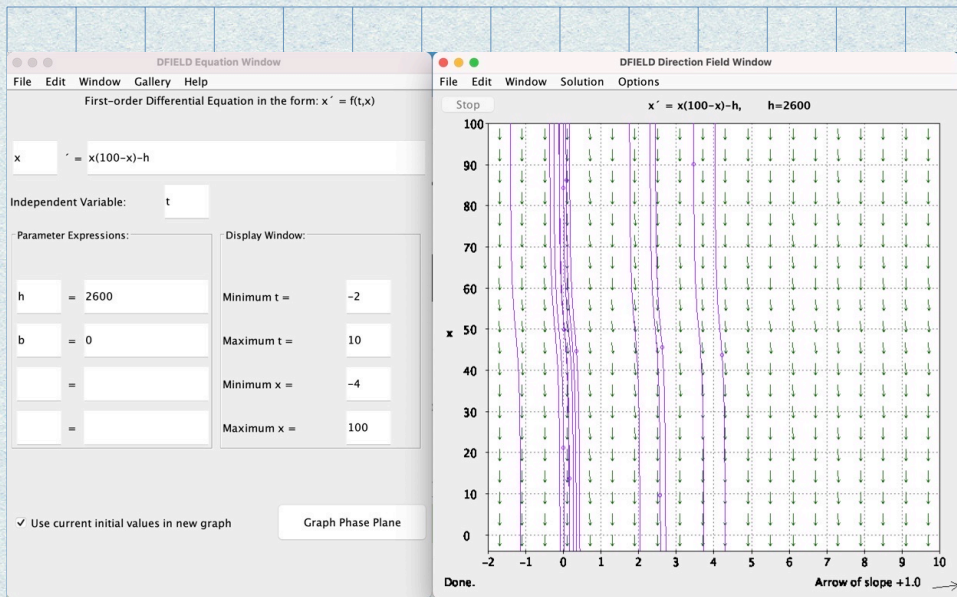
If $h = 2500$ then $10000 - 4h = 0$ and we have only 1 crit. pt.



If $h < 2500$ then $\Delta > 0$ and \rightarrow 2 crit pts



If $h > 2500$ then $\Delta < 0$ and we have no crit pts.

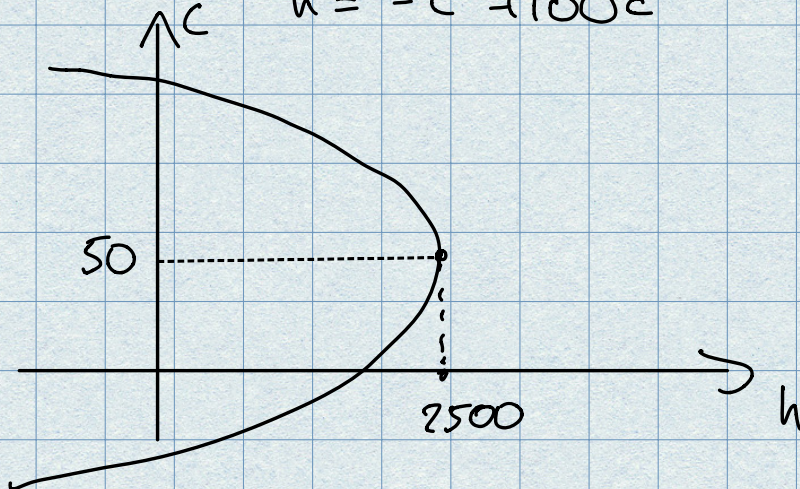


$h = 2500 \rightarrow$ bifurcation pt: qualitative behavior of eqn changes between $h < 2500$ & $h > 2500$

Bifurcation Diagram: sets of pts (h, c) so that c is a crit. pt.

\otimes $c^2 - 100c + h = 0$

$h = -c^2 + 100c$



2.3. Acceleration & velocity models.

In general: air resistance

$$F_R = k v^p \quad 1 \leq p \leq 2$$

↑ resistance
↑ a const.
↑ velocity

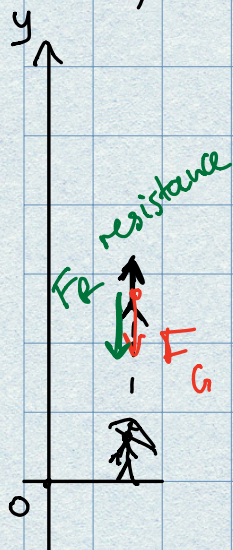
F_R always in direction opposite to the motion

$k \rightarrow$ depends on viscosity / density of air & shape of body.

Ex: Arrow shot straight upwards, initial velocity $v_0 = 160$ ft/s.

deceleration due to air resistance: $\frac{v^2}{800} \frac{\text{ft}}{\text{s}^2}$

a) how high does it go?



maybe $\frac{dy}{dt^2} = \dots$; easier to work w/ velocity directly.

$$\frac{dv}{dt} = -\frac{v^2}{800} - 32$$

↑ acceleration
↓ air resistance
↓ gravitational acceleration

autonomous, separable!

Exercise: solve! (soln at the end)

find: $v(t) = 160 \tan\left(-\frac{t}{5} + c\right)$

$$160 = 160 \tan(c)$$

Know:

$$v(0) = 160 \rightarrow c = \frac{\pi}{4}$$

$$\tan(c) = 1$$

How do we find when it will be at its highest point?

want $v(t) = 0 \Leftrightarrow 160 \tan\left(-\frac{t}{5} + \frac{\pi}{4}\right) = 0$
 $\Rightarrow t = \frac{5\pi}{4}$

$$y(t) = \int v(t) dt = \int 160 \tan\left(-\frac{t}{5} + \frac{\pi}{4}\right) dt$$

$$y(t) = 800 \ln\left(\cos\left(\frac{\pi}{4} - \frac{t}{5}\right)\right) + C_2$$

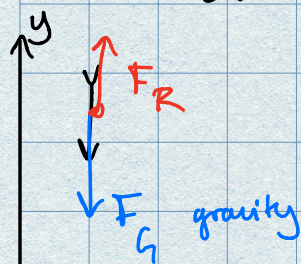
Find C_2 : $y(0) = 0$
 $\Rightarrow \dots \Rightarrow C_2 = 400 \ln(2)$

So: highest we reach

$$y\left(\frac{5\pi}{4}\right) = 800 \ln\left(\cos\left(\frac{\pi}{4} - \frac{\pi}{4}\right)\right) + 400 \ln(2)$$

$= 400 \ln(2)$.

b) When arrow is going down.



$$\frac{dv}{dt} = -32 + \frac{v^2}{800}, \quad v \text{ negative}$$

$\frac{d}{dt} = \frac{v^2}{800}$

Solve (exercice)

Find: $v(t) = -160 \frac{1 - e^{-2t/5}}{1 + e^{-2t/5}} \xrightarrow{t \rightarrow \infty} -160$

g

Reach limiting velocity.

time measured from the moment when
arrow is at highest altitude

Sols of examples

1.
$$\frac{dv}{dt} = -32 - \frac{v^2}{800}$$

$$\frac{dv}{dt} = -32 \left(1 + \frac{v^2}{25600} \right)$$
$$= -32 \left(1 + \left(\frac{v}{160} \right)^2 \right)$$

$$32 \cdot 800 = 25600 = 160^2$$

Separate variables:

$$\int \frac{dv}{1 + \left(\frac{v}{160} \right)^2} = - \int 32 dt, \text{ set } \frac{v}{160} = z$$

$$\int \frac{160 dz}{1 + z^2} = - \int 32 dt$$

$$\Rightarrow \arctan(z) = - \frac{1}{5} t + C$$

$$\stackrel{z=160v}{\Rightarrow} v = 160 \tan \left(- \frac{t}{5} + C \right)$$

2.
$$\frac{dv}{dt} = -32 + \frac{v^2}{800} = -32 \left(1 - \frac{v^2}{25600} \right)$$

$$\Rightarrow \int \frac{dv}{1 - \left(\frac{v}{160} \right)^2} = \int -32 dt \Rightarrow$$

$$\stackrel{z = \frac{v}{160}}{\Rightarrow} \int \frac{160 dz}{1 - z^2} = -32t + C$$

$$\Rightarrow 160 \int \frac{1}{2} \frac{1}{1-z} + \frac{1}{2} \frac{1}{1+z} dz = -32t + C$$

$$\Rightarrow 160 \left(-\frac{1}{2} \ln|1-z| + \frac{1}{2} \ln|1+z| \right) = -32t + C$$

$$\Rightarrow 80 \ln \left| \frac{1+z}{1-z} \right| = -32t + C$$

$$\Rightarrow \ln \left| \frac{1+z}{1-z} \right| = -\frac{2}{5}t + C_1 \quad \left(C_1 = \frac{C}{80} \right)$$

$$\Rightarrow \frac{1+z}{1-z} = \pm e^{C_1} e^{-\frac{2}{5}t}$$

$$\Rightarrow \frac{1+z}{1-z} = C_2 e^{-\frac{2}{5}t} \quad \left(C_2 = \pm e^{C_1} \right)$$

$$\Rightarrow z \left(C_2 e^{-\frac{2}{5}t} + 1 \right) = C_2 e^{-\frac{2}{5}t} - 1$$

$$\Rightarrow v = 160 \frac{C_2 e^{-\frac{2}{5}t} - 1}{C_2 e^{-\frac{2}{5}t} + 1}$$

Starting to measure time from the moment when the arrow reaches its highest altitude, $v(0) = 0$.

So $C_2 - 1 = 0 \Rightarrow C_2 = 1$

$$v = 160 \frac{e^{-\frac{2}{5}t} - 1}{e^{-\frac{2}{5}t} + 1}$$