

Multistage and Multistep Methods

- Euler's method is only first-order accurate
- Multistage method is a one-step method achieving high-order accuracy.
- Another way to achieve high accuracy is the Multistep method using several steps of previous values.

General R-stage Runge-Kutta family

$$U^{n+1} = U^n + \Delta t \Phi(U^n, t_n; \Delta t)$$

$$\Phi = \sum_{r=1}^R b_r k_r$$

$$k_r = f(Y_r, t_n + c_r \Delta t)$$

$$Y_r = U^n + \Delta t \sum_{j=1}^R a_{rj} f(Y_j, t_n + c_j \Delta t)$$

with

$$k_1 = f(U^n, t_n)$$

$$\sum_{j=1}^R a_{ij} = c_i, \quad i=1, \dots, R$$

$$\sum_{j=1}^R b_j = 1.$$

Butcher table

c_1	a_{11}	$\dots$	a_{1R}
$\vdots$	$\vdots$		$\vdots$
c_R	a_{R1}	$\dots$	a_{RR}
	b_1	$\dots$	b_R

Examples. 1. one-stage Runge-Kutta method $K=1$

$$u^{n+1} = u^n + \Delta t f(u^n, t_n) \quad \begin{array}{c|c} 0 & \\ \hline & 1 \end{array}$$

2. A two-stage explicit Runge-Kutta method

$$u^* = u^n + \frac{1}{2} \Delta t f(u^n, t_n)$$

$$u^{n+1} = u^n + \Delta t f(u^*, t_n + \frac{1}{2} \Delta t) \quad \begin{array}{c|c} 0 & \frac{1}{2} \\ \hline \frac{1}{2} & 1 \end{array}$$

$$(u^* \simeq \frac{u^{n+1} + u^n}{2} \text{ with } u(t_{n+1}) = u(t_n) + \int_{t_n}^{t_{n+1}} f(u, t) dt)$$

Combine the two steps

$$u^{n+1} = u^n + \Delta t f(u^n + \frac{1}{2} \Delta t f(u^n), t_n + \frac{1}{2} \Delta t)$$

$$\tau^n = \frac{u(t_{n+1}) - u(t_n)}{\Delta t} - f(u(t_n) + \frac{1}{2} \Delta t f(u(t_n), t_n), t_n + \frac{1}{2} \Delta t)$$

$$= u'(t_n) + \frac{1}{2} u''(t_n) \Delta t + \frac{1}{6} u'''(t_n) \Delta t$$

$$- \left[f + \frac{1}{2} \Delta t (f_u f + f_t) + \frac{1}{2} (\frac{1}{2} \Delta t)^2 (f_{uu} f^2 + 2 f_{tu} f + f_{tt}) \right]$$

+ h.o.t.

$$= O(\Delta t^2)$$

Notice that

$$u' = f, \quad u'' = \frac{df}{dt} = f_u u' + f_t$$

$$f(u(t_n) + \frac{1}{2} \Delta t f(u(t_n), t_n), t_n + \frac{1}{2} \Delta t) = f(u(t_n) + \frac{1}{2} \Delta t u'(t_n), t_n + \frac{1}{2} \Delta t)$$

Remark. We may also use the special test func. $u' = \ln$

$$\text{with } u(t_{n+1}) = e^{\lambda \Delta t} u(t_n)$$

$$\begin{aligned}
 u^{n+1} &= u^n + \Delta t \lambda (u^n + \frac{1}{2} \Delta t \lambda u^n) \\
 &= u^n + (\Delta t \lambda) u^n + \frac{1}{2} (\Delta t \lambda)^2 u^n \\
 &= e^{\Delta t \lambda} u^n + O(\Delta t^3)
 \end{aligned}$$

This is also a fundamental tool in stability analysis.

3. Trapezoidal rule for integral

$$u^{n+1} = u^n + \frac{1}{2} \Delta t f(u^n, t_n) + \frac{1}{2} \Delta t f(u^{n+1}, t_{n+1})$$

Another explicit two-stage RK

$$u^* = u^n + \Delta t f(u^n, t_n)$$

$$u^{n+1} = u^n + \frac{1}{2} \Delta t f(u^n, t_n) + \frac{1}{2} \Delta t f(u^*, t_{n+1})$$

0	
1	1
	$\frac{1}{2}$ $\frac{1}{2}$

4. A very popular 4th-order RK method

$$u^{(1)} = u^n$$

$$u^{(2)} = u^n + \frac{1}{2} \Delta t f(u^{(1)}, t_n)$$

$$u^{(3)} = u^n + \frac{1}{2} \Delta t f(u^{(2)}, t_n + \frac{1}{2} \Delta t)$$

$$u^{(4)} = u^n + \Delta t f(u^{(3)}, t_n + \frac{1}{2} \Delta t)$$

0			
$\frac{1}{2}$	$\frac{1}{2}$		
$\frac{1}{2}$	0	$\frac{1}{2}$	
1	0	0	1
	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$ $\frac{1}{6}$

$$\begin{aligned}
 u^{n+1} &= u^n + \frac{1}{6} \Delta t [f(u^{(1)}, t_n) + 2 f(u^{(2)}, t_n + \frac{1}{2} \Delta t) \\
 &\quad + 2 f(u^{(3)}, t_n + \frac{1}{2} \Delta t) + f(u^{(4)}, t_n + \Delta t)]
 \end{aligned}$$

Simpson's quadrature rule

$$u(t_{n+1}) - u(t_n) \approx \Delta t \left[\frac{1}{6} f(u(t_n), t_n) + \frac{4}{6} f(u(t_n + \frac{1}{2} \Delta t), t_n + \frac{1}{2} \Delta t) \right]$$

$$+ \frac{1}{6} f(u^{(4)}, t_{n+1})]$$

- Explicit RK methods: $a_{ij} = 0, j \geq i$
- Diagonally implicit RK methods: $a_{ij} = 0, j > i$

Order of accuracy

An R -stage explicit RK method can have order at most R .

# of stages R	1	2	3	4	5	6	7	8	9	10
attainable order (explicit RK)	1	2	3	4	4	5	6	6	7	7

Among implicit RK methods, R -stage methods of order $2R$ exist.

Example. Explicit three-stage Runge-Kutta method $R=3$

$$u^{n+1} = u^n + \Delta t (b_1 k_1 + b_2 k_2 + b_3 k_3)$$

$$k_1 = f(u^n, t_n)$$

$$k_2 = f(u^n + a_{21} \Delta t k_1, t_n + c_2 \Delta t)$$

$$k_3 = f(u^n + a_{31} \Delta t k_1 + a_{32} \Delta t k_2, t_n + c_3 \Delta t)$$

$$\begin{array}{ccc} 0 & & \\ c_2 & a_{21} & \\ c_3 & a_{31} & a_{32} \\ \hline & b_1 & b_2 & b_3 \end{array}$$

$$c_2 = a_{21}, \quad c_3 = a_{31} + a_{32}$$

Taylor series about (u^n, t_n) yields

$$\begin{aligned}
 k_2 &= f + \Delta t c_2 (f_t + k_1 f_u) + \frac{1}{2} \Delta t^2 c_2^2 (f_{tt} + 2k_1 f_{tu} + k_1^2 f_{uu}) \\
 &= f + \Delta t c_2 F_1 + \frac{1}{2} \Delta t^2 c_2^2 (f'' + O(\Delta t^3))
 \end{aligned}$$

with

$$F_1 = f_t + f f_u, \quad F_2 = f_{tt} + 2f f_{tu} + f^2 f_{uu}$$

$$\begin{aligned}
 k_3 &= f + \Delta t \{ c_3 f_t + [(c_3 - a_{32}) k_1 + a_{32} k_2] f_u \} \\
 &\quad + \frac{1}{2} \Delta t^2 \{ c_3^2 f_{tt} + 2c_3 [(c_3 - a_{32}) k_1 + a_{32} k_2] f_{tu} \\
 &\quad + [(c_3 - a_{32}) k_1 + a_{32} k_1^2] f_{uu} \} + O(\Delta t^3) \\
 &= f + \Delta t c_3 F_1 + \Delta t^2 (c_2 a_{32} f_1 f_u + \frac{1}{2} c_3^2 F_2) + O(\Delta t^3)
 \end{aligned}$$

$$\begin{aligned}
 \Phi(u^n, t_n; \Delta t) &= (b_1 + b_2 + b_3) f + \Delta t (b_2 c_1 + b_3 c_3) F_1 \\
 &\quad + \frac{1}{2} \Delta t^2 [2b_3 c_2 a_{32} F_1 f_u + (b_2 c_2^2 + b_3 c_3^2) F_2] + O(\Delta t^3)
 \end{aligned}$$

match with the Taylor series

$$\begin{aligned}
 \frac{u(t_{n+1}) - u(t_n)}{\Delta t} &= u'(t_n) + \frac{1}{2} \Delta t u''(t_n) + \frac{1}{6} \Delta t^2 u'''(t_n) + O(\Delta t^3) \\
 &= f + \frac{1}{2} \Delta t F_1 + \frac{1}{6} \Delta t^2 (F_1 f_u + F_2) + O(\Delta t^3)
 \end{aligned}$$

$$\Rightarrow b_1 + b_2 + b_3 = 1$$

$$b_2 c_1 + b_3 c_3 = \frac{1}{2}$$

$$b_2 c_2^2 + b_3 c_3^2 = \frac{1}{3}$$

$$b_3 c_2 a_{32} = \frac{1}{6}$$

(i) Heun's method

$$\begin{array}{ccc} 0 & & \\ \frac{1}{3} & \frac{1}{3} & \\ \frac{2}{3} & 0 & \frac{2}{3} \\ \hline & \frac{1}{4} & 0 & \frac{3}{4} \end{array}$$

(ii) Standard 3rd-order RK

$$\begin{array}{ccc} 0 & & \\ \frac{1}{2} & \frac{1}{2} & \\ 1 & -1 & 2 \\ \hline & \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array}$$

Absolute stability of RK methods

Consider $u' = \lambda u$, $u(0) = u_0 \neq 0$, (*)
and $\lambda < 0$ real.

We discuss R -stage RK method with order of accuracy R
that is, $1 \leq R \leq 4$.

1) $R = 1$, forward Euler's method

$$u^{n+1} = (1 + h) u^n, \quad n \geq 0 \text{ with } h = \lambda \Delta t$$

$$\Rightarrow u^n = (1 + h)^n u^0$$

$$\Rightarrow \text{sequence } \{u^n\}_{n=0}^{\infty} \text{ will converge iff } |1 + h| < 1$$

$$\Rightarrow \lambda \Delta t = h \in (-2, 0).$$

Euler's method is absolutely stable in $(-2, 0)$

The interval $(-2, 0)$ is referred to as interval of absolute stability

2) $K=2$

$$u^{n+1} = u^n + \Delta t (b_1 k_1 + b_2 k_2)$$

$$\text{where } k_1 = f(u^n, t_n), \quad k_2 = f(u^n + a_2 \Delta t k_1, t_n + c_2 \Delta t)$$

$$\text{and } b_1 + b_2 = 1, \quad c_2 b_2 = a_2, \quad b_2 = \frac{1}{2}$$

Applying this to (*) yields

$$u^{n+1} = (1 + h + \frac{1}{2}h^2) u^n \quad h = \Delta t$$

$$\Rightarrow u^n = (1 + h + \frac{1}{2}h^2)^n u^0$$

$\Rightarrow$ absolutely stable iff

$$|1 + h + \frac{1}{2}h^2| < 1 \Leftrightarrow h \in (-2, 0)$$

3) $K=3$ analogous argument shows

$$u^{n+1} = (1 + \hat{h} + \frac{1}{2}\hat{h}^2 + \frac{1}{6}\hat{h}^3) u^n$$

$$|1 + \hat{h} + \frac{1}{2}\hat{h}^2 + \frac{1}{6}\hat{h}^3| < 1$$

$$\Leftrightarrow \hat{h} \in (-2.51, 0)$$

4) $K=4$

$$u^{n+1} = (1 + \hat{h} + \frac{1}{2}\hat{h}^2 + \frac{1}{6}\hat{h}^3 + \frac{1}{24}\hat{h}^4) u^n$$

$$\Leftrightarrow \hat{h} \in (-2.87, 0)$$

In general, we will have

$$u^{n+1} = A_R(h) u^n$$

however, for $R \geq 5$ in addition to h , the expression for $A_R(h)$ also depends on the coefficients of the RK method.

Taylor Series methods

$$u(t_{n+1}) \approx u(t_n) + \Delta t u'(t_n) + \frac{1}{2} \Delta t^2 u''(t_n) + \dots \\ + \frac{1}{p!} \Delta t^p u^{(p)}(t_n)$$

$$\text{with } u'(t) = f(u(t), t)$$

$$u''(t) = f_u(u(t), t) u'(t) + f_t(u(t), t) \\ = f_u(u(t), t) f(u(t), t) + f_t(u(t), t)$$

Example. Solving $u'(t) = t^2 \sin(u(t))$

$$u''(t) = 2t \sin(u(t)) + t^2 \cos(u(t)) u'(t) \\ = 2t \sin(u(t)) + t^4 \cos(u(t)) \sin(u(t))$$

A Second-order method

$$u^{n+1} = u^n + \Delta t \, t_n^2 \sin(u^n) + \frac{\Delta t^2}{2} [2t_n \sin(u^n) + t_n^4 \cos(u^n) \sin(u^n)].$$

One-step v.s. Multistep Methods

* RK methods are one-step methods:

u^{n+1} depends on u^n but not on previous $u^{n-1}, u^{n-2}, \dots$

Advantages of one-step method:

- self-starting from u^0 the initial data;
- time step k can be changed at any point;
- solution $u(t)$ can be non-smooth at some point t^* .

Disadvantages:

- cumbersome and expensive to implement (especially high-order RK methods)
- function values expensive to compute
- difficulty in implicit (nonlinear) systems.

Linear Multistep Methods (LMMs)

In general, an r -step LMM has the form

$$\sum_{j=0}^r \alpha_j u^{n+j} = \Delta t \sum_{j=0}^r \beta_j f(u^{n+j}, t_{n+j})$$

- $\beta_r = 0$, explicit; $\beta_r \neq 0$, implicit.
- normalization $\alpha_r = 1$

Example. 1. Apply Simpson's rule

$$\begin{aligned} u(t_{n+1}) &= u(t_{n-1}) + \int_{t_{n-1}}^{t_{n+1}} f(u(t), t) dt \\ &\approx u(t_{n-1}) + \frac{1}{3} \Delta t \left[f(u(t_{n-1}), t_{n-1}) \right. \\ &\quad \left. + 4 f(u(t_n), t_n) + f(u(t_{n+1}), t_{n+1}) \right] \end{aligned}$$

$$u^{n+1} = u^{n-1} + \frac{\Delta t}{3} \left[f(u^{n-1}, t_{n-1}) + 4 f(u^n, t_n) + f(u^{n+1}, t_{n+1}) \right]$$

2. Adams Methods

$$u^{n+r} = u^{n+r-1} + \Delta t \sum_{j=0}^r \beta_j f(u^{n+j})$$

β_j coefficients are chosen to maximize the order of accuracy.

$$\begin{aligned}
 u(t_{n+r}) &= u(t_{n+r-1}) + \int_{t_{n+r-1}}^{t_{n+r}} u'(t) dt \\
 &= u(t_{n+r-1}) + \int_{t_{n+r-1}}^{t_{n+r}} f(u(t)) dt \\
 &\approx u(t_{n+r-1}) + \Delta t \sum_{j=1}^{r-1} \beta_j f(u(t_{n+j}))
 \end{aligned}$$

Explicit Adams-Bashforth

$$1\text{-step: } u^{n+1} = u^n + \Delta t f(u^n) \quad (FE)$$

$$2\text{-step: } u^{n+2} = u^{n+1} + \frac{\Delta t}{2} [-f(u^n) + 3f(u^{n+1})]$$

$$3\text{-step: } u^{n+3} = u^{n+2} + \frac{\Delta t}{12} [3f(u^n) - 8f(u^{n+1}) + 5f(u^{n+2})]$$

Implicit Adams-Moulton

$$1\text{-step: } u^{n+1} = u^n + \frac{\Delta t}{2} [f(u^n) + f(u^{n+1})] \quad (\text{trapezoidal rule})$$

$$2\text{-step: } u^{n+2} = u^{n+1} + \frac{\Delta t}{12} [-f(u^n) + 8f(u^{n+1}) + 5f(u^{n+2})]$$

$$\begin{aligned}
 3\text{-step: } u^{n+3} &= u^{n+2} + \frac{\Delta t}{24} [f(u^n) - 5f(u^{n+1}) + 19f(u^{n+2}) \\
 &\quad + 9f(u^{n+3})]
 \end{aligned}$$

3. Nyström methods

$$\begin{aligned}
 u^{n+r} &= u^{n+r-2} + \Delta t \sum_{j=0}^{r-1} \beta_j f(u^{n+j}) \\
 &\quad (r=2 \text{ Simpson's rule})
 \end{aligned}$$

Local truncation error (LTE)

$$\tau(t_{n+1}) = \frac{1}{\Delta t} \left(\sum_{j=0}^r \alpha_j u(t_{n+1}) - \Delta t \sum_{j=0}^r \beta_j u'(t_{n+j}) \right)$$

with $u(t_{n+j}) = u(t_n) + j\Delta t u'(t_n) + \frac{1}{2} j^2 \Delta t^2 u''(t_n) + \dots$

$$u'(t_{n+j}) = u'(t_n) + j\Delta t u''(t_n) + \frac{1}{2} j^2 \Delta t^2 u'''(t_n) + \dots$$

therefore,

$$\tau(t_{n+1}) = \frac{1}{\Delta t} \left(\sum_{j=0}^r \alpha_j \right) u(t_n) + \left(\sum_{j=0}^r (j\alpha_j - \beta_j) \right) u'(t_n) + O(\Delta t).$$

The method is consistent if $\tau \rightarrow 0$ as $\Delta t \rightarrow 0$,

which requires

$$\sum_{j=0}^r \alpha_j = 0, \quad \sum_{j=0}^r j\alpha_j = \sum_{j=0}^r \beta_j.$$

Characteristic Polynomials of LMM

$$\rho(x) = \sum_{j=0}^r \alpha_j x^j$$

$$\sigma(x) = \sum_{j=0}^r \beta_j x^j.$$

note that

$$p^{(r)} = \sum_{j=0}^r \alpha_j \quad p^{(r)}(x) = \sum_{j=0}^r j \alpha_j x^{j-1}$$

the consistent condition gives

$$p(1) = 0, \quad p'(1) = \sigma(1).$$

Example. 2-step Adams-Moulton

$$p(x) = x^2 - x$$

$$\sigma(x) = \frac{1}{12} (-1 + 8x + 5x^2)$$

Comments.

- Starting values

Using r -stage LMMs, $u^0, u^1, \dots, u^{r-1}$ are needed.

- Predictor-corrector methods

$$\hat{u}^{n+1} = u^n + \Delta t f(u^n)$$

$$u^{n+1} = u^n + \frac{\Delta t}{2} [f(u^n) + f(\hat{u}^{n+1})]$$

(ode113 in MATLAB uses this approach,

with Adams-Bashforth-Moulton of orders 1-12)