Parametrizing surfaces

February 27, 2018

1. Ellipsoids: The ellipsoid

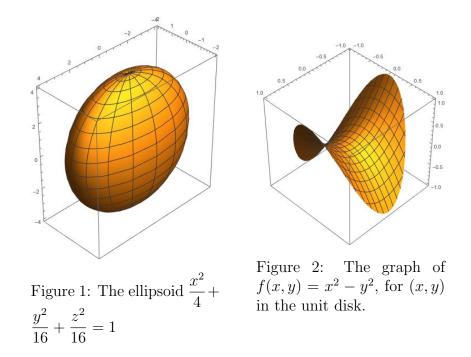
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

can be parametrized by setting

$$\vec{r}(u,v) = \langle a\sin(u)\cos(v), b\sin(u)\sin(v), c\cos(u) \rangle \text{ for } (u,v) \in [0,\pi] \times [0,2\pi].$$

As a special case, the **sphere** $x^2 + y^2 + z^2 = r^2$ can be parametrized as

 $\vec{r}(u,v) = \langle r\sin(u)\cos(v), r\sin(u)\sin(v), r\cos(u) \rangle \text{ for } (u,v) \in [0,\pi] \times [0,2\pi].$



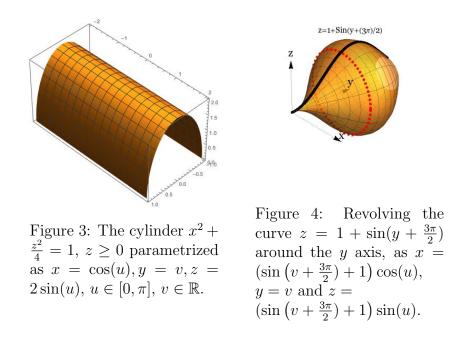
2. Graphs: When our surface is the graph of a function f(x, y), where $(x, y) \in D$, we can let x = u, y = v and z = f(u, v), that is,

$$\vec{r}(u,v) = \langle u, v, f(u,v) \rangle$$
 for $(u,v) \in D$.

- Cylinders: (in a broad sense, surfaces described by an equation that only involves 2 variables, e.g. x² + z²/4 = 1.) We look at the equation of the cylinder and parametrize as if it were a plane curve, with respect to u. Then set the third variable to be v. In this example, we would write x = cos(u), z = 2 sin(u), u ∈ [0, 2π] and y = v, v ∈ ℝ.
- 4. Surfaces of Revolution: Say that we'd like to parametrize the surface obtained by revolving the graph of $z = f(y), y \in [a, b]$ around the y axis. Then we can set y = v and therefore, since for each v we have a circle of radius f(v) on the plane y = v,

 $\vec{r}(u,v) = \langle f(v)\cos(u), v, f(v)\sin(u) \rangle, (u,v) \in [0,2\pi] \times [a,b].$

We work similarly if we need to revolve about another axis.



5. Tori: A torus (bagel) about the z axis can be parametrized as

 $\vec{r}(u,v) = \langle (a + b\cos(v))\cos(u), (a + b\cos(v))\sin(u), b\sin(v) \rangle, \text{ for } (u,v) \in [0,2\pi] \times [0,2\pi],$ where 0 < b < a.

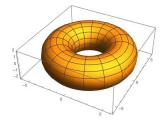


Figure 5: A torus with parametrization $x = (4 + 2\cos(v))\cos(u), y = (4 + 2\cos(v))\sin(u), z = 2\sin(v)$, for $(u, v) \in [0, 2\pi] \times [0, 2\pi]$.