

Plan: (S. 2)

- Solving linear systems with distinct real eigenvalues
- Examples, elementary row operations

If  $\underline{x}_1(t), \dots, \underline{x}_n(t)$  are lin. indep. sols of  $\underline{\dot{x}} = P(t) \underline{x}$   
 then any other sol'n of  $\underline{\dot{x}} = P(t) \underline{x}$  is of form

$$\underline{x} = c_1 \underline{x}_1(t) + \dots + c_n \underline{x}_n(t)$$

↑                              ↗  
 const., possibly complex.

$P(t) = \underline{A}$  const. matrix, real entries

$\Sigma_k$ :  $\underline{A} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}, \quad \underline{\dot{x}} = \underline{A} \underline{x}$

no t dependence.

Would need 2 lin. indep. sols.

Remember:  $y'' + 2y' + 3y = 0$  tried  $y = e^{rt}$ , found  
 char. eqn, found r.

Today: hope that a sol'n to  $\underline{\dot{x}} = \underline{A} \underline{x}$  looks  
 like  $\underline{x} = e^{\lambda t} \underline{v}$   $\leftarrow$  unknown vector

unknown scalar

$$\underline{\dot{x}} = \underline{A} \underline{x} \Rightarrow \lambda e^{\lambda t} \underline{v} = \underline{A}(e^{\lambda t} \underline{v})$$

$$e^{\lambda t} \neq 0 \Rightarrow \lambda \underline{v} = \underline{A} \underline{v} \Rightarrow \underline{A} \underline{v} = \lambda \underline{I} \underline{v}$$

identity,  $n \times n$

$$\Rightarrow (\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}.$$

If we can find  $\lambda \in \mathbb{C}$  (or  $\mathbb{R}$ ) so that there exists  $\underline{v} \neq \underline{0}$  satisfying  $(\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}$  then

$$\underline{x} = e^{\lambda t} \underline{v}$$

would be a (non-trivial) solution of  $\dot{\underline{x}} = \underline{A} \underline{x}$ .

*n × n*

Want: non-zero sol'n to  $(\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}$   
 This happens when

$$\textcircled{1} \quad \det(\underline{A} - \lambda \underline{I}) = 0 \leftarrow \text{characteristic eqn of } \underline{A}.$$

A  $\lambda$  (real, complex or 0) which satisfies  $\textcircled{1}$  is called an eigenvalue of  $\underline{A}$ .

An eigenvector associated w/ an eigenvalue  $\lambda$  is a non-zero vector  $\underline{v}$  so that

$$(\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0} \Leftrightarrow \underline{A}\underline{v} = \lambda \underline{v}$$

$$\text{Ex: } \underline{A} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad \underline{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{A}\underline{v} = 1 \cdot \underline{v}$$

Method Given  $\underline{\dot{x}} = \underline{A} \underline{x}$ ,  $\underline{A}$  const. matrix,  $n \times n$ .

1. Solve characteristic equation.

$$\det(\underline{A} - \lambda \underline{I}) = 0$$

→ find eigenvalues  $\lambda_1, \dots, \lambda_n$  ( $n$  of them, possibly complex or repeated)

2. Find associated eigenvectors  $\underline{v}_1, \dots, \underline{v}_n$

3. If process gives  $n$  linearly eigenvectors then:

$x_1(t) = e^{\lambda_1 t} \underline{v}_1, \dots, x_n(t) = e^{\lambda_n t} \underline{v}_n$   
are lin. indep. sol's of  $\underline{\dot{x}} = \underline{A} \underline{x}$

4. Any soln is of form

$$\underline{x} = c_1 x_1(t) + \dots + c_n x_n(t)$$

all different from each other

Fact

If  $\lambda_1, \dots, \lambda_n$  are all distinct then step 3 works.

Ex:  $\underline{A} = \begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix}$   $\underline{\dot{x}} = \underline{A} \underline{x}$

$$\underline{I} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

1. Find eigenvalues

$$\det(A - \lambda I) = \det \begin{bmatrix} 5-\lambda & 0 & -6 \\ 2 & -1-\lambda & -2 \\ 4 & -2 & -4-\lambda \end{bmatrix}$$

$$= (5-\lambda) \left| \begin{array}{cc|c} -1-\lambda & -2 & +0 \\ -2 & -4-\lambda & \\ \hline -6 & 2 & -1-\lambda \\ 4 & -2 & \end{array} \right|$$

$$= (5-\lambda) \left( (-1-\lambda)(-4-\lambda) - 4 \right) - 6(-4 - 4(-1-\lambda))$$

$$= \dots =$$

$$= \lambda - \lambda^3$$

So:

$$\det(A - \lambda I) = 0 \Leftrightarrow \lambda - \lambda^3 = 0 \Leftrightarrow \underbrace{1, -1, 0}_{\text{distinct!}}$$

method works

2. Find eigenvectors

$$\lambda = 0$$

$$(A - 0I)v = 0$$

Want:

$$\begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \textcircled{1} & \quad \left\{ \begin{array}{l} 5v_1 - 6v_3 = 0 \\ 2v_1 - v_2 - 2v_3 = 0 \end{array} \right. \\ \textcircled{2} & \quad \left. \begin{array}{l} \\ 4v_1 - 2v_2 - 4v_3 = 0 \end{array} \right. \end{aligned}$$

multiple  
of  $\textcircled{2}$ , no  
new info.

$$\textcircled{1} \Rightarrow v_1 = \frac{6}{5}v_3$$

$$\textcircled{2} \Rightarrow v_2 = 2 \cdot \frac{6}{5}v_3 - 2v_3$$

so:

$$\begin{bmatrix} \frac{6}{5}v_3 \\ \frac{12}{5}v_3 - 2v_3 \\ v_3 \end{bmatrix} = \begin{bmatrix} \frac{6}{5} \\ \frac{12}{5} - 2 \\ 1 \end{bmatrix} v_3$$

we have an eigenvector for any  $v_3 \neq 0$

take  $v_3 = 5$ , an e-vector associated  
w/  $\lambda = 0$  is

$$v = \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix}, \text{ so}$$

$c_1 e^{0t} \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix}$  solves  
 $\begin{matrix} x' = Ax \\ = \end{matrix}$

$$\underline{\underline{\lambda = 1}} \quad (A - 1 \cdot I) v = 0$$

$$\begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 0 & -6 \\ 2 & -2 & -2 \\ 4 & -2 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Elementary row operations:

1. interchange rows
2. multiply row by non-zero number
3. add multiple of a row to another.

1st goal: have 1 at top left, 0's under it.

$$\left| \begin{array}{ccc|c} 4 & 0 & -6 & 0 \\ 2 & -2 & -2 & 0 \\ 4 & -2 & -5 & 0 \end{array} \right|$$

(2)  $\leftrightarrow$  (1)

$$\left[ \begin{array}{ccc|c} 2 & -2 & -2 & 0 \\ 4 & 0 & -6 & 0 \\ 4 & -2 & -5 & 0 \end{array} \right]$$

$\frac{1}{2} \textcircled{1} \rightarrow \textcircled{1}$

$$\left[ \begin{array}{ccc|c} 1 & -1 & -1 & 0 \\ 4 & 0 & -6 & 0 \\ 4 & -2 & -5 & 0 \end{array} \right]$$

$\textcircled{2} - 4 \cdot \textcircled{1} \rightarrow \textcircled{2}$   
 $\textcircled{3} - 4 \cdot \textcircled{1} \rightarrow \textcircled{3}$

$$\left[ \begin{array}{ccc|c} 1 & -1 & -1 & 0 \\ 0 & 4 & -2 & 0 \\ 0 & 2 & -1 & 0 \end{array} \right]$$

$\textcircled{3} - \frac{1}{2}\textcircled{2} \rightarrow \textcircled{3}$

$$\left[ \begin{array}{ccc|c} 1 & -1 & -1 & 0 \\ 0 & 4 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Equiv. system:

$$\left[ \begin{array}{ccc} 1 & -1 & -1 \\ 0 & 4 & -2 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$v_3 = 2v_2$$

$$v_1 = v_2 + 2v_2 \Rightarrow v_1 = 3v_2$$

$$V = \begin{bmatrix} 3v_2 \\ v_2 \\ 2v_2 \end{bmatrix}$$

is an eigenvector. Take  
 $v_2 = 1$

$$\underline{x}(t) e^t \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} \text{ is a sol'n.}$$

Ex: do case  $\lambda = -1$ , find eigen v.  $v_3$

General soln of  $\dot{\underline{x}} = A \underline{x}$

$$\underline{x} = c_1 \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix} + c_2 e^t \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} + c_3 e^{-t} \underline{v}_3$$