

Lecture #37

• Last time: Linear transformations & Linear Fractional Transformations  
= Möbius

Ex1 (True/False): a) Composition of Linear transformations is linear.

b) Inverse of Linear transformation is linear.

$$\begin{aligned} \triangleright \text{a) If } L_1(z) = az + b \text{ with } a \in \mathbb{C} \setminus 0, b \in \mathbb{C} \\ L_2(z) = \tilde{a}z + \tilde{b} \text{ with } \tilde{a} \in \mathbb{C} \setminus 0, \tilde{b} \in \mathbb{C} \end{aligned} \left\{ \Rightarrow (L_1 \circ L_2)(z) = a(\tilde{a}z + \tilde{b}) + b \right. \\ \left. = \underbrace{a\tilde{a}}_{\neq 0} \cdot z + (a\tilde{b} + b) \right.$$

$\Rightarrow L_1 \circ L_2$  is also linear  $\Rightarrow$  True!

$$\text{b) If } w = L_1(z) = az + b, \text{ then } z = \frac{w-b}{a} = \tilde{a}^{-1} \cdot w - \tilde{a}^{-1} \cdot b \Rightarrow L_1^{-1}(w) = \underbrace{\tilde{a}^{-1}}_{\neq 0} \cdot w - \tilde{a}^{-1} \cdot b$$

$\Rightarrow$  inverse  $L_1^{-1}$  is also linear  $\Rightarrow$  True!

Ex2 (True/False): Composition of any sequence of translation, magnification, and rotation is always linear.

$\triangleright$  As each of above three transformations is linear, the previous exercise shows that so is their composition  $\Rightarrow$  True!

[ Rmk: Last time we verified that every linear transformation is a composition of above three basic ones, but now we see that the converse is also true.

Ex3 (True/False): a) Composition of Möbius transp. is again Möbius

b) Inverse of any Möbius transformation is again Möbius

# Lecture #37

2

## ► (Solution of Ex3)

a) Let  $L_1(z) = \frac{az+b}{cz+d}$ ,  $L_2(z) = \frac{\tilde{a}z+\tilde{b}}{\tilde{c}z+\tilde{d}}$  with  $ad-bc \neq 0$ ,  $\tilde{a}\tilde{d}-\tilde{b}\tilde{c} \neq 0$ . Then

$$(L_1 \circ L_2)(z) = \frac{a \cdot \frac{\tilde{a}z+\tilde{b}}{\tilde{c}z+\tilde{d}} + b}{c \cdot \frac{\tilde{a}z+\tilde{b}}{\tilde{c}z+\tilde{d}} + d} = \frac{(a\tilde{a}+b\tilde{c})z + (a\tilde{b}+b\tilde{d})}{(c\tilde{a}+d\tilde{c})z + (c\tilde{b}+d\tilde{d})}$$

$$\text{Also: } (a\tilde{a}+b\tilde{c})(c\tilde{b}+d\tilde{d}) - (c\tilde{a}+d\tilde{c})(a\tilde{b}+b\tilde{d})$$

$$= a\tilde{c}\tilde{b} + ad\tilde{a}\tilde{d} + bc\tilde{b}\tilde{c} + bd\tilde{c}\tilde{d} - a\tilde{c}\tilde{a}\tilde{b} - bc\tilde{a}\tilde{d} - ad\tilde{b}\tilde{c} - bd\tilde{c}\tilde{d}$$

$$= (ad-bc)(\tilde{a}\tilde{d}-\tilde{b}\tilde{c}) \neq 0$$

So:  $L_1 \circ L_2$  is again a Möbius transformation  $\Rightarrow$  True!

b) If  $w = L_1(z) = \frac{az+b}{cz+d}$ , then  $az+b = cwz+dw \Rightarrow z = \frac{dw-b}{-cw+a}$

$\Rightarrow$  inverse transformation  $L_1^{-1}$  is  $L_1^{-1}(w) = \frac{dw-b}{-cw+a}$  with  $da-bc \neq 0$

$\Rightarrow$  again Möbius transformation  $\Rightarrow$  True!

Ex4 (True/False): Composition of any sequence of translation, magnification, rotation, and inversion is always a Möbius transform.

► As each of these basic 4 transformations is Möbius, so is their arbitrary composition by Ex3  $\Rightarrow$  True!

[ Rmk: Last time we verified that every Möbius transformation is a composition of above 4 basic ones, but now we see that the converse is also true.

Note:  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$  and this is compatible with above f-la  $L_1^{-1}(z)$

•  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \begin{pmatrix} \tilde{a} & \tilde{b} \\ \tilde{c} & \tilde{d} \end{pmatrix} = \begin{pmatrix} a\tilde{a}+b\tilde{c} & a\tilde{b}+b\tilde{d} \\ c\tilde{a}+d\tilde{c} & c\tilde{b}+d\tilde{d} \end{pmatrix}$  which is compatible with above f-la for  $L_1 \circ L_2$ .

(in fact, the group of Möbius transformations is  $PGL_2(\mathbb{C})$ )

## Lecture #37

Let's now solve the exercise from the very end of Lecture #36:

Ex 5: Find a conformal map of the unit disk  $D_1(0) = \{z \in \mathbb{C} : |z| < 1\}$  onto the upper half plane  $\mathcal{H} = \{w \in \mathbb{C} : \operatorname{Im} w > 0\}$

Idea: Look for a Möbius transformation  $f$  mapping the unit circle  $C_1(0) = \{z : |z| = 1\}$  onto the real line  $\mathbb{R} = \{w \in \mathbb{C} : \operatorname{Im} w = 0\}$  and then make sure that interior of  $C_1(0)$  is mapped to  $\mathcal{H}$ , not  $-\mathcal{H}$ .

- Note:  $f(C_1(0)) = \text{line} \iff f$  has a pole on  $C_1(0)$ . Thus, there are two points  $z_1, z_3 \in C_1(0)$  s.t.  $f(z_1) = 0$ ,  $f(z_3) = \infty$  (we use  $z_2$  not  $z_3$  for the latter discussion)

Let's make some choice, e.g.  $z_1 = -1$ ,  $z_3 = 1$ . Then

writing  $f(z) = \frac{az+b}{cz+d}$  we see  $a-b=0=c+d$ , so that  $f$  can be

written  $f(z) = A \cdot \frac{z+1}{z-1}$  (with  $A = \frac{a}{c} \in \mathbb{C} \setminus \{0\}$ ). For any  $A \neq 0$ , the

image of  $C_1(0)$  is thus a line passing through the origin.

- To make sure, this line  $\mathbb{R}$ , pick any other point on  $C_1(0)$ ,

e.g.  $z_2 = i$ . Then  $f(i) = A \cdot \frac{i+1}{i-1} = A \cdot \frac{1}{i}$ , hence  $f(i) \in \mathbb{R} \iff A \in i \cdot \mathbb{R}$

- Above shows that for any  $t \in \mathbb{R} \setminus \{0\}$ , the map  $z \mapsto f(z) = it \cdot \frac{z+1}{z-1}$  maps  $C_1(0)$  onto  $\mathbb{R}$ . But we also need interior to be mapped to  $\mathcal{H}$  not  $-\mathcal{H}$ . To do so, pick any point inside, e.g.  $z_4 = 0$ .

Then  $f(0) = it \cdot \frac{1}{-1} = -it$  which is in  $\mathcal{H}$  iff  $t < 0$ .

So: A possible answer is  $f(z) = -i \cdot \frac{z+1}{z-1} = i \cdot \frac{1+z}{1-z}$

An importance of such maps is illustrated by the following exercise:

# Lecture #37

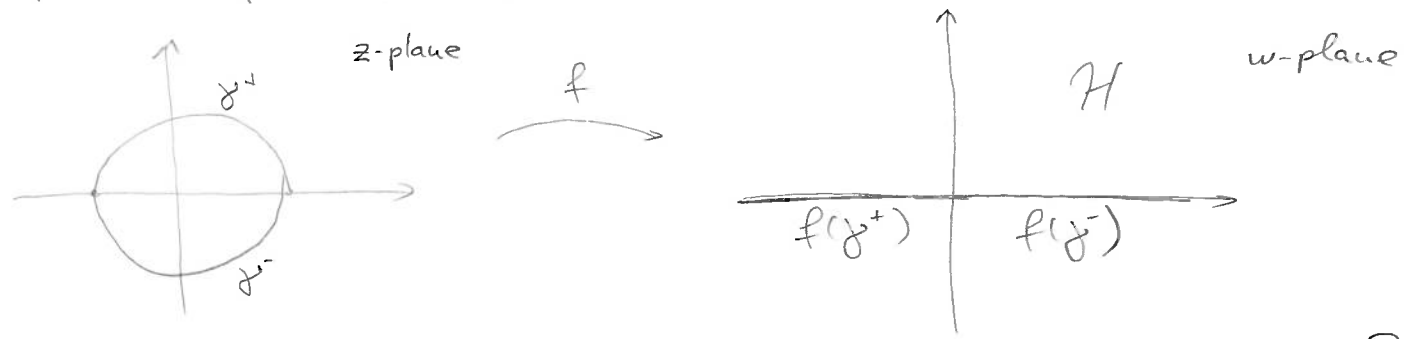
Ex 6 (~ [Example 1 in Section 7.1]): Find a harmonic function  $\phi(x,y)$  on the open unit disk  $D_1(0)$  such that

$$\begin{aligned} \phi(x,y) &\rightarrow +1 \text{ in } H \cap C_1(0) = \text{upper half-circle} =: \gamma^+ \\ &\rightarrow -1 \text{ in } (-H) \cap C_1(0) = \text{lower half-circle} =: \gamma^- \end{aligned}$$

Consider  $f = i \cdot \frac{1+z}{1-z}$  from Ex 5 which maps  $D_1(0) \xrightarrow[1:1]{\text{onto}} H$

As  $f(-1)=0$ ,  $f(i)=-1$ ,  $f(1)=\infty$ , we see that  $f(\gamma^+) = \mathbb{R}_{\leq 0}$

$f(-1)=0$ ,  $f(-i)=\frac{i}{-i}=1$ ,  $f(1)=\infty$ , we get  $f(\gamma^-) = \mathbb{R}_{\geq 0}$



Pick a harmonic  $\tilde{\phi}$  on  $H$  with boundary condition  $\tilde{\phi} \begin{cases} -1 \text{ in } \mathbb{R}_{>0} \\ +1 \text{ in } \mathbb{R}_{<0} \end{cases}$  by solving a wedge problem (see Lecture 11). For example, we look for  $\tilde{\phi} = A \cdot \arg_{-\pi/2} w + B$  so that 
$$\begin{aligned} B &= -1 \\ A \cdot \pi + B &= 1 \end{aligned} \quad \rightarrow \quad \begin{cases} A = 2/\pi \\ B = 1 \end{cases}$$

$\Rightarrow$  can take  $\tilde{\phi} = \frac{2}{\pi} \arg_{-\pi/2} w - 1$

$\Rightarrow \phi := \tilde{\phi} \circ f$  solves the problem, so that

$$\phi(x,y) = \frac{2}{\pi} \arg_{-\pi/2} \left( i \cdot \frac{1+z}{1-z} \right) - 1 = \frac{2}{\pi} \left( \arg_{-\pi/2} \left( \frac{1+z}{1-z} \right) + \frac{\pi}{2} \right) - 1 = \frac{2}{\pi} \arg_{-\pi/2} \frac{1+z}{1-z}$$

Here:  $z = x+iy \Rightarrow \frac{1+z}{1-z} = \frac{1+x+iy}{1-x-iy} = \frac{(1+x+iy)(1-x+iy)}{(1-x)^2+y^2} = \frac{1-x^2-y^2+i \cdot 2y}{(1-x)^2+y^2}$

$\Rightarrow \phi(x,y) = \frac{2}{\pi} \tan^{-1} \frac{2y}{1-x^2-y^2}$

[Rem: This solution is much easier than applying Poisson integral formula (see Lecture 18).

## Lecture #37

As we saw in Solution of Ex5, the key was to find a Möbius map  $f$  so that  $f: \mathbb{C}(0) \xrightarrow{\text{onto}} \mathbb{R}$ . This admits the following natural generalization:

Question 1: Find a Möbius map  $f$  which maps any given "generalized circle"  $C_1$  onto another given "generalized circle"  $C_2$ .

Here, a "generalized circle" means either a circle or a line (by Theorem from Lecture 36, we know Möbius maps: gen. circle  $\rightarrow$  gen. circle). The latter is determined by any 3 points on it (we get a line if the points are on a line). Hence, the above question admits the following upgrade:

Question 2: Given any three distinct points  $z_1, z_2, z_3$  in  $z$ -plane, and any three distinct points  $w_1, w_2, w_3$  in  $w$ -plane, find a Möbius map  $f$  s.t.  $f(z_1) = w_1, f(z_2) = w_2, f(z_3) = w_3$ .

To answer this, let's first find a Möbius map  $L_1$  so that

$L_1(z_1) = 0, L_1(z_2) = 1, L_1(z_3) = \infty$ . Arguing as in the sol-n of Ex5:

$L_1(z) = A \cdot \frac{z - z_1}{z - z_3}$  for some  $A \in \mathbb{C} \setminus \{0\}$  (which encodes  $L_1(z_1) = 0, L_1(z_3) = \infty$ )

Plug  $z = z_2$  to get  $1 = L_1(z_2) = A \cdot \frac{z_2 - z_1}{z_2 - z_3} \Rightarrow A = \frac{z_2 - z_3}{z_2 - z_1}$ .

So:  $L_1(z) = \frac{z - z_1}{z - z_3} \cdot \frac{z_2 - z_3}{z_2 - z_1}$   $\leftarrow$  This answers Question 2 in the special case  $w_1 = 0, w_2 = 1, w_3 = \infty$ .

But we can likewise consider Möbius map  $L_2$  so that

$L_2(w_1) = 0, L_2(w_2) = 1, L_2(w_3) = \infty$  which is given by formula alike:

$$L_2(w) = \frac{w - w_1}{w - w_3} \cdot \frac{w_2 - w_3}{w_2 - w_1}$$

But then the composition  $L_2^{-1} \circ L_1 =: f$  is a Möbius transformation (by Ex3) and satisfies  $f(z_1) = w_1, f(z_2) = w_2, f(z_3) = w_3$ , which answers above Question 2!

# Lecture #37

6

In fact, we claim that a solution  $f$  to Question 2 is unique:

Lemma 1: If  $S, T$  are Möbius transformations such that  $S(z) = T(z)$  at 3 points  $z \in \{z_1, z_2, z_3\}$ , then in fact  $S = T$ !

Consider  $L := S^{-1} \circ T$  which is also a Möbius transformation and satisfies  $L(z) = z$  at three distinct points. Then, by the next lemma,  $L(z) = z$  for all  $z \Rightarrow S = T$

Lemma 2: Any Möbius map that fixes three distinct points is identity

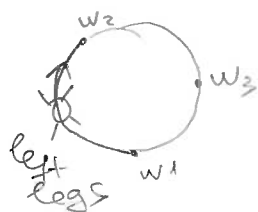
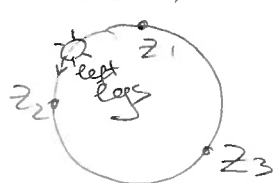
Let  $L(z) = \frac{az+b}{cz+d}$ .

Case 1 ( $c=0$ ):  $\frac{az+b}{d} = z \Leftrightarrow (a-d)z + b = 0$  has 3 sol-s only if  $\begin{cases} b=0 \\ a=d \end{cases}$   
 $\Rightarrow L(z) = \frac{az}{a} = z \Rightarrow L = \text{identity}$

Case 2 ( $c \neq 0$ ):  $\frac{az+b}{cz+d} = z \Leftrightarrow c \cdot z^2 + (d-a)z - b = 0$  has 3 sol-s only if  $\begin{cases} c=0 \\ b=0 \\ a=d \end{cases}$   
 $\Rightarrow \text{contradiction with } c \neq 0$

Remark: Now that we know how to construct a Möbius transformation

"Bug test"  $f$  mapping a circle  $C_1$  to a circle  $C_2$ , so that  $z_1, z_2, z_3 \in C_1$  are mapped to  $w_1, w_2, w_3 \in C_2$ , respectively, it still remains to understand if  $f$  maps interior of  $C_1$  to interior or exterior of  $C_2$ . (if  $C_1$  or  $C_2$  is a line, then we get two half planes)  
 To this end, imagine you have a "bug" crawling from  $z_1$  to  $z_2$ , and then look at its "image" from  $w_1$  to  $w_2$



In this picture  $f(\text{interior}) = \text{exterior}$