

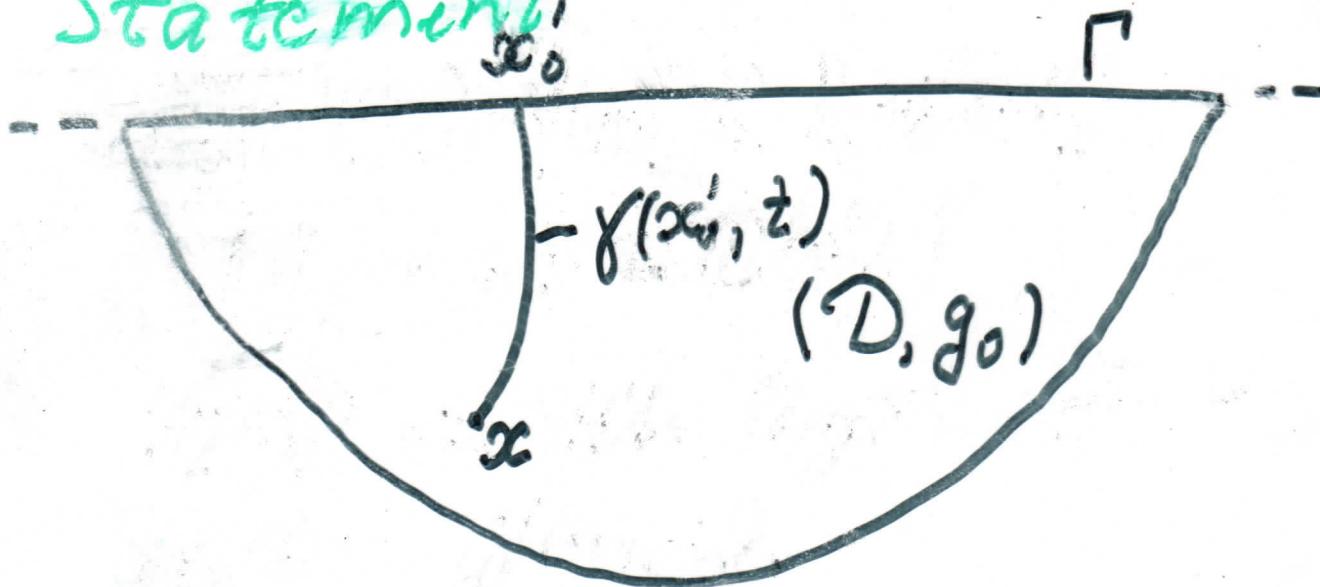
①

On determining a conformal-euclidean metric by its copy
 (Inverse kinematic problem with internal sources)

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Statement:



$$g_{ij}^0(x) = \delta_{ij} / c^2(x)$$

Inverse data: $\tau(x, x')$, $x \in D$
 $x' \in U(x_0) \cap \Gamma$, $c \mid \Gamma$

$$(c, D) = ?$$

(2)

semigeodesic coordinates of the curve:

$$x'(x), t(x) = \gamma(x'; x)$$

$x'(x)$ - geodesic projection

$\gamma(x'_0, t)$ geodesic, starting from
(c) $x'_0 \in \Gamma$ orthogonally to Γ

Assumption: $\gamma: \tilde{\mathcal{D}} \rightarrow \mathcal{D}$,

$$\gamma(x'_0, t) = x$$

is diffeomorphism

$$\begin{aligned} \tilde{\mathcal{D}} = \gamma^{-1}(\mathcal{D}) &= \{(\tilde{x}'_0, \tilde{t}) \mid x'_0 \in \Gamma, \\ &0 \leq \tilde{t} \leq T(x'_0)\} \end{aligned}$$

$T(x'_0)$ is the length of
geodesic $\gamma(x'_0, t)$.

$\tilde{\mathcal{D}}$ is known

$$\gamma(\Gamma) = \Gamma$$

(3)

Metric g

The map γ keeps the distance

$$\tilde{\tau}(x, x') = \tilde{\tau}_g(y, x')$$

where $y = (x', t)$

$$g = \gamma^* g_0$$

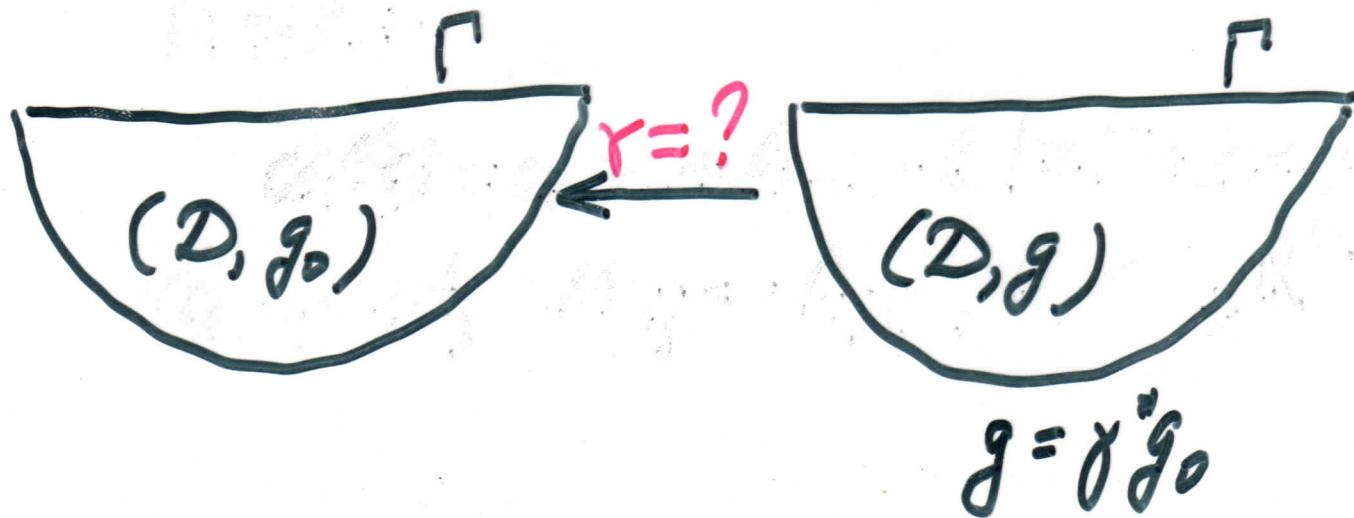
Eikonal equation

$$|\nabla \tilde{\tau}_g|^2 = g^{ij}(y) \frac{\partial \tilde{\tau}_g}{\partial y^i} \frac{\partial \tilde{\tau}_g}{\partial y^j} = 1$$

$\Rightarrow g$ (copy of g_0)

(4)

Pullback problem



Yamabe problem:

$$\alpha \Delta_g u + R_g u = 0$$

Conformal Killing's vector field

(CKVF):

$$Ku := \sigma \nabla u - \frac{g}{n} \delta u = 0$$

$$\frac{1}{2} (\nabla_i u_j + \nabla_j u_i) - \frac{\delta^{ij}}{n} \delta u = 0$$

(5)

$$n=2: \quad \nabla u^1 = \nabla_1 u^2$$

$$n > 2:$$

$$u(x) = a_0 x + Ax - B|x|^2 + 2x(B, x) + C$$

$$a_0 = \text{const}, \quad A_{ij} = -A_{ji}, \quad B, C \in \mathbb{R}^n$$

Solving

1). Take standardt basic vector fields

$$e_{(k)}, e_{(k)}^i = \delta_k^i, \quad i, k = 1, n$$

$$K^0 e_{(k)} = G \nabla^0 e_{(k)} - \frac{2}{n} \delta^0 \delta^0 e_{(k)} = 0$$

$e_{(k)}$ are CKVF

(6)

2). $u_{(k)} = \gamma^* e_{(k)}$
 CKVF on $\gamma^{-1}(\mathcal{D})$

$$\sigma \nabla u_{(k)} - \frac{\partial}{\partial t} \sigma u_{(k)} = 0 \quad (1)$$

$$k=1, \dots, n \quad g = \gamma^* g_0$$

$$\begin{cases} u_{(k)}^i(x', 0) = \delta_k^i, & k=1, \dots, n-1 \\ u_{(n)}^i(x', 0) = \gamma_1^i(x', 0) = e(x')(0, \dots, 1) \end{cases} \quad (2)$$

$$(1), (2) \Rightarrow u_{(k)}$$

If $n > 2$ dimension of CKVF is
 finite! $\Rightarrow (1), (2)$ is stable

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3) $u_{(k)}, e_{(0)}$ are known

The equality

$$u_{(k)} = \gamma^* e_{(k)}$$

determines Jacobi's matrix of γ . In particular we get

$$\frac{d\gamma^i}{dt}(x'_0, t) = u_n^i(x'_0, t)$$

\Rightarrow

$$\gamma(x'_0, t) = x'_0 + \int_0^t u_n(s) ds$$

$$c(\gamma(x'_0, t)) = |\gamma(x'_0, t)|$$

The problem is solved $\mathcal{D} = \gamma(\tilde{\mathcal{D}})$

