

## Lesson 6

01/24/2022

### §5.5 Linear systems with defective eigenvalues

Ex 1:  $\underline{x}' = \underline{A} \underline{x}$ ,  $\underline{A} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

Want: 2 lin. indep. sols.

Find e-values:

$$\det(\underline{A} - \lambda \underline{I}) = \begin{vmatrix} 1-\lambda & 0 \\ 0 & 1-\lambda \end{vmatrix} \\ = (1-\lambda)^2$$

$$\Rightarrow (1-\lambda)^2 = 0 \Rightarrow \lambda = 1 \text{ multiplicity 2.}$$

Seek eigenvectors

$$(\underline{A} - 1 \cdot \underline{I}) \underline{v} = \underline{0} \Rightarrow \underline{0} \underline{v} = \underline{0}$$

Any non-zero vector is an e-vector.

In particular, we can find 2 lin indep. e-vectors.

E.g.:  $\underline{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $\underline{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$\Rightarrow$  We can build 2 lin. indep. sols as

$$\underline{x}_1(t) = e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \underline{x}_2(t) = e^t \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$\Rightarrow$  gen. sol'n:

$$\underline{x}(t) = c_1 e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^t \begin{bmatrix} 0 \\ 1 \end{bmatrix} //$$

Ex 2 :

$$\underline{x}' = \underbrace{\begin{bmatrix} 1 & -4 \\ 4 & 9 \end{bmatrix}}_{\underline{A}} \underline{x}$$

Eigenvalues:  $\lambda = 5$ , multiplicity 2

Eigenvectors:  $(\underline{A} - 5\underline{I}) \underline{v} = \underline{0}$

$$\begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} -4v_1 - 4v_2 = 0 \\ \cancel{4v_1 + 4v_2 = 0} \end{cases}$$

$$\Rightarrow v_1 = -v_2$$

Can take

$$\underline{v} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$\Rightarrow$  a sol'n of  $\underline{x}' = \underline{A} \underline{x}$  is

$$\underline{x}(t) = e^{5t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Q: How do we find a second lin. indep. sol'n?

Method above doesn't give a second

lin. indep. soln.

A: Look for sol'n in a different form.

Terminology: If  $\lambda$  is an eigenvalue of  $\underline{A}$  w/ multiplicity  $k$  and we can find at most  $p \leq k$  lin. indep. eigenvectors associated w/  $\lambda$  then we say that  $\lambda$  has defect  $k-p$ .

In Ex 1: defect =  $2 - 2 = 0$

Ex 2: defect =  $2 - 1 = 1$

If defect  $\geq 1$  then  $\lambda$  is called defective

To deal w/ eigenvalues of defect 1.  
Assume that a sol'n of  $\underline{x}' = \underline{A}\underline{x}$  has the form

$$\underline{x}(t) = e^{\lambda t} (\underline{v}_1 t + \underline{v}_2)$$

w/  $\underline{v}_1 \neq \underline{0}$ .

Plug in:

$$\cancel{\lambda e^{\lambda t}} (\underline{v}_1 t + \underline{v}_2) + \cancel{e^{\lambda t}} \underline{v}_1 = \underline{A} (\cancel{e^{\lambda t}} (\underline{v}_1 t + \underline{v}_2))$$



reorganize  
 $\Rightarrow$

$$(\lambda \underline{v}_1 - \underline{A} \underline{v}_1) t + (\lambda \underline{v}_2 + \underline{v}_1 - \underline{A} \underline{v}_2) = 0 \quad \text{for all } t.$$

$$\Rightarrow \begin{cases} (\underline{A} - \lambda \underline{I}) \underline{v}_1 = \underline{0} & \textcircled{1} \\ (\underline{A} - \lambda \underline{I}) \underline{v}_2 = \underline{v}_1 \neq \underline{0} & \textcircled{2} \end{cases}$$

$\textcircled{1} \Rightarrow$   $\lambda$  is an eigenvalue  
 $\underline{v}_1$  is an eigenvector

Note:

$$\begin{aligned} (\underline{A} - \lambda \underline{I})^2 \underline{v}_2 &= (\underline{A} - \lambda \underline{I}) (\underline{A} - \lambda \underline{I}) \underline{v}_2 \\ &= (\underline{A} - \lambda \underline{I}) \underline{v}_1 = \underline{0} \end{aligned}$$

So  $\underline{v}_2$  satisfies

$$\begin{cases} (\underline{A} - \lambda \underline{I})^2 \underline{v}_2 = \underline{0} \\ (\underline{A} - \lambda \underline{I}) \underline{v}_2 \neq \underline{0} \end{cases}$$

A vector  $\underline{v}_2$  which satisfies  $\textcircled{*}$  is called a generalized vector of rank 2.

So: to find a sol'n we should find

a generalized e-vector  $\underline{v}_2$  by ~~\*~~ and an eigenvector  $\underline{v}_1$  tied to  $\underline{v}_2$  via 2.

Back to our Ex 2:

Look for gen. e-vector.

Want:

$$\underbrace{\begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix}}_{(A-5I)} \underline{v}_2 = \underline{0} \quad \textcircled{1}$$

AND

$$\begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix} \underline{v}_2 \neq \underline{0} \quad : \quad \textcircled{2}$$

Note:  $\begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix}^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

So  $\textcircled{1} \Rightarrow$  gives no restrictions on  $\underline{v}_2$  :  
any restriction will come from

$\textcircled{2}$

Want:  $\begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix} \underline{v}_2 \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Can take  $\underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 25 \\ -2 \end{bmatrix}, \dots$

Can't take  $\underline{v}_2$  to be an eigenvector:  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix}$   
won't work.

E.g. take  $\underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and

$$\underline{v}_1 = (A - 5I) \underline{v}_2$$

3

$$= \begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$= \begin{bmatrix} -8 \\ 8 \end{bmatrix}$$



$\underline{v}_1$  is an eigenvector but not any e-vector: it is tied to  $\underline{v}_2$  by means of 3

A sol'n of  $\underline{x}' = \underline{A} \underline{x}$  is given by

$$\underline{x}_2(t) = e^{5t} \left( \begin{bmatrix} -8 \\ 8 \end{bmatrix} t + \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right),$$

and it is lin. indep. from  $\underline{x}_1 = e^{5t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ .

The general sol'n can be written as

$$\underline{x}(t) = c_1 \underline{x}_1(t) + c_2 \underline{x}_2(t)$$

$$= c_1 e^{5t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{5t} \left( \begin{bmatrix} -8 \\ 8 \end{bmatrix} t + \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right).$$



Again:  $\underline{x}(t) = e^{5t} \left( \begin{bmatrix} -1 \\ 1 \end{bmatrix} t + \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$  is  
not a sol'n for  $\underline{x}' = \underline{A} \underline{x}$   
 even though  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is a generalized  
 e-vector and  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  is an e-vector  
 bec.  $\begin{bmatrix} -1 \\ 1 \end{bmatrix} \neq \begin{bmatrix} -4 & -4 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

Summary of method for systems w/  
 an e-value of defect 1.

1. Find eigenvalue(s) and corresponding e-vectors
2. For a defective eigenvalue  $\lambda$ , find a generalized e-vector of rank 2, i.e. solve

$$\begin{cases} (\underline{A} - \lambda \underline{I})^2 \underline{v}_2 = \underline{0} \\ (\underline{A} - \lambda \underline{I}) \underline{v}_2 \neq \underline{0} \end{cases} \quad \underline{v}_2 \neq \underline{0}$$

Set  $\underline{v}_1 = (\underline{A} - \lambda \underline{I}) \underline{v}_2$

$\underline{x}(t) = e^{\lambda t} (\underline{v}_1 t + \underline{v}_2)$  is a sol'n.  
 $e^{\lambda t} \underline{v}_1$  is also a sol'n, lin.  
 independent.