

Lecture #15

Last time:

- finished proof of Lie theorem
- proved Engel's theorem
- introduced notions of semisimple, simple, reductive Lie algs
- radical $\text{rad}(\mathfrak{g})$ and Levi theorem
- finished with decomposition of reductive Lie algs (as direct sum!)

$$\mathfrak{g} \simeq \underbrace{\mathfrak{z}(\mathfrak{g})}_{\text{abelian}} \oplus \underbrace{\mathfrak{g}_{\text{s.s.}}}_{\text{semisimple}}$$

(we shall get a different proof of this later)

Example: $\mathfrak{g} = \mathfrak{gl}_n \rightarrow \mathfrak{g} = \mathbb{C} \cdot \text{Id} \oplus \mathfrak{sl}_n$

Semisimplicity through invariant bilinear forms

Last time we established simplicity of \mathfrak{sl}_2 by brute force (using $\text{ad}(h): \mathfrak{sl}_2 \cong \mathbb{Z}$)

We shall now see how one could check semisimplicity in general.

Exercise: a) Verify that given any \mathfrak{g} -module V , the following defines a \mathfrak{g} -action on the space of all bilinear forms $V \times V \rightarrow \mathbb{K}$:

$$x \cdot B(v, w) = -B(x \cdot v, w) - B(v, x \cdot w) \quad \forall x \in \mathfrak{g}$$

We call B to be \mathfrak{g} -invariant if $B(x \cdot v, w) + B(v, x \cdot w) = 0 \quad \forall x \in \mathfrak{g} \quad \forall v, w$

b) Verify that B is \mathfrak{g} -invariant if the corresponding linear map $V \rightarrow V^*$, $v \mapsto B(v, -)$

is a \mathfrak{g} -module homom. (check that identifying bil. maps $V \times V \rightarrow \mathbb{K}$ with linear maps $V \rightarrow V^*$, action in a) agrees with that on V^*)

c) If V is an irreducible \mathfrak{g} -module, show that the space of \mathfrak{g} -inv. bilinear forms $V \times V \rightarrow \mathbb{C}$ is zero or 1-dimensional

d) If $V = \mathfrak{g}$ w.r.t. adjoint action of \mathfrak{g} , and $I \subseteq \mathfrak{g}$ -ideal, then its orthogonal complement $I^\perp = \{x \in \mathfrak{g} \mid B(x, y) = 0 \quad \forall y \in I\}$ is also ideal.

Example: Let $\mathfrak{g} = \mathfrak{gl}_n$ and $B(x, y) := \text{tr}(xy)$. It is clearly symmetric and invariant.

$$B([x, y], z) + B(y, [x, z]) = \text{tr}(xyz - yxz + yxz - yzx) = \text{tr}([x, yz]) = 0$$

Generalizing this example with the same proof, we have:

Lemma 1. For any \mathfrak{g} -module V , the following is a symmetric inv. bilinear form on \mathfrak{g} :

$$B_V(x, y) = \text{tr}_V(\rho(x)\rho(y))$$

Lecture #15

The reason why the forms from Lemma 1 are important is the following:

Lemma 2: Let \mathfrak{g} be a Lie alg, V \mathfrak{g} -module, s.t. $B_V: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{K}$ is nondegenerate
Then: \mathfrak{g} -reductive

Exercise: Given any filtration $0 = F_0 V \subseteq F_1 V \subseteq \dots \subseteq F_n V = V$ of a \mathfrak{g} -module V by submodules, we have $B_V(x, y) = \sum_{k=1}^n B_{F_k V / F_{k-1} V}(x, y) \forall x, y \in \mathfrak{g}$

Proof of Lemma 2

To prove \mathfrak{g} -reductive, it suffices to show that $[\mathfrak{g}, \text{rad}(\mathfrak{g})] = 0$.
Pick any $x \in [\mathfrak{g}, \text{rad}(\mathfrak{g})]$. Then by [Lecture 14, Prop 2], $\rho_W(x) = 0$ for any irreducible \mathfrak{g} -module (W, ρ_W) . Thus, $B_W(x, y) = 0 \forall y \in \mathfrak{g} \forall \text{irred. } W$.

But any fin. dim \mathfrak{g} -module V admits a (Jordan-Holder) filtration $0 = F_0 V \subseteq F_1 V \subseteq \dots \subseteq F_n V = V$ s.t. each $F_k V / F_{k-1} V$ is an irreducible \mathfrak{g} -mod.
Then $B_V(x, -) \equiv 0$ by the above Exercise \rightarrow contradiction!

Now we are ready to state our first key result for today:

Theorem 1: All classical Lie algebras are reductive.

- a) For $\mathfrak{g} = \mathfrak{gl}_n(\mathbb{K})$, consider the natural \mathfrak{g} -action $\mathfrak{gl}_n(\mathbb{K}) \curvearrowright \mathbb{K}^n =: V$
Then $B_V(x, y) = \sum_{i,j=1}^n x_{ij} y_{ji}$ is clearly non-degenerate (with $\{E_{ji}\}$ being dual to $\{E_{ij}\}$)
- b) For $\mathfrak{g} = \mathfrak{sl}_n(\mathbb{K})$, we take the same $V = \mathbb{K}^n$. Then $B_V(x, y) = 0$ for $x \in \mathfrak{sl}_n, y \in \mathbb{C} \cdot \text{Id}$, hence, non-degeneracy follows from a)
- c) For $\mathfrak{g} = \mathfrak{so}_n(\mathbb{K})$, take $V = \mathbb{K}^n$. Then:
 $B_V(x, y) = \sum_{i,j} x_{ij} y_{ji} \frac{x_{ij} = -x_{ji}}{y_{ij} = -y_{ji}} = -2 \sum_{i>j} x_{ij} y_{ij}$, which is clearly nondegenerate.

Exercise: a) Finish above proof by treating $\mathfrak{g} = \mathfrak{sp}_n(\mathbb{K}), \mathfrak{g} = \mathfrak{u}_n, \mathfrak{g} = \mathfrak{su}_n$ (explain why other cases follow as well)
b) Verify that $\mathfrak{sl}_n(\mathbb{K}), \mathfrak{so}_n(\mathbb{K})$ with $n > 2, \mathfrak{su}_n, \mathfrak{sp}_{2n}$ are semisimple, while $\mathfrak{gl}_n(\mathbb{K}) = \mathbb{K} \cdot \text{Id} \oplus \mathfrak{sl}_n(\mathbb{K}), \mathfrak{u}_n = i\mathbb{R} \cdot \text{Id} \oplus \mathfrak{su}_n$

As an important example of the above setup, we can consider $\mathfrak{g} \xrightarrow{\text{ad}} \mathfrak{g} =: V$.

Def 1: The Killing form on \mathfrak{g} is the bilinear form $B_{\mathfrak{g}}$ from above, i.e.

$$K(x, y) = \text{tr}_{\mathfrak{g}}(\text{ad } x \circ \text{ad } y) \quad \leftarrow \text{it's clearly symmetric}$$

Warning: If $\mathfrak{a} \leq \mathfrak{g}$ is a Lie subalgebra, then the Killing form on \mathfrak{a} is NOT the restriction of the one on \mathfrak{g} to $\mathfrak{a} \times \mathfrak{a}$. Hence, if needed, we shall use $K^{\mathfrak{a}}$ for the former and $K^{\mathfrak{g}}$ to the latter.

Exercise: If \mathfrak{a} is an ideal of \mathfrak{g} , then $K^{\mathfrak{a}} = K^{\mathfrak{g}}|_{\mathfrak{a} \times \mathfrak{a}}$.

Example: Let's work out example of \mathfrak{sl}_2 first of all. Pick a basis e, h, f :

$$\text{ad}(e) = \begin{pmatrix} 0 & -2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad \text{ad}(f) = \begin{pmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix}, \quad \text{ad}(h) = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

$$\text{Thus: } K(e, f) = K(f, e) = 4, \quad K(h, e) = K(e, h) = 0, \quad K(h, f) = K(f, h) = 0 \\ K(h, h) = 8, \quad K(e, e) = 0, \quad K(f, f) = 0.$$

$$\text{So: } K(x, y) = 4 \text{tr}(xy)$$

\uparrow by Exercise 1c) on p.1, this is not surprising as \mathfrak{sl}_2 -simple.

Our other two Key Results for today are Cartan's Criteria for solvability and semisimplicity of Lie algebras.

Theorem 2 (Cartan's Criteria for solvability): \mathfrak{g} -solvable iff $K([\mathfrak{g}, \mathfrak{g}], \mathfrak{g}) = 0$

Theorem 3 (Cartan's Criteria for semisimplicity):

$$\mathfrak{g}\text{-semisimple} \iff \text{Killing form } K \text{ is non-degenerate}$$

It is instructive to compare Thm 3 to Lemma 2.

Lecture #15

Let us first deduce Theorem 3 from Theorem 2.

Proof of Theorem 3

⇐: K -nondeg, hence, \mathfrak{g} -reductive by Lemma 2. Hence, remains to prove $z(\mathfrak{g}) = 0$.

Pick $x \in z(\mathfrak{g})$, then $\text{ad}(x) \equiv 0 \Rightarrow K(x, -) \equiv 0 \Rightarrow x \in \text{Ker } K \Rightarrow \downarrow$

⇒: Let \mathfrak{g} -semisimple, and set $I := \text{Ker } K$. By Exercise 1d), with $I = \mathfrak{g}$, get $I \subseteq \mathfrak{g}$ -ideal \Rightarrow Killing form of I is the restriction of the one on \mathfrak{g} .

Thus: $K^I \equiv 0 \xrightarrow{\text{Thm 2}} I$ -solvable, hence, $I = 0$ as \mathfrak{g} -semisimple

The proof of Theorem 2 is based on the following general result in linear alg:

Theorem 4 (Jordan decomposition): Let V be a fin. dim. complex vector space

a) Any linear operator A can be uniquely written as

$$A = A_s + A_n, \text{ with } \begin{array}{l} A_n \text{-nilpotent} \\ A_s \text{-semisimple (a.k.a. diagonalizable)} \\ A_s \cdot A_n = A_n \cdot A_s \end{array}$$

b) Define $\text{ad}(A): \text{End}(V) \ni B \mapsto \text{ad}(A)B := AB - BA = [A, B]$. Then:

$$\text{ad}(A)_s = \text{ad}(A_s), \text{ ad}(A)_n = \text{ad}(A_n)$$

and $\text{ad}(A_s)$ can be written as

$$\text{ad}(A_s) = p(\text{ad}(A)) \text{ for some } p \in \mathbb{C}[t]$$

c) Define \bar{A}_s that has the same eigenspaces as A_s , but conjugate eigenvalues

$$A_s v = \lambda v \Rightarrow \bar{A}_s v = \bar{\lambda} v$$

Then $\text{ad}(\bar{A}_s)$ can also be written as

$$\text{ad}(\bar{A}_s) = q(\text{ad}(A)) \text{ for some } q \in \mathbb{C}[t]$$

We shall now first deduce Thm 2 from Thm 4, and then prove Thm 4

Terminology: The operator $A: V \rightarrow V$ is called semisimple if \forall subspace $V' \subseteq V$ s.t. $A(V') \subseteq V' \exists V''$ s.t. $A(V'') \subseteq V''$ and $V = V' \oplus V''$.

Remark: As we shall see next time, the result also holds over \mathbb{R} , where semisimple \neq diagonalizable, but is deduced from version over \mathbb{C} .