

Sketch of solutions.

1. a.) Eigenvalues: $\lambda = 2 \pm 2i$

Eigenvector v_1 :

$$\begin{bmatrix} -1-2i & -5 \\ 1 & 1-2i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Take $\underline{v} = \begin{bmatrix} -5 \\ 1+2i \end{bmatrix}$

Solⁿ:

$$\underline{x}(t) = \underline{v} e^{(2+2i)t}$$
$$= e^{2t} \begin{bmatrix} -5 \cos(2t) - 5i \sin(2t) \\ \cos(2t) - 2\sin(2t) + i(\sin(2t) + 2\cos(2t)) \end{bmatrix}$$

Take real & imaginary parts: sols:

$$\underline{x}_1(t) = e^{2t} \begin{bmatrix} -5 \cos(2t) \\ \cos(2t) - 2\sin(2t) \end{bmatrix}$$

$$\underline{x}_2(t) = e^{2t} \begin{bmatrix} -5 \sin(2t) \\ \sin(2t) + 2\cos(2t) \end{bmatrix}$$

Check linear indep.: Wronskian

$$W(x_1, x_2) = e^{4t} \begin{vmatrix} -5 \cos(2t) & -5 \sin(2t) \\ \cos(2t) - 2\sin(2t) & \sin(2t) + 2\cos(2t) \end{vmatrix}$$

$$= e^{4t} \left(-5 \cos(2t) \sin(2t) - 10 \cos^2(2t) + 5 \sin(2t) \cos(2t) - 10 \sin^2(2t) \right)$$

$$= -10 e^{4t} \neq 0 \Rightarrow \text{lin. indep.}$$

b. Fig. 1 (spiral source).

2. Eigenvalues: $\lambda_1 = -2, \lambda_2 = 5$

Eigenvectors:

$$\text{for } \lambda_1 = -2, \underline{v}_1 = \begin{bmatrix} 1 \\ -6 \end{bmatrix}$$

$$\text{for } \lambda_2 = 5, \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{gen. sol'n: } \underline{x} = c_1 e^{-2t} \begin{bmatrix} 1 \\ -6 \end{bmatrix} + c_2 e^{5t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\underline{x}(0) = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \Rightarrow \begin{cases} c_1 + c_2 = 2 \\ -6c_1 + c_2 = -1 \end{cases} \Rightarrow \begin{cases} c_1 = \frac{3}{7} \\ c_2 = \frac{11}{7} \end{cases}$$

$$\Rightarrow \underline{x}(t) = \frac{3}{7} e^{-2t} \begin{bmatrix} 1 \\ -6 \end{bmatrix} + \frac{11}{7} e^{5t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

3. Find defect: Eigenvector system $(\underline{A} - 2\underline{I})\underline{v} = \underline{0}$

$$\begin{bmatrix} -17 & -7 & 4 \\ 34 & 14 & -11 \\ 17 & 7 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -17 & -7 & 4 \\ 0 & 0 & -3 \\ 0 & 0 & 7 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -17 & -7 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow v_3 = 0$$

$$-17v_1 - 7v_2 + 4v_3 = 0 \Rightarrow$$

$$v_1 = -\frac{7}{17}v_2$$

So defect 2. Look for chain of length 3.

Look for gen. e-vector of rank 3: want

$$\text{given } \begin{cases} (A - \lambda I)^3 v_3 = 0 \\ (A - \lambda I)^2 v_3 \neq 0 \end{cases}$$

$$\text{Take } v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Then } v_2 = (A - \lambda I)v_3 = \begin{bmatrix} 4 \\ -11 \\ 3 \end{bmatrix}$$

$$v_1 = \begin{bmatrix} 21 \\ -51 \\ 0 \end{bmatrix} \leftarrow \text{true eigenvector}$$

Solu:

$$\underline{x} = c_1 e^{2t} \begin{bmatrix} 2 \\ -5 \\ 0 \end{bmatrix} + c_2 e^{2t} \left(\begin{bmatrix} 2 \\ -5 \\ 0 \end{bmatrix} t + \begin{bmatrix} 4 \\ -11 \\ 3 \end{bmatrix} \right) + c_3 e^{2t} \left(\begin{bmatrix} 2 \\ -5 \\ 0 \end{bmatrix} \frac{t^2}{2} + \begin{bmatrix} 4 \\ -11 \\ 3 \end{bmatrix} t + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right)$$

4. a). $F(0,0) = G(0,0) = 0$, so $(0,0)$ is crit. pt

b). Jacobian:

$$J = \begin{bmatrix} y e^{x+y} & (y+1) e^{x+y} \\ -(x+1) e^{x+y} & -x e^{x+y} \end{bmatrix}$$

$$\Rightarrow J(0,0) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}. \text{ Eigenvalues } \lambda = \pm i$$

Origin is a stable center.

c). The C.P. $(0,0)$ for the non-linear system is a stable center, a spiral source or a spiral sink.

d).

$$\frac{dy}{dx} = \frac{-x}{y} \Rightarrow y dy = -x dx$$

$$\Rightarrow \frac{1}{2} y^2 = -\frac{1}{2} x^2 + C$$

$$\Rightarrow x^2 + y^2 = 2C$$

so the origin is a center for the non-linear system as well.

5. Char. eqn: $(4-\lambda)(-1-\lambda) - \varepsilon = 0$

$$\Rightarrow \lambda^2 - 3\lambda - 4 - \varepsilon = 0$$

$$\Rightarrow \lambda = \frac{1}{2} \left(3 \pm \sqrt{25 + 4\varepsilon} \right)$$

Unstable node: eigenvalues must be both real & positive (distinct or repeated), so we want

1. $25 + 4\varepsilon > 0 \Rightarrow \varepsilon \geq -\frac{25}{4}$

2. $\sqrt{25 + 4\varepsilon} < 3$

$$\Rightarrow 25 + 4\varepsilon < 9 \Rightarrow$$

$$\Rightarrow \varepsilon < -4.$$

So $-\frac{25}{4} \leq \varepsilon < -4$

6. a) Predation: x is the predator
 y is the prey.

b) Want $x, y \geq 0$

$$\begin{cases} 7x - x^2 + xy = 0 & \textcircled{1} \\ y - 4xy = 0 & \textcircled{2} \end{cases}$$

$\textcircled{2} \Rightarrow y = 0$ or $x = \frac{1}{4}$

If $y = 0$ then $7x - x^2 = 0 \Rightarrow x = 0$ or $x = 7$

$$\text{If } x = \frac{1}{4} \text{ then } \textcircled{1} \Rightarrow 7 - \frac{1}{4} + y = 0 \Rightarrow$$

$$y = -7 + \frac{1}{4} < 0$$

not relevant.

So $(0, 0)$, $(7, 0)$ are the only relevant ones.

c). The population of the prey eventually vanishes and the predators approach $x = 7$.

7. Set $y = x'$. Then:

$$\begin{cases} x' = y \\ y' = -4x + 5x^3 - x^5 \end{cases}$$

Equil: find C.P.

$$\begin{cases} y = 0 & \textcircled{1} \\ -4x + 5x^3 - x^5 = 0 & \textcircled{2} \end{cases}$$

$$\textcircled{2} \Rightarrow x = 0 \text{ or}$$

$$-4 + 5x^2 - x^4 = 0 \Rightarrow x^4 - 5x^2 + 4 = 0$$

$$\Rightarrow x^2 = \frac{1}{2}(5 \pm 3) \Rightarrow x^2 = 4 \text{ or } x^2 = 1$$

$$\Rightarrow x = \pm 1, x = \pm 2.$$

So C.P. $(0, 0)$, $(\pm 2, 0)$, $(\pm 1, 0)$. For each

$(x(t), y(t)) = (x_0, y_0)$ is an equil. sol'n.

8. Full soln of this can be found in the handout on chains of gen. e-vectors, Ex. 2.

https://www.math.purdue.edu/~neptamin/303Sp22/Handouts/High_defect.pdf

b) Check that $A \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 3 \end{bmatrix}$

c) We'd have to solve

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$\Rightarrow 0 \cdot d = 1$, impossible.

So the bottom-to-top approach does not work in this case.