

Lecture #7

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Due to the Survey results, let's practice more today, leaving §2.5 to the end.

Ex1: (True/False) Any $f: \mathbb{C} \rightarrow \mathbb{C}$ differentiable at z_0 is continuous at z_0

True: As $g(z) := \frac{f(z) - f(z_0)}{z - z_0} \xrightarrow{z \rightarrow z_0} a \in \mathbb{C} \Rightarrow f(z) - f(z_0) = a(z - z_0) + h(z)(z - z_0)$ with $h(z) \xrightarrow{z \rightarrow z_0} 0$

Thus, $|f(z) - f(z_0)| \leq |a| \cdot |z - z_0| + |h(z)| \cdot |z - z_0| \rightarrow 0$ as $z \rightarrow z_0$
 $\uparrow$ triangular inequality

Ex2: Compute $\lim_{z \rightarrow i} \frac{1+z^6}{1+z^{10}}$

Hint: As in usual calculus, we can apply L'Hopital rule which says that if $f(z), g(z)$ are analytic at z_0 , with $f(z_0) = 0 = g(z_0)$, $g'(z_0) \neq 0$, then:

$$\lim_{z \rightarrow z_0} \frac{f(z)}{g(z)} = \lim_{z \rightarrow z_0} \frac{\frac{f(z) - f(z_0)}{z - z_0}}{\frac{g(z) - g(z_0)}{z - z_0}} = \frac{f'(z_0)}{g'(z_0)}$$

For $f(z) = 1+z^6$, $g(z) = 1+z^{10}$, note that $f(i) = 0 = g(i)$, while $f'(i) = 6i^5$, $g'(i) = 10i^9$

So: $\lim_{z \rightarrow i} \frac{f(z)}{g(z)} = \frac{6i^5}{10i^9} = \frac{3}{5}$ as $i^4 = 1$

Ex3: At which points is $z \mapsto |z|^2 = f(z)$ differentiable?

Proof #1 (from definition)

$$f'(z_0) = \lim_{\Delta z \rightarrow 0} \frac{|z_0 + \Delta z|^2 - |z_0|^2}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{(z_0 + \Delta z)(\bar{z}_0 + \bar{\Delta z}) - z_0 \bar{z}_0}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{\bar{z}_0 \cdot \Delta z + z_0 \cdot \bar{\Delta z} + \Delta z \cdot \bar{\Delta z}}{\Delta z}$$

$$= \bar{z}_0 + \lim_{\Delta z \rightarrow 0} z_0 \cdot \frac{\bar{\Delta z}}{\Delta z}$$

If $z_0 = 0$, then we just get $\bar{z}_0 = 0 \Rightarrow f'(0)$ is well-defined and equals 0.

If $z_0 \neq 0$, then if $f'(z_0)$ existed, we would also have $\lim_{\Delta z \rightarrow 0} \frac{\bar{\Delta z}}{\Delta z}$ which we showed last time doesn't exist.

Answer: Only at 0.

Much faster!

Proof #2 (Cauchy-Riemann = CR) Just need to find points where $\begin{cases} u_x = v_y \\ u_y = -v_x \end{cases}$

But $v(x,y) = 0 \Rightarrow v_x = 0 = v_y$, while $u(x,y) = x^2 + y^2 \Rightarrow u_x = 2x$, $u_y = 2y$

Hence CR holds only at $x=0, y=0 \Rightarrow$ at $z=0$

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Ex 4: Is $f(z) = 3x^2 + 2x - 3y^2 - 1 + (6xy + 2y)i$ an entire function?

If so, express it solely via z .

• By definition $f(z)$ -entire $\Leftrightarrow f$ is differentiable at each point

For the latter it suffices to check CR at each point.

$$u(x,y) = 3x^2 + 2x - 3y^2 - 1 \Rightarrow u_x = 6x + 2, u_y = -6y \quad \left. \vphantom{u(x,y)} \right\} \Rightarrow \text{CR holds!}$$

$$v(x,y) = 6xy + 2y \Rightarrow v_x = 6y, v_y = 6x + 2$$

So: yes $f(z)$ is entire.

• Looking carefully at $f(z)$ it is easy to recognize that $f(z) = 3z^2 + 2z - 1$ where $z = x + yi$

Best: in general, if you didn't see this right away, just plug

$x = \frac{z+\bar{z}}{2}, y = \frac{z-\bar{z}}{2i}$. Let's do it in above example:

$$\begin{aligned} f(z) &= 3\left(\frac{z+\bar{z}}{2}\right)^2 + 2\left(\frac{z+\bar{z}}{2}\right) - 3\left(\frac{z-\bar{z}}{2i}\right)^2 - 1 + \left(6 \cdot \frac{z+\bar{z}}{2} \cdot \frac{z-\bar{z}}{2i} + 2 \cdot \frac{z-\bar{z}}{2i}\right)i \\ &= \frac{3}{4}(z^2 + \bar{z}^2 + 2z\bar{z}) + (z + \bar{z}) + \frac{3}{4}(z^2 + \bar{z}^2 - 2z\bar{z}) - 1 + \frac{6}{4}(z + \bar{z})(z - \bar{z}) + (z - \bar{z}) \\ &= \frac{6}{4}z^2 + \frac{6}{4}\bar{z}^2 + z + \bar{z} - 1 + \frac{6}{4}z^2 - \frac{6}{4}\bar{z}^2 + z - \bar{z} = 3z^2 + 2z - 1 \end{aligned}$$

[Note: Once you know that $f(z)$ is entire and plug $x = \frac{z+\bar{z}}{2}, y = \frac{z-\bar{z}}{2i}$, you are guaranteed that after all cancellations there will be no $\bar{z}$!]

! Comment regarding some HWk 2 problems from §1.7, 2.1 that were asking to geometrically describe $w = f(z)$ as a transformation of the Riemann sphere:

• if you don't know geometric answer, there is only one way to do:

$$\begin{array}{l} z \mapsto (x_1, x_2, x_3) \text{ via Lemma 1 of Lecture 5} \\ w \mapsto (x_1', x_2', x_3') \text{ ---} \end{array} \left. \vphantom{z \mapsto (x_1, x_2, x_3)} \right\} \text{try to relate } (x_1', x_2', x_3') \text{ to } (x_1, x_2, x_3)$$

• In #15 from p. 58 it will actually be much faster to do opposite way:

$$\begin{array}{l} (x_1, x_2, x_3) \mapsto z \text{ via Lemma 2 of Lecture 5} \\ (x_1', x_2', x_3') \mapsto w \text{ ---} \end{array} \left. \vphantom{(x_1, x_2, x_3) \mapsto z} \right\} \text{verify these } z, w \text{ are related by stated } f\text{-leg}$$

geom. description

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The essence of Cauchy-Riemann eqs from [Thm 1, Thm 2 of Lecture 6] is as follows. Given $u, v: \mathbb{R}^2 \rightarrow \mathbb{R}$ such that u_x, u_y, v_x, v_y exist and are continuous:

$$f(z=x+iy) := u(x,y) + i \cdot v(x,y) \quad \Leftrightarrow \quad \underline{\text{CR}} \text{ holds} \quad \begin{cases} u_x(x_0, y_0) = v_y(x_0, y_0) \\ u_y(x_0, y_0) = -v_x(x_0, y_0) \end{cases}$$

is differentiable at $z_0 = x_0 + iy_0$

Note: The matrix consisting of first partial derivatives now takes the form

$$\begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} \stackrel{\text{CR}}{=} \begin{pmatrix} A & B \\ -B & A \end{pmatrix}$$

↑ called the Jacobian

← which corresponds to a linear map $\mathbb{R}^2 \rightarrow \mathbb{R}^2$
which is a composition of rotation and scaling

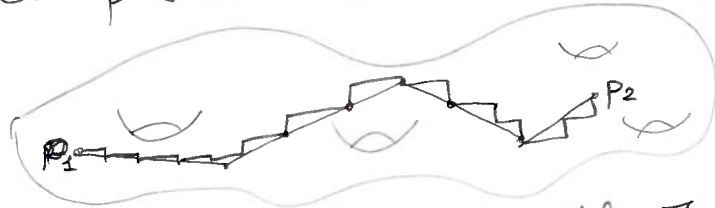
← which corresponds to $(A+Bi) \cdot$ as a map $\mathbb{C} \rightarrow \mathbb{C}$

Lemma: If $f(z)$ -analytic in a domain Ω , $f'(z)=0$ in $\Omega \Rightarrow f(z)=\text{const}$

The equality $f'(z_0) = u_x(x_0, y_0) + i \cdot v_x(x_0, y_0) = -i \cdot u_y(x_0, y_0) + v_y(x_0, y_0)$ from Lecture 6 imply:

$$u_x = 0 = u_y \text{ in } \Omega \text{ and similarly } v_x = 0 = v_y \text{ in } \Omega$$

As Ω is connected, any two points can be connected by a piece-wise linear path in Ω , which can be further approximated by a piece-wise linear path with each segment being horizontal or vertical.



As $u_x = 0 \Rightarrow u$ is constant on all horizontal segments
 $u_y = 0 \Rightarrow u$ is constant on all vertical segments

follows from Mean Value Theorem.

$\Rightarrow u(p_1) = u(p_2)$

Similarly: $v(p_1) = v(p_2) \Rightarrow f$ is constant

Corollary:- a) If f, g -analytic in domain and $f' = g'$ in $\Omega \Rightarrow f - g = \text{constant}$

b) If f -analytic and $\text{Im } f$ is constant $\Rightarrow f$ -constant

c) If f -analytic and $\text{Re } f$ is constant $\Rightarrow f$ -constant

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Ex 5: Show that if $f(z)$ is analytic in domain and $|f(z)| = \text{constant}$, then actually $f(z) = \text{constant}$.

• If $|f(z)| = 0 \Rightarrow$ clear as $f(z) = 0$ for all z .

• Assume $|f(z)| = c > 0$. Write $f(x+iy) = u(x,y) + i \cdot v(x,y)$.

Then $u^2(x,y) + v^2(x,y) = c^2$. Apply ∂_x or ∂_y to get:

$$\begin{cases} 2 \cdot u \cdot u_x + 2v \cdot v_x = 0 \\ 2 \cdot u \cdot u_y + 2v \cdot v_y = 0 \end{cases}$$

$\leftarrow$ each u, v, u_x, u_y, v_x, v_y is evaluated at the given point

But f -analytic $\stackrel{CR}{\Rightarrow} u_x = v_y, u_y = -v_x$. Hence, we get:

$$\begin{cases} u \cdot v_y + v \cdot v_x = 0 \\ -u \cdot v_x + v \cdot v_y = 0 \end{cases} \Rightarrow \begin{pmatrix} v & u \\ -u & v \end{pmatrix} \cdot \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow v_x = v_y = 0 \stackrel{CR}{\Rightarrow} u_x = u_y = 0$$

However, $\det \begin{pmatrix} v & u \\ -u & v \end{pmatrix} = u^2 + v^2 = c^2 \neq 0$

Hence, by the same argument as in the proof of lemma above:

$u = \text{const}, v = \text{const} \Rightarrow f = \text{constant}$

§2.5 Harmonic functions

Def: A function $g: \underbrace{\Omega}_{\text{domain in } \mathbb{R}^2} \rightarrow \mathbb{R}$ is called harmonic if it satisfies

the following equation $\underbrace{\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2}} = 0$

Laplace's equation, often written $\nabla^2 g = 0$
where $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$.

Theorem: If $f: \mathbb{C} \rightarrow \mathbb{C}$ is analytic in a domain $\Omega \subseteq \mathbb{C}$

then $\text{Re}(f), \text{Im}(f)$ are both harmonic functions in Ω

• Write $f(x+iy) = u(x,y) + i \cdot v(x,y)$. We shall see later: $u(x,y), v(x,y)$

admit continuous partial derivatives of any order!

(this is a surprising fact, very different from usual calculus)

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Continuation of the proof -

$$\begin{array}{lcl} \underline{\underline{C-R}} : & u_x = v_y & \xRightarrow{\text{apply } \partial_x} u_{xx} = v_{yx} \\ & u_y = -v_x & \xRightarrow{\text{apply } \partial_y} u_{yy} = -v_{xy} \end{array} \quad \left. \vphantom{\begin{array}{lcl} \underline{\underline{C-R}} : & u_x = v_y & \xRightarrow{\text{apply } \partial_x} u_{xx} = v_{yx} \\ & u_y = -v_x & \xRightarrow{\text{apply } \partial_y} u_{yy} = -v_{xy} \end{array}} \right\} \Rightarrow u_{xx} + u_{yy} = v_{yx} - v_{xy} = 0$$

↑ as both v_{xy}, v_{yx} are continuous

$$\Downarrow$$

u-harmonic

$$\begin{array}{lcl} \underline{\underline{C-R}} : & u_x = v_y & \xRightarrow{\text{apply } \partial_y} v_{yy} = u_{xy} \\ & -u_y = v_x & \xRightarrow{\text{apply } \partial_x} v_{xx} = -u_{yx} \end{array} \quad \left. \vphantom{\begin{array}{lcl} \underline{\underline{C-R}} : & u_x = v_y & \xRightarrow{\text{apply } \partial_y} v_{yy} = u_{xy} \\ & -u_y = v_x & \xRightarrow{\text{apply } \partial_x} v_{xx} = -u_{yx} \end{array}} \right\} \Rightarrow v_{xx} + v_{yy} = u_{xy} - u_{yx} = 0$$

$$\Downarrow$$

v-harmonic

Next time : Finish §2.5 & start §3.1