

Plan for today

5.6

Learning goals/important concepts

1. Fundamental matrix, exponential of a matrix
2. Be able to compute the exponential of a diagonal or nilpotent matrix

Reminders/Announcements

1. Read the textbook!
2. Quiz 5 grades will be ready by Monday
3. Office hours 2-3 pm today
4. HW 29 due tonight

5.6. $\underline{x}' = \overbrace{A(t)}^{n \times n} \underline{x}$ linear systems
n lin. indep. sol's $\underline{x}_1, \dots, \underline{x}_n$

General sol'n: $\underline{x} = c_1 \underline{x}_1 + \dots + c_n \underline{x}_n$
 $\uparrow \qquad \qquad \uparrow$
n x 1 col. vectors. $\det \Phi(t) = W(\underline{x}_1, \dots, \underline{x}_n)$

Arrange into a matrix:

$$\underline{\Phi}(t) = \begin{bmatrix} | & & | \\ \underline{x}_1 & \dots & \underline{x}_n \\ | & & | \end{bmatrix}$$

fundamental matrix.

$$\underline{x} = \underline{\Phi}(t) \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

Ex 1. $x_1' = 5x_1 - 4x_2$
 $x_2' = 3x_1 - 2x_2$

$$A = \begin{bmatrix} 5 & -4 \\ 3 & -2 \end{bmatrix}$$

Eigen. $\lambda = 1$ e.v. $\underline{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$
 $\lambda = 2$ e.v. $\underline{v}_2 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$

2 lin. indep. sol's:

$$\underline{x}_1 = e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad \underline{x}_2 = e^{2t} \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

$$\Phi(t) = \begin{bmatrix} e^t & 4e^{2t} \\ e^t & 3e^{2t} \end{bmatrix}$$

Note: $\Phi(t) \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} c_1 e^t + c_2 4e^{2t} \\ c_1 e^t + c_2 3e^{2t} \end{bmatrix}$

$$= c_1 \begin{bmatrix} e^t \\ e^t \end{bmatrix} + c_2 \begin{bmatrix} 4e^{2t} \\ 3e^{2t} \end{bmatrix} //$$

Fund. matrix is not unique: if $\Phi(t)$ is a F.M. then

$$\Phi(t) \cdot C \text{ is a F.M.}$$

\uparrow
 $n \times n$ non-singular

Ex:

$$\begin{bmatrix} e^t & 4e^{2t} \\ e^t & 3e^{2t} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{\text{non-sing. } 2 \times 2 \text{ matrix}}$

$$= \begin{bmatrix} 4e^{2t} & e^t \\ 3e^{2t} & e^t \end{bmatrix} \rightarrow \text{still a F.M.}$$

Now: IVP

$$\begin{cases} \underline{x}' = A(t) \underline{x} \\ \underline{x}(a) = \underline{x}_a \end{cases} \leftarrow \text{known vector.} \quad \text{⊗}$$

let $\Phi(t)$ be a fund. matrix, \leftarrow known

$$x(t) = \Phi(t) \underline{c} \rightarrow \text{general soln.}$$

$$\underline{c} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

unknown.

$$\underline{x}(a) = \underline{x}_a$$

known

$$\Rightarrow \Phi(a) \underline{c} = \underline{x}_a$$

$$\Rightarrow \underline{c} = \Phi(a)^{-1} \underline{x}_a$$

inverse always exists.

Soln: $\Phi(t) \Phi(a)^{-1} \underline{x}_a$ is the soln to ~~*~~

Ex:

$$x_1' = 5x_1 - 4x_2$$

$$x_2' = 3x_1 - 2x_2$$

$$\begin{cases} x_1(0) = 5 \\ x_2(0) = 3 \end{cases}$$

$$\left. \begin{array}{l} x_1(0) = 5 \\ x_2(0) = 3 \end{array} \right\} \text{IVP}$$

$$\Phi(t) = \begin{bmatrix} e^t & 4e^{2t} \\ e^t & 3e^{2t} \end{bmatrix}$$

$$\underline{x}_0 = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

Soln will be:

$$\Phi(t) \Phi(0)^{-1} \underline{x}_0 = \begin{bmatrix} e^t & 4e^{2t} \\ e^t & 3e^{2t} \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} -3e^t + 4e^{2t} & 4e^t - 4e^{2t} \\ -3e^t + 3e^{2t} & 4e^t - 3e^{2t} \end{bmatrix} \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

~~*~~

Upshot:

The sol'n to any IVP

$$x_1' = 5x_1 - 4x_2$$

$$x_2' = 3x_1 - 2x_2$$

$$\begin{cases} x_1(0) = a \\ x_2(0) = b \end{cases}$$

$$A = \begin{bmatrix} 5 & -4 \\ 3 & -2 \end{bmatrix}$$

is

$$\begin{bmatrix} -3e^t + 4e^{2t} & 4e^t - 4e^{2t} \\ -3e^t + 3e^{2t} & 4e^t - 3e^{2t} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\Phi(t) \Phi(0)^{-1}$$

no + here.

Note: If $\Phi(t)$ is a F.M. for $\underline{x}' = A \underline{x}$

$\underline{x}(t) = \Phi(t) \Phi(0)^{-1}$ is a F.M.

and it solves IVP

$$\begin{cases} \underline{x}'(t) = A \underline{x}(t) \\ \underline{x}(0) = I \end{cases}$$

works bec. columns of \underline{x} are sols of $\underline{x}' = A \underline{x}$

Ex:

$$\underline{x}(t) = \begin{bmatrix} -3e^t + 4e^{2t} & 4e^t - 4e^{2t} \\ -3e^t + 3e^{2t} & 4e^t - 3e^{2t} \end{bmatrix}$$

Check: $\underline{x}'(t) = \begin{bmatrix} 5 & -4 \\ 3 & -2 \end{bmatrix} \underline{x}(t)$

and: $\underline{x}(0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = Id$

Compare \odot w/ \neq const.

$$\begin{cases} x' = kx \\ x(0) = 1 \end{cases}$$

$$x(t) = e^{kt}$$

Hope: can make use of e^{-At} , and it will solve \odot

Recall: $e^z = 1 + z + \frac{1}{2!} z^2 + \frac{1}{3!} z^3 + \dots$

Define, for a matrix \underline{A} ($n \times n$)

$$e^{\underline{A}} = \underline{I} + \underline{A} + \frac{1}{2!} \underline{A}^2 + \frac{1}{3!} \underline{A}^3 + \dots$$

\downarrow
 $n \times n$ matrix.

How do we compute $e^{\underline{A}}$?

Start w/ Easy cases.

→ Diagonal matrices.

$$\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}^2 = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{bmatrix}$$

$$\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}^k = \begin{bmatrix} \lambda_1^k & 0 \\ 0 & \lambda_2^k \end{bmatrix} \leftarrow \text{special to diag. matrices.}$$

$$A = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

$$e^{At} = Id + \frac{A}{1!}t + \frac{1}{2!}A^2t^2 + \frac{1}{3!}A^3t^3 + \dots$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}t + \frac{1}{2!} \begin{bmatrix} a^2 & 0 \\ 0 & b^2 \end{bmatrix}t^2 + \frac{1}{3!} \begin{bmatrix} a^3 & 0 \\ 0 & b^3 \end{bmatrix}t^3 + \dots$$

$$= \begin{bmatrix} 1 + a + \frac{1}{2!}a^2t + \dots & 0 \\ 0 & 1 + b + \frac{1}{2!}b^2t + \dots \end{bmatrix} = \begin{bmatrix} e^a & 0 \\ 0 & e^b \end{bmatrix}$$

Can use def'n to compute e^{At} , $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$.

$$e^{At} = \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \quad \left(At = \begin{bmatrix} t & 0 \\ 0 & 2t \end{bmatrix} \right)$$