Efficient Algorithms for Computing Betti Numbers of Semi-algebraic Sets

Saugata Basu

School of Mathematics Georgia Tech

Nov 14, 2005/ Minicourse (Advanced)/ IHP

< □ > < 同 > < 回 > < 回 > < 回 >

Outline



Introduction

- Brief History
- 2 Ideas behind ETR and computing Euler-Poincaré Characteristic
 - Digression on Morse Theory
- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions
 - Deciding Connectivity
 - Definition of Roadmaps
 - Properties of pseudo-critical values
 - Roadmap Algorithm for a bounded algebraic set

< □ > < 同 > < 回 > < 回 > < 回 >

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Brief History

Statement of the problem

- Let R be a real closed field and S ⊂ R^k a semi-algebraic set defined by a quantifier-free Boolean formula with atoms of the form P > 0, P < 0, P = 0 for P ∈ P ⊂ R[X₁,..., X_k]. We call S a P-semi-algebraic set. If, instead, the Boolean formula has atoms of the form P = 0, P ≥ 0, P ≤ 0, P ∈ P, and additionally contains no negation, then we will call S a P-closed semi-algebraic set.
- The sum of the Betti numbers of S is bounded by O(sd)^k, where s = #(P) and d = max_{P∈P} deg(P).
- Even though the Betti numbers of *S* are bounded singly exponentially in *k*, there is no singly exponential algorithm for computing the Betti numbers of *S*.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Brief History

Statement of the problem

- Let R be a real closed field and S ⊂ R^k a semi-algebraic set defined by a quantifier-free Boolean formula with atoms of the form P > 0, P < 0, P = 0 for P ∈ P ⊂ R[X₁,..., X_k]. We call S a P-semi-algebraic set. If, instead, the Boolean formula has atoms of the form P = 0, P ≥ 0, P ≤ 0, P ∈ P, and additionally contains no negation, then we will call S a P-closed semi-algebraic set.
- The sum of the Betti numbers of S is bounded by O(sd)^k, where s = #(P) and d = max_{P∈P} deg(P).
- Even though the Betti numbers of *S* are bounded singly exponentially in *k*, there is no singly exponential algorithm for computing the Betti numbers of *S*.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Brief History

Statement of the problem

- Let R be a real closed field and S ⊂ R^k a semi-algebraic set defined by a quantifier-free Boolean formula with atoms of the form P > 0, P < 0, P = 0 for P ∈ P ⊂ R[X₁,..., X_k]. We call S a P-semi-algebraic set. If, instead, the Boolean formula has atoms of the form P = 0, P ≥ 0, P ≤ 0, P ∈ P, and additionally contains no negation, then we will call S a P-closed semi-algebraic set.
- The sum of the Betti numbers of S is bounded by O(sd)^k, where s = #(P) and d = max_{P∈P} deg(P).
- Even though the Betti numbers of *S* are bounded singly exponentially in *k*, there is no singly exponential algorithm for computing the Betti numbers of *S*.

・ロン・(部)・・ヨン・ヨン 三連

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Brief History

Outline



- Ideas behind ETR and computing Euler-Poincaré Characteristic
 Digression on Morse Theory
- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions
- 4 Deciding Connectivity
 - Definition of Roadmaps
 - Properties of pseudo-critical values
 - Roadmap Algorithm for a bounded algebraic set

< □ > < 同 > < 回 > < 回 > < 回 >

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Previous Work

Doubly exponential algorithms (with complexity (sd)^{2^{O(k)}}) for computing all the Betti numbers are known, since it is possible to obtain a triangulation of S in doubly exponential time using cylindrical algebraic decomposition (Collins,Schwartz-Sharir).

Brief History

 Algorithms with single exponential complexity are known only for the problems of testing emptiness, computing the zero-th Betti number (i.e. the number of semi-algebraically connected components of S) the Euler-Poincaré characteristic of S, as well as the dimension of S.

・ロッ ・ 一 ・ ・ ヨッ ・ ・ ・ ・ ・

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Brief History

Previous Work

- Doubly exponential algorithms (with complexity (sd)^{2^{O(k)}}) for computing all the Betti numbers are known, since it is possible to obtain a triangulation of S in doubly exponential time using cylindrical algebraic decomposition (Collins,Schwartz-Sharir).
- Algorithms with single exponential complexity are known only for the problems of testing emptiness, computing the zero-th Betti number (i.e. the number of semi-algebraically connected components of S) the Euler-Poincaré characteristic of S, as well as the dimension of S.

ヘロト 人間 ト イヨト イヨト

Digression on Morse Theory

The Critical Point Method

- Using infinitesimal perturbation to deform a given algebraic set to a basic, closed semi-algebraic set with smooth boundary, which has the same homotopy type.
- Compute the critical points (as well as the index of the Hessian at these points) efficiently, making use of the particular structure of the deformation.
- Use Morse theory to compute the Euler-Poincaré characteristic.

(日)

Digression on Morse Theory

The Critical Point Method

- Using infinitesimal perturbation to deform a given algebraic set to a basic, closed semi-algebraic set with smooth boundary, which has the same homotopy type.
- Compute the critical points (as well as the index of the Hessian at these points) efficiently, making use of the particular structure of the deformation.
- Use Morse theory to compute the Euler-Poincaré characteristic.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Digression on Morse Theory

The Critical Point Method

- Using infinitesimal perturbation to deform a given algebraic set to a basic, closed semi-algebraic set with smooth boundary, which has the same homotopy type.
- Compute the critical points (as well as the index of the Hessian at these points) efficiently, making use of the particular structure of the deformation.
- Use Morse theory to compute the Euler-Poincaré characteristic.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Ideas behind ETR and computing Euler-Poincaré Characteristic

Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity

Digression on Morse Theory

Outline



Ideas behind ETR and computing Euler-Poincaré Characteristic Digression on Morse Theory

- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions
- 4 Deciding Connectivity
 - Definition of Roadmaps
 - Properties of pseudo-critical values
 - Roadmap Algorithm for a bounded algebraic set

< ロ > < 同 > < 回 > < 回 > < □ > <

Digression on Morse Theory

Morse Lemma A

Lemma (Morse lemma A)

Let [a, b] be an interval containing no critical value of π . Then $Z(Q, \mathbb{R}^k)_{[a,b]}$ is homeomorphic to $Z(Q, \mathbb{R}^k)_a \times [a, b]$ and $Z(Q, \mathbb{R}^k)_{\leq a}$ is homotopy equivalent to $Z(Q, \mathbb{R}^k)_{\leq b}$.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Digression on Morse Theory

Morse Lemma B

Lemma (Morse lemma B)

Let $Z(Q, \mathbb{R}^k)$ be a non-singular bounded algebraic hypersurface such that the projection π to the X_1 -axis is a Morse function. Let p be a non-degenerate critical point of π of index λ and such that $\pi(p) = c$. Then, for all sufficiently small $\epsilon > 0$, the set $Z(Q, \mathbb{R}^k)_{\leq c+\epsilon}$ has the homotopy type of the union of $Z(Q, \mathbb{R}^k)_{\leq c-\epsilon}$ with a ball of dimension $k - 1 - \lambda$, attached along its boundary.

(日)

Ideas behind ETR and computing Euler-Poincaré Characteristic

Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity Digression on Morse Theory

Example of the torus

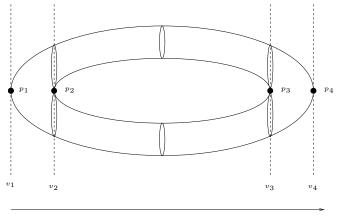




Figure: Critical values for the smooth torus in \mathbb{R}^3 ,

Saugata Basu Efficient Algorithms for Computing Betti Numbers

・ロット (雪) (日) (日) 日

Computing the Euler-Poincaré characteristic of a bounded algebraic set

• Let $Q \in D[X_1, \ldots, X_k]$, $Z(Q, \mathbb{R}^k) \subset B(0, 1/c)$ for some $0 < c \le 1, c \in \mathbb{D}$.

$$G_k(d,c) = c^d (X_1^d + \dots + X_k^d + X_2^2 + \dots + X_k^2) - (2k-1),$$

Def $(Q^2, d, c, \zeta) = \zeta G_k(d, c) + (1-\zeta)Q^2,$

$$\operatorname{Def}_{+}(Q^2, d, c, \zeta) = \operatorname{Def}(Q^2, d, c, \zeta) + X_{k+1}^2.$$

・ロット (雪) (日) (日) 日

Computing the Euler-Poincaré characteristic of a bounded algebraic set

• Let $Q \in D[X_1, \ldots, X_k]$, $Z(Q, \mathbb{R}^k) \subset B(0, 1/c)$ for some $0 < c \le 1, c \in \mathbb{D}$.

$$G_k(d,c) = c^d (X_1^d + \dots + X_k^d + X_2^2 + \dots + X_k^2) - (2k-1),$$

 $Def(Q^2, d, c, \zeta) = \zeta G_k(d, c) + (1-\zeta)Q^2,$

and

٠

$$\operatorname{Def}_{+}(Q^{2}, \boldsymbol{d}, \boldsymbol{c}, \zeta) = \operatorname{Def}(Q^{2}, \boldsymbol{d}, \boldsymbol{c}, \zeta) + X_{k+1}^{2}.$$

・ロット (雪) (日) (日) 日

Computing the Euler-Poincaré characteristic of a bounded algebraic set (cont.)

$$\operatorname{Cr}(Q^{2}, d, c, \zeta) = \left\{ \operatorname{Def}(Q^{2}, d, c, \zeta), \frac{\partial \operatorname{Def}(Q^{2}, d, c, \zeta)}{\partial X_{2}}, \dots, \frac{\partial \operatorname{Def}(Q^{2}, d, c, \zeta)}{\partial X_{k}} \right\}, \\ \operatorname{Cr}_{+}(Q^{2}, d, c, \zeta) = \left\{ \operatorname{Def}_{+}(Q^{2}, d, c, \zeta), \frac{\partial \operatorname{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{2}}, \dots, \frac{\partial \operatorname{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{k}}, 2X_{k+1} \right\}$$

 $Cr(Q^2, d, c, \zeta)$ as well as $Cr_+(Q^2, d, c, \zeta)$ are both (very nearly) Grobner bases.

Algorithm for a bounded algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF A BOUNDED ALGEBRAIC SET)

Input : $Q \in D[X_1, ..., X_k]$ with $Z(Q, \mathbb{R}^k) \subset B(0, 1/c)$. Output : $\chi(Z(Q, \mathbb{R}^k))$.

$$H_{1} = \left[\frac{\partial^{2} \text{Def}(Q^{2}, \zeta, d, c)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k}$$
$$H_{2} = \left[\frac{\partial^{2} \text{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k+1}$$

Algorithm for a bounded algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF A BOUNDED ALGEBRAIC SET)

Input: $Q \in D[X_1, ..., X_k]$ with $Z(Q, \mathbb{R}^k) \subset B(0, 1/c)$. Dutput: $\chi(Z(Q, \mathbb{R}^k))$.

$$H_{1} = \left[\frac{\partial^{2} \text{Def}(Q^{2}, \zeta, d, c)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k}$$
$$H_{2} = \left[\frac{\partial^{2} \text{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k+1}$$

Algorithm for a bounded algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF A BOUNDED ALGEBRAIC SET)

Input : $Q \in D[X_1, ..., X_k]$ with $Z(Q, R^k) \subset B(0, 1/c)$. Output : $\chi(Z(Q, R^k))$.

$$H_{1} = \left[\frac{\partial^{2} \text{Def}(Q^{2}, \zeta, d, c)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k}$$
$$H_{2} = \left[\frac{\partial^{2} \text{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k+1}$$

Algorithm for a bounded algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF A BOUNDED ALGEBRAIC SET)

Input : $Q \in D[X_1, ..., X_k]$ with $Z(Q, R^k) \subset B(0, 1/c)$. Output : $\chi(Z(Q, R^k))$.

$$H_{1} = \left[\frac{\partial^{2} \text{Def}(Q^{2}, \zeta, d, c)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k}$$
$$H_{2} = \left[\frac{\partial^{2} \text{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k+1}$$

Algorithm for a bounded algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF A BOUNDED ALGEBRAIC SET)

Input : $Q \in D[X_1, ..., X_k]$ with $Z(Q, R^k) \subset B(0, 1/c)$. Output : $\chi(Z(Q, R^k))$.

$$H_{1} = \left[\frac{\partial^{2} \text{Def}(Q^{2}, \zeta, d, c)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k}$$
$$H_{2} = \left[\frac{\partial^{2} \text{Def}_{+}(Q^{2}, d, c, \zeta)}{\partial X_{i} \partial X_{j}}\right]_{2 \le i, j \le k+1}$$

Algorithm for a bounded algebraic set

Compute the signature $\sigma(H_1)$ (respectively $\sigma(H_2)$), of the matrix H_1 (respectively H_2) at the real roots of $Cr(Q^2, d, c, \zeta)$ (respectively $Cr_+(Q^2, d, c, \zeta)$). For *i* from 0 to k - 1 let,

$$\ell_i := \#\{x \in \mathbb{Z}(\operatorname{Cr}(\mathbb{Q}^2, d, c, \zeta), \mathbb{C}\langle \zeta \rangle^k) \mid \frac{k - 1 + \sigma(H_1(x))}{2} = i\}.$$

For *i* from 0 to *k*, let

$$m_i := \#\{x \in \mathbb{Z}(\operatorname{Cr}_+(\mathbb{Q}^2, d, c, \zeta), \mathbb{C}\langle\zeta\rangle^{k+1}) \mid \frac{k + \sigma(H_2(x))}{2} = i\}.$$

Output

$$\chi(\mathbf{Z}(\mathbf{Q},\mathbf{R}^{k})) = \frac{1}{2} \left(\sum_{i=0}^{k-1} (-1)^{k-1-i} \ell_{i} + \sum_{i=0}^{k} (-1)^{k-i} m_{i} \right).$$

Applications: Euler-Poincaré Characteristics of Sign Conditions

・ロット (雪) (日) (日)

э

Algorithm for a general algebraic set

Algorithm (Euler-Poincaré Characteristic of an Algebraic Set)

Input : $Q \in D[X_1, ..., X_k]$. Output : $\chi(Z(Q, \mathbb{R}^k))$.

Procedure : Let

$$Q_1 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_k^2) - 1)^2.$$

$$Q_2 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_{k+1}^2) - 1)^2.$$

Applications: Euler-Poincaré Characteristics of Sign Conditions

・ロット (雪) () () () ()

3

Algorithm for a general algebraic set

Algorithm (Euler-Poincaré Characteristic of an Algebraic Set)

Input : $Q \in D[X_1, ..., X_k]$.

Output : $\chi(Z(Q, \mathbb{R}^k))$.

Procedure : Let

$$Q_1 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_k^2) - 1)^2.$$

$$Q_2 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_{k+1}^2) - 1)^2.$$

Applications: Euler-Poincaré Characteristics of Sign Conditions

・ロット (雪) () () () ()

3

Algorithm for a general algebraic set

Algorithm (Euler-Poincaré Characteristic of an Algebraic Set)

Input : $Q \in D[X_1, ..., X_k]$. Output : $\chi(Z(Q, \mathbb{R}^k))$.

Procedure : Let

$$Q_1 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_k^2) - 1)^2.$$

$$Q_2 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_{k+1}^2) - 1)^2.$$

Applications: Euler-Poincaré Characteristics of Sign Conditions

・ロット (雪) () () () ()

3

Algorithm for a general algebraic set

Algorithm (Euler-Poincaré Characteristic of an Algebraic Set)

Input : $Q \in D[X_1, ..., X_k]$. Output : $\chi(Z(Q, \mathbb{R}^k))$.

Procedure : Let

$$Q_1 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_k^2) - 1)^2.$$

$$Q_2 = Q^2 + (\varepsilon^2 (X_1^2 + \ldots + X_{k+1}^2) - 1)^2.$$

Applications: Euler-Poincaré Characteristics of Sign Conditions

・ロト・西ト・ モト・ モー

Algorithm for a general algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF AN ALGEBRAIC SET)

Using previous Algorithm (Euler-Poincaré Characteristic of a Bounded Algebraic Set) compute $\chi(Z(Q_1, R\langle \varepsilon \rangle^k))$ and $\chi(Z(Q_2, R\langle \varepsilon \rangle^{k+1}))$ Output,

 $\chi(\mathbf{Z}(\mathbf{Q},\mathbf{R}^k)) = \frac{1}{2}(\chi(\mathbf{Z}(\mathbf{Q}_2,\mathbf{R}\langle\varepsilon\rangle^{k+1})) - \chi(\mathbf{Z}(\mathbf{Q}_1,\mathbf{R}\langle\varepsilon\rangle^k))).$

Applications: Euler-Poincaré Characteristics of Sign Conditions

ヘロト 人間 ト イヨト イヨト

Algorithm for a general algebraic set

ALGORITHM (EULER-POINCARÉ CHARACTERISTIC OF AN ALGEBRAIC SET)

Using previous Algorithm (Euler-Poincaré Characteristic of a Bounded Algebraic Set) compute $\chi(Z(Q_1, R\langle \varepsilon \rangle^k))$ and $\chi(Z(Q_2, R\langle \varepsilon \rangle^{k+1}))$.

 $\chi(\mathbf{Z}(\mathbf{Q},\mathbf{R}^{k})) = \frac{1}{2}(\chi(\mathbf{Z}(\mathbf{Q}_{2},\mathbf{R}\langle\varepsilon\rangle^{k+1})) - \chi(\mathbf{Z}(\mathbf{Q}_{1},\mathbf{R}\langle\varepsilon\rangle^{k}))).$

・ロッ ・ 一 ・ ・ ヨッ ・ ・ ・ ・ ・

Algorithm for a general algebraic set

Algorithm (Euler-Poincaré Characteristic of an Algebraic Set)

Using previous Algorithm (Euler-Poincaré Characteristic of a Bounded Algebraic Set) compute $\chi(Z(Q_1, R\langle \varepsilon \rangle^k))$ and $\chi(Z(Q_2, R\langle \varepsilon \rangle^{k+1}))$. Output,

 $\chi(\mathbf{Z}(\mathbf{Q},\mathbf{R}^{k})) = \frac{1}{2}(\chi(\mathbf{Z}(\mathbf{Q}_{2},\mathbf{R}\langle\varepsilon\rangle^{k+1})) - \chi(\mathbf{Z}(\mathbf{Q}_{1},\mathbf{R}\langle\varepsilon\rangle^{k}))).$

Applications: Euler-Poincaré Characteristics of Sign Conditions

< ロ > < 同 > < 回 > < 回 > < □ > <

Outline



Ideas behind ETR and computing Euler-Poincaré Characteristic
 Digression on Morse Theory

3 Algorithm for Computing the Euler-Poincaré characteristic

- Applications: Euler-Poincaré Characteristics of Sign Conditions
- Deciding Connectivity
 - Definition of Roadmaps
 - Properties of pseudo-critical values
 - Roadmap Algorithm for a bounded algebraic set

Applications: Euler-Poincaré Characteristics of Sign Conditions

(日) (圖) (E) (E) (E)

Euler-Poincaré Queries

Given *S* a locally closed semi-algebraic set contained in *Z*, we denote by $\chi(S)$ the Euler-Poincaré characteristic of *S*. Given $P \in \mathbb{R}[X_1, \ldots, X_k]$, we denote

$$\begin{aligned} \mathcal{R}(P = 0, S) &= \{ x \in S \ | \ P(x) = 0 \}, \\ \mathcal{R}(P > 0, S) &= \{ x \in S \ | \ P(x) > 0 \}, \\ \mathcal{R}(P > 0, S) &= \{ x \in S \ | \ P(x) < 0 \}, \end{aligned}$$

and $\chi(P = 0, S), \chi(P > 0, S), \chi(P < 0, S)$ the Euler-Poincaré characteristics of the corresponding sets The Euler-Poincaré-query of *P* for *S* is

$$\mathrm{EQ}(\boldsymbol{P},\boldsymbol{S}) = \chi(\boldsymbol{P} > \boldsymbol{0},\boldsymbol{S}) - \chi(\boldsymbol{P} < \boldsymbol{0},\boldsymbol{S}).$$

(日)

Euler-Poincaré of sign conditions

Let $\mathcal{P} = P_1, \ldots, P_s$ be a finite list of polynomials in $\mathbb{R}[X_1, \ldots, X_k]$. Let $Q \in \mathbb{R}[X_1, \ldots, X_k]$, $Z = Z(Q, \mathbb{R}^k)$. We denote as usual by $\operatorname{Sign}(\mathcal{P}, Z)$ the list of $\sigma \in \{0, 1, -1\}^{\mathcal{P}}$ such that $\mathcal{R}(\sigma, Z)$ is non-empty. We denote by $\chi(\mathcal{P}, Z)$ the list of Euler-Poincaré characteristics $\chi(\sigma, Z) = \chi(\mathcal{R}(\sigma, Z))$ for $\sigma \in \operatorname{Sign}(\mathcal{P}, Z)$.

Algorithm for Computing Euler-Poincaré of sign conditions

 Same as that of B-K-R sign determination algorithm, except we we compute Euler-Poincaré characteristics of realizations of sign conditions rather than cardinalities of sign conditions on a finite set, using the notion of Euler-Poincaré-query rather than that of Sturm-query.

• Complexity:

 $s^{k'+1}O(d)^k + s^{k'}((k'\log_2(s) + k\log_2(d))d)^{O(k)}.$

・ロット (雪) (日) (日) 日

Algorithm for Computing Euler-Poincaré of sign conditions

 Same as that of B-K-R sign determination algorithm, except we we compute Euler-Poincaré characteristics of realizations of sign conditions rather than cardinalities of sign conditions on a finite set, using the notion of Euler-Poincaré-query rather than that of Sturm-query.

• Complexity:

 $s^{k'+1}O(d)^k + s^{k'}((k'\log_2(s) + k\log_2(d))d)^{O(k)}.$

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Outline



- Brief History
- Ideas behind ETR and computing Euler-Poincaré Characteristic
 Digression on Morse Theory
- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions

Deciding Connectivity

- Definition of Roadmaps
- Properties of pseudo-critical values
- Roadmap Algorithm for a bounded algebraic set

< □ > < 同 > < 回 > < 回 > < 回 >

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

What is a roadmap?

Let *S* be a semi-algebraic set. We denote by π the projection on the *X*₁-axis and set

$$\mathbf{S}_{\mathbf{x}} = \{\mathbf{y} \in \mathbf{R}^{k-1} \mid (\mathbf{x}, \mathbf{y}) \in \mathbf{S}\}.$$

A **roadmap** for *S* is a semi-algebraic set *M* of dimension at most one contained in *S* which satisfies the following roadmap conditions:

 RM_1 For every semi-algebraically connected component *D* of *S*, $D \cap M$ is semi-algebraically connected.

RM₂ For every $x \in \mathbb{R}$ and for every semi-algebraically connected component D' of S_x , $D' \cap M \neq \emptyset$.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

What is a roadmap?

Let *S* be a semi-algebraic set. We denote by π the projection on the *X*₁-axis and set

$$\mathbf{S}_{\mathbf{x}} = \{\mathbf{y} \in \mathbf{R}^{k-1} \mid (\mathbf{x}, \mathbf{y}) \in \mathbf{S}\}.$$

A **roadmap** for *S* is a semi-algebraic set *M* of dimension at most one contained in *S* which satisfies the following roadmap conditions:

 RM_1 For every semi-algebraically connected component *D* of *S*, $D \cap M$ is semi-algebraically connected.

RM₂ For every $x \in \mathbb{R}$ and for every semi-algebraically connected component D' of S_x , $D' \cap M \neq \emptyset$.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Outline



- Ideas behind ETR and computing Euler-Poincaré Charact
 Digression on Morse Theory
- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions

Deciding Connectivity

- Definition of Roadmaps
- Properties of pseudo-critical values
- Roadmap Algorithm for a bounded algebraic set

< □ > < 同 > < 回 > < 回 > < 回 >

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Pseudo-critical values

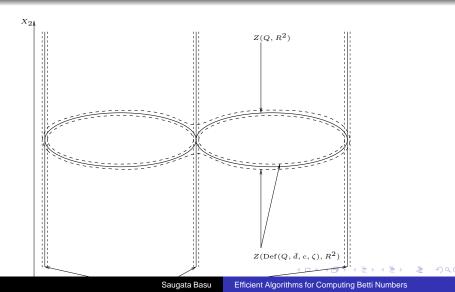
Definition

An X_1 -pseudo-critical point on $Z(Q, R^k)$ is the \lim_{ζ} of an X_1 -critical point on $Z(\text{Def}(Q, \overline{d}, c, \zeta), R\langle \zeta \rangle^k)$. An X_1 -pseudo-critical value on $Z(Q, R^k)$ is the projection to the X_1 -axis of an X_1 -pseudo-critical point on $Z(Q, R^k)$.

Introduction

Ideas behind ETR and computing Euler-Poincaré Characteristic Algorithm for Computing the Euler-Poincaré characteristic Deciding Connectivity Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Pseudo-critical values



Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Proposition

Let $Z(Q, R^k)$ be a bounded algebraic set and S a semi-algebraically connected component of $Z(Q, R^k)_{[a,b]}$. If $v \in (a, b)$ and $[a, b] \setminus \{v\}$ contains no X_1 -pseudo-critical value on $Z(Q, R^k)$, then S_v is semi-algebraically connected.

・ロト ・雪 ・ ・ ヨ ・ ・ ヨ

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Proposition

Let $Z(Q, R^k)$ be a bounded algebraic set and let S be a semi-algebraically connected component of $Z(Q, R^k)_{[a,b]}$. If $S_{[a,b]}$ is not semi-algebraically connected, then b is an X_1 -pseudo-critical value of $Z(Q, R^k)$.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Outline



- Brief History
- Ideas behind ETR and computing Euler-Poincaré Characteristic
 Digression on Morse Theory
- 3 Algorithm for Computing the Euler-Poincaré characteristic
 - Applications: Euler-Poincaré Characteristics of Sign Conditions

Deciding Connectivity

- Definition of Roadmaps
- Properties of pseudo-critical values
- Roadmap Algorithm for a bounded algebraic set

< □ > < 同 > < 回 > < 回 > < 回 >

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Roadmap of a bounded $Z(Q, \mathbb{R}^k)$ containing finite $\mathcal{N} \subset Z(Q, \mathbb{R}^k)$.

- We first construct X₂-pseudo-critical points on Z(Q, R^k) in a parametric way along the X₁-axis. This results in curve segments and their endpoints on Z(Q, R^k).
- Since these curves and their endpoints include, for every x ∈ R, the X₂-pseudo-critical points of Z(Q, R^k)_x, they meet every connected component of Z(Q, R^k)_x. Thus the set of curve segments and their endpoints already satisfy RM₂.
- We add additional curve segments to ensure that M is connected by recursing in certain distinguished hyperplanes defined by X₁ = z for distinguished values z.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Roadmap of a bounded $Z(Q, \mathbb{R}^k)$ containing finite $\mathcal{N} \subset Z(Q, \mathbb{R}^k)$.

- We first construct X₂-pseudo-critical points on Z(Q, R^k) in a parametric way along the X₁-axis. This results in curve segments and their endpoints on Z(Q, R^k).
- Since these curves and their endpoints include, for every x ∈ R, the X₂−pseudo-critical points of Z(Q, R^k)_x, they meet every connected component of Z(Q, R^k)_x. Thus the set of curve segments and their endpoints already satisfy RM₂.
- We add additional curve segments to ensure that M is connected by recursing in certain distinguished hyperplanes defined by X₁ = z for distinguished values z.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Roadmap of a bounded $Z(Q, \mathbb{R}^k)$ containing finite $\mathcal{N} \subset Z(Q, \mathbb{R}^k)$.

- We first construct X₂-pseudo-critical points on Z(Q, R^k) in a parametric way along the X₁-axis. This results in curve segments and their endpoints on Z(Q, R^k).
- Since these curves and their endpoints include, for every x ∈ R, the X₂−pseudo-critical points of Z(Q, R^k)_x, they meet every connected component of Z(Q, R^k)_x. Thus the set of curve segments and their endpoints already satisfy RM₂.
- We add additional curve segments to ensure that M is connected by recursing in certain distinguished hyperplanes defined by X₁ = z for distinguished values z.

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Roadmap of a bounded $Z(Q, R^k)$

- The set of **distinguished values** is the union of the X_1 -pseudo-critical values, the first coordinates of the input points \mathcal{N} and the first coordinates of the endpoints of the curve segments. The input points, the endpoints of the curve segments and the intersections of the curve segments with the distinguished hyperplanes define the set of **distinguished points**.
- We then repeat this construction in each each distinguished hyperplane *H_i* defined by *X*₁ = *v_i* with input *Q*(*v_i, X₂,...,X_k*) and the distinguished points in *N_i*. The process is iterated until for

 $I = (i_1, \ldots, i_{k-2}), 1 \le i_1 \le \ell, \ldots, 1 \le i_{k-2} \le \ell(i_1, \ldots, i_{k-3}),$

we have distinguished values

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Roadmap of a bounded $Z(Q, R^k)$

- The set of **distinguished values** is the union of the X_1 -pseudo-critical values, the first coordinates of the input points \mathcal{N} and the first coordinates of the endpoints of the curve segments. The input points, the endpoints of the curve segments and the intersections of the curve segments with the distinguished hyperplanes define the set of **distinguished points**.
- We then repeat this construction in each each distinguished hyperplane H_i defined by X₁ = v_i with input Q(v_i, X₂,..., X_k) and the distinguished points in N_i. The process is iterated until for

$$I = (i_1, \ldots, i_{k-2}), 1 \le i_1 \le \ell, \ldots, 1 \le i_{k-2} \le \ell(i_1, \ldots, i_{k-3}),$$

we have distinguished values

< ロ > < 同 > < 回 > < 回 > .

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Complexity Analysis and open problem

 $T(d, k) = d^{O(k)} + d^{O(k)}T(d, k-1)$ = $d^{O(k^2)}$.

- Question: Can this be improved to $d^{O(k)}$?
- Remark: Using Crofton's formula from integral geometry this also shows that any two points in a connected component of a real algebraic variety of defined by polynomials of degree *d* contained in the unit ball can be connected by a semi-algebraic path of length *d*^{O(k²)}. Can this be improved to *d*^{O(k)} also ?

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Complexity Analysis and open problem

$$T(d, k) = d^{O(k)} + d^{O(k)}T(d, k-1)$$

= $d^{O(k^2)}$.

Question: Can this be improved to d^{O(k)}?

Remark: Using Crofton's formula from integral geometry this also shows that any two points in a connected component of a real algebraic variety of defined by polynomials of degree *d* contained in the unit ball can be connected by a semi-algebraic path of length *d*^{O(k²)}. Can this be improved to *d*^{O(k)} also ?

Definition of Roadmaps Properties of pseudo-critical values Roadmap Algorithm for a bounded algebraic set

Complexity Analysis and open problem

$$T(d, k) = d^{O(k)} + d^{O(k)}T(d, k-1)$$

= $d^{O(k^2)}$.

- Question: Can this be improved to d^{O(k)}?
- Remark: Using Crofton's formula from integral geometry this also shows that any two points in a connected component of a real algebraic variety of defined by polynomials of degree *d* contained in the unit ball can be connected by a semi-algebraic path of length d^{O(k²)}. Can this be improved to d^{O(k)} also ?