

# Linearized internal functionals for anisotropic conductivities

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June 20th, 2012

UC Irvine Conference in honor of Gunther Uhlmann

## 1. Background

$$-\nabla \cdot (\gamma \nabla u) \equiv -\sum_{i,j=1}^n \partial_i (\gamma^{ij} \partial_j u) = 0 \quad (\Omega) \quad u|_{\partial\Omega} = g$$

$\gamma$  is a real-valued symmetric positive definite tensor with bounded coefficients, satisfying a uniform ellipticity condition for some  $\kappa \geq 1$

$$\kappa^{-1} |\xi|^2 \leq \xi \cdot \gamma(x) \xi \leq \kappa |\xi|^2 \quad \xi \in \mathbb{R}^n \quad x \in \Omega$$

- *Conductivity* equation: rules the equilibrium distribution of the electrostatic potential  $u$  inside the domain  $\Omega$  in response to a prescribed boundary voltage  $g$ . Electrical Impedance Tomography (EIT).

$$\gamma \nabla u \cdot \nu|_{\partial\Omega} \rightarrow \text{Calderon's problem}$$

- Internal measurement

$$\text{power density of a solution } u \quad H_\gamma[g](x) := \nabla u(x) \cdot \gamma(x) \nabla u(x)$$

Application: Hybrid imaging

How to construct power densities: [Ammari et al. \(2008\)](#),  
[Kuchment-Kunyansky \(2010\)](#)

$$-\nabla \cdot (\gamma \nabla u) = 0 \quad (\Omega) \quad u|_{\partial\Omega} = g \quad H_\gamma[g](x) := \nabla u(x) \cdot \gamma(x) \nabla u(x)$$

History (non-linear case):

- Isotropic case  $\gamma = \sigma I_n$  from only one measurement  $H = \sigma |\nabla u|^2$

$$\nabla \cdot \left( \frac{H}{|\nabla u|^2} \nabla u \right) = 0 \quad (\Omega) \quad u|_{\partial\Omega} = g$$

- Newton-based method see ([Gebauer and Scherzer \(2009\)](#))
- Theoretically, by [Bal \(2012\)](#).

The conductivity equation

$$\nabla \cdot (\underbrace{\gamma'}_{\text{unknown}} \nabla u) = 0 \quad (\Omega), \quad u|_{\partial\Omega} = \underbrace{g}_{\text{known}} \quad (1)$$

Fixing a few boundary conditions  $g_1, \dots, g_m$  with  $u_i$  solving (1) with  $g \equiv g_i$

Measurement operator :  $H: \gamma' \rightarrow H(\gamma') = H_{ij}(\gamma') = \gamma' \nabla u_i \cdot \nabla u_j \quad 1 \leq i, j \leq m$

**Problem:** recover  $\gamma'$  from  $H$

- Isotropic, 2 dimensional setting, [see \(Capdeboscq et al. \(2009\)\)](#)
- Explicit reconstruction using a large number of functionals in an isotropic case in dimension 3. [see \(Bal, Monard, Bonnetier and Triki\)](#)
- Generalized to dimension n, isotropic tensor with more general type of measurements  $\sigma^{2\alpha} |\nabla u|^2$

where  $\alpha$  not necessary  $\frac{1}{2}$

[see Monard and Bal \(2012\).](#)

- reconstruction formulas for the anisotropic two-dimensional problem [see Monard and Bal \(2012\).](#)

## Linearization of the problem

The partial differential equation

$$\nabla \cdot (\underbrace{\gamma'}_{\text{unknown}} \nabla u) = 0 \quad (\Omega), \quad u|_{\partial\Omega} = \underbrace{g}_{\text{known}} \quad (1)$$

Fix a few boundary conditions  $g_1, \dots, g_m$  with  $u_i'$  solving (1) with  $g \equiv g_i$

Measurement operator :  $H: \gamma' \rightarrow H(\gamma') = H_{ij}(\gamma') = \gamma' \nabla u_i' \cdot \nabla u_j' \quad 1 \leq i, j \leq m$

**Non-linear problem:** recover  $\gamma'$  from  $H$

Fréchet derivative:

$$\gamma' = \underbrace{\gamma_0}_{\text{known}} + \varepsilon \gamma + o(\varepsilon^2)$$

$$u_i' = u_i + \varepsilon v_i + o(\varepsilon^2)$$

PDE (1) of order  $\mathcal{O}(1)$  and  $\mathcal{O}(\varepsilon)$

$$-\nabla \cdot (\gamma_0 \nabla \underbrace{u_i}_{\text{known}}) = 0 \quad (\Omega), \quad u_i|_{\partial\Omega} = \underbrace{g_i}_{\text{known}}$$

$$-\nabla \cdot (\gamma_0 \nabla \underbrace{v_i}_{\text{unknown}}) = \nabla \cdot (\gamma \nabla u_i) \quad (\Omega), \quad v_i|_{\partial\Omega} = 0$$

The measurements look like  $H_{ij} = \gamma_0 \nabla u_i \cdot \nabla u_j + \varepsilon (\gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i) + o(\varepsilon^2)$

Linearized measurements

$$\downarrow$$

$$\underbrace{dH_{ij}}_{\text{known}} = \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i$$

Linearized problem: recover  $\gamma$  from  $dH_{ij}$

### References on the linearized problem

- isotropic case in dimension 2 and 3 with numerical implementation  
see (Kuchment and Kunyansky (2011))
- isotropic case, studied using pseudo-differential calculus, inversion modulo a compact operator. see (Kuchment and Steinhauer (2011))

## 2. Microlocal inversion

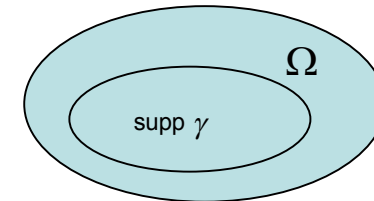
Study of the principal symbol  $M_{ij}(x, \xi)$  of  $dH_{ij}$

Recall the equations and measurements:

$$\begin{aligned} -\nabla \cdot (\gamma_0 \nabla \underbrace{u_i}_{\text{known}}) &= 0 \quad (\Omega), \quad u_i|_{\partial\Omega} = \underbrace{g_i}_{\text{known}} \\ -\nabla \cdot (\gamma_0 \nabla \underbrace{v_i}_{\text{unknown}}) &= \nabla \cdot (\gamma \nabla u_i) \quad (\Omega), \quad v_i|_{\partial\Omega} = 0 \\ \underbrace{dH_{ij}}_{\text{known}} &= \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i \end{aligned}$$

Denote  $L_0 := -\nabla \cdot (\gamma_0 \nabla)$   $v_i = L_0^{-1}(\nabla \cdot (\gamma \nabla u_i))$

suppose  $\gamma$  compactly supported inside  $\Omega$



Insert  $v_i = L_0^{-1}(\nabla \cdot (\gamma \nabla u_i))$  into  $dH_{ij}$  and express as a pseudo-DO

$$dH_{ij}(\gamma, x) = (2\pi)^{-n} \iint_{R^n \times R^n} e^{i\xi \cdot (x-y)} (M_{ij}(x, \xi) + M_{ij|_{-1}}(x, \xi)) : \gamma(y) d\xi dy$$

$$M_{ij}(x, \xi) = o(|\xi|^0) \quad M_{ij|_{-1}}(x, \xi) = o(|\xi|^{-1})$$

↓  
principal symbol

↓  
the symbol of order -1

$$dH_{ij}(\gamma, x) = (2\pi)^{-n} \iint_{R^n \times R^n} e^{i\xi \cdot (x-y)} (M_{ij}(x, \xi) + M_{ij}|_{-1}(x, \xi)) : \gamma(y) d\xi dy$$

$$M_{ij}(x, \xi) = o(|\xi|^0)$$



principal symbol

$$M_{ij}|_{-1}(x, \xi) = o(|\xi|^{-1})$$



the symbol of order -1

Goal: determine under which conditions the operator  $dH = \{dH_{ij}\}_{1 \leq i, j \leq m}$  is an elliptic pseudo-differential operator

Conclusion: with only principal symbols  $M_{ij}(x, \xi)$ ,  $dH = \{dH_{ij}\}_{1 \leq i, j \leq m}$  will never be elliptic, no matter how large  $m$

Define  $A_0 = (\gamma_0)^{\frac{1}{2}}$ ,  $\xi_0 := \hat{A}_0 \xi$  and  $V_i := A_0 \nabla u_i$  rewrite the principal symbol  $M_{ij}(x, \xi)$

$$\begin{aligned} \tilde{M}_{ij}(x, \xi) &= A_0 M_{ij}(x, \xi) A_0 \\ &= V_i \odot V_j - (\xi_0 \cdot V_i) \xi_0 \odot V_j - (\xi_0 \cdot V_j) \xi_0 \odot V_i \end{aligned}$$

Notation:  $U \odot V = \frac{1}{2}(U \otimes V + V \otimes U)$



Lemma:

For any  $i, j$  and vector fields  $V_i, V_j$  defined as above  $V_i := A_0 \nabla u_i$  the symbol  $\tilde{M}_{ij}(x, \xi)$  satisfies

$$\tilde{M}_{ij}(x, \xi) : \xi_0 \odot \eta = 0 \quad \text{for all } \eta \in S^{n-1} \quad \text{and} \quad \eta \perp \xi_0$$

**Conclusion:** the  $M_{ij}$  can never control a subspace of  $S_n(R)$  of dimension  $n-1$

**Basic Hypothesis:** the gradients  $\{\nabla u_i\}_{i=1}^n$  form a frame in  $R^n$

Lemma:

Suppose that the vector fields  $\{V_i\}_{i=1}^n$  form a basis of  $R^n$  If a matrix  $P \in S_n(R)$

$$\tilde{M}_{ij}(x, \xi) : P = 0 \quad 1 \leq i \leq j \leq n$$

Then  $P$  is of the form  $P = \xi_0 \odot \eta$  for some vector  $\eta$  satisfying  $\eta \perp \xi_0$

**Conclusion:** the **only** directions that are not controlled  
by the principal symbols are

$$P = \xi_0 \odot \eta \quad \eta \perp \xi_0$$

The second term of  $dH_{ij}$

$$dH_{ij}(\gamma, x) = (2\pi)^{-n} \iint_{R^n \times R^n} e^{i\xi \cdot (x-y)} (M_{ij}(x, \xi) + M_{ij}|_{-1}(x, \xi)) : \gamma(y) d\xi dy$$

**Goal:** invert  $dH = \{dH_{ij}\}_{1 \leq i, j \leq m}$  microlocally from  $M_{ij}(x, \xi) + M_{ij}|_{-1}(x, \xi)$

• **case**  $\gamma_0$  is constant  $\tilde{M}_{ij}|_{-1}(x, \xi) = A_0 M_{ij}|_{-1}(x, \xi) A_0$

$$= \|A_0 \xi\|^{-1} \sqrt{-1} [H_i((\xi_0 \cdot V_j)(I_n - 2\xi_0 \otimes \xi_0) + V_j \otimes \xi_0) + H_j((\xi_0 \cdot V_i)(I_n - 2\xi_0 \otimes \xi_0) + V_i \otimes \xi_0)]^{sym}$$

where  $H_i = A_0 \nabla^2 u_i A_0$

### Lemma

Suppose  $\gamma_0$  is constant, pick  $u_i = x_i$   $1 \leq i \leq n$  and add an additional solution denoted by  $u_{n+1}$  with full-rank Hessian  $\nabla^2 u_{n+1}$ . If there exist  $P, Q \in S_n(R)$  such that for all  $1 \leq i, j \leq n$

$$(\tilde{M}_{ij} + \tilde{M}_{ij}|_{-1})(x, \xi) : (P + \sqrt{-1}Q) = 0$$

$$(\tilde{M}_{i,n+1} + \tilde{M}_{i,n+1}|_{-1})(x, \xi) : (P + \sqrt{-1}Q) = 0$$

then  $P=Q=0$

- case  $\gamma_0$  is not constant

### Basic Hypotheses

- $(\nabla u_1, \dots, \nabla u_n)$  form a frame  $-\nabla \cdot (\gamma_0 \nabla \underbrace{u_i}_{known}) = 0$   $u_i|_{\partial\Omega} = \underbrace{g_i}_{known}$
- Add one addition  $u_{n+1}$  such that  $\sum_j^n \mu_j \nabla u_j + \nabla u_{n+1} = 0$

we construct the matrix  $Z = [\nabla \mu_1, \dots, \nabla \mu_n]$  assume  $Z$  to be **invertible**

**Remark:** in the case  $\gamma_0$  constant, the above hypothesis is automatically satisfied, by choosing

$$u_i = x_i \quad 1 \leq i \leq n$$

$$u_{n+1} = \frac{1}{2} x^t Q x \quad Q \text{ invertible} \quad \text{tr}(Q) = 0$$

Recall  $dH_{ij}(\gamma, x) = (2\pi)^{-n} \iint_{R^n \times R^n} e^{i\xi \cdot (x-y)} (M_{ij}(x, \xi) + M_{ij}|_{-1}(x, \xi)) : \gamma(y) d\xi dy$

**Goal:** under the above hypotheses,  $\tilde{M}_{ij}|_{-1}$  can control all bad directions  $\xi_0 \odot \eta$

Recall:

$$\underbrace{dH_{ij}}_{\text{known}} = \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i$$

$$v_i = L_0^{-1}(\nabla \cdot (\gamma \nabla u_i))$$

$$dH_{ij}(\gamma, x) = (2\pi)^{-n} \iint_{R^n \times R^n} e^{i\xi \cdot (x-y)} (M_{ij}(x, \xi) + M_{ij}|_{-1}(x, \xi)) : \gamma(y) d\xi dy$$

### Lemma

Assume that  $Z = [\nabla \mu_1, \dots, \nabla \mu_n]$  is invertible, if  $\tilde{M}_{ij}|_{-1}^{nc} : \xi_0 \odot \eta = 0$  and  $\tilde{M}_{i,n+1}|_{-1}^{nc} : \xi_0 \odot \eta = 0$  for any  $1 \leq i, j \leq n$  and  $\xi_0 \perp \eta$  then  $\eta = 0$

### Theorem

Suppose that we have measurements  $\{dH_{ij}\}_{1 \leq i, j \leq n}$  and  $\{dH_{i,n+1}\}_{1 \leq i \leq n}$

such that  $Z = [\nabla \mu_1, \dots, \nabla \mu_n]$  is invertible and  $(\nabla u_1, \dots, \nabla u_n)$  form a frame.

we denote the operator  $dH$  as follows  $dH := (dH_{ij}, \dots, dH_{i,n+1})_{1 \leq i, j \leq n}$

Then the operator  $G \circ dH : \{L^2(\Omega')\}^{\frac{n(n+1)}{2}} \Rightarrow \{L^2(\Omega')\}^{\frac{n(n+1)}{2} + n}$

is semi-Fredholm, where  $G$  is the restriction operator to  $L^2(\Omega')$

Proof: construct a parametrix  $\mathcal{Q}$  such that  $\mathcal{Q} \circ dH - Id$  is of order -1

### 3.Explicit reconstruction

$$-\nabla \cdot (\gamma_0 \nabla \underbrace{u_i}_{known}) = 0 \quad (\Omega), \quad u_i|_{\partial\Omega} = \underbrace{g_i}_{known} \quad (*)$$

$$\begin{cases} -\nabla \cdot (\gamma_0 \nabla \underbrace{v_i}_{unknown}) = \nabla \cdot (\gamma \nabla u_i) & (\Omega), \quad v_i|_{\partial\Omega} = 0 \\ \underbrace{dH_{ij}}_{known} = \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i \end{cases}$$

Let us now add another solution of  $(*)$   $u$  with corresponding  $v$  at order  $\varepsilon$

$$u' = u + \varepsilon v + o(\varepsilon^2)$$

$\nabla u$  may be expressed in the basis  $\nabla u_1, \dots, \nabla u_n$

$$\sum_j^n \mu_j \nabla u_j + \nabla u = 0$$

Suppose  $[\nabla U] := [\nabla u_1 | \dots | \nabla u_n]$  and  $Z := [Z_1 | \dots | Z_n]$  be invertible, where  $Z_i = \nabla \mu_i$

In the end, we obtain the strongly **coupled** elliptic system

$$-\nabla \cdot (\gamma_0 \nabla v_i) + \sum_{j=1}^n W_{ij} \cdot \nabla v_j = f_i, \quad v_i|_{\partial\Omega} = 0 \quad 1 \leq i \leq n$$

where  $W_{ij}$  depends on  $\gamma_0$  and  $(u_1, \dots, u_n)$

$f_i$  depends on  $dH_{pq}$  and their derivatives

With  $L_0 := -\nabla \cdot (\gamma_0 \nabla)$  define  $L_0^{-1} : f \in L^2 \mapsto u \in H_0^1(\Omega)$  where  $u$  solves  $-\nabla \cdot (\gamma_0 \nabla u) = f$   
 $u|_{\partial\Omega} = 0$

By Lax-Milgram theorem, and by Rellich imbedding,  $L_0^{-1} : L^2(\Omega) \mapsto H_0^1(\Omega)$  is compact.

Applying  $L_0^{-1}$  to the elliptic system yields  $v_i + \sum_{j=1}^n L_0^{-1}(W_{ij} \cdot \nabla v_j) = h_i := L_0^{-1} f_i$

$P_{ij} : H_0^1(\Omega) \ni v \rightarrow P_{ij} v := L_0^{-1}(W_{ij} \cdot \nabla v) \in H_0^1(\Omega)$  compact if  $W_{ij}$  bounded.

we obtain  $(I + P)v = h \quad (*)$

where  $v = (v_1, \dots, v_n)$ ,  $h = (h_1, \dots, h_n)$ , and  $P$  compact

$(*)$  satisfies a Fredholm alternative, if -1 is not an eigenvalue of  $P$

and we obtain the stability:  $\|v_i\|_{H^1(\Omega)} \leq C \|dH\|_{H^1(\Omega)}$

once  $(\nu_1, \dots, \nu_n)$  are reconstructed

the relations

$$\underbrace{dH_{ij}}_{known} = \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla \nu_j + \gamma_0 \nabla u_j \cdot \nabla \nu_i$$

can be inverted for  $\gamma$

$$\gamma = \gamma_0 (dH_{ip} (H^{pq} \nabla u_q \otimes H^{ij} \nabla u_j) - 2 H^{ij} \nabla \nu_i \odot \nabla u_j) \gamma_0$$

and we get the stability

$$\|\gamma\|_{L^2(\Omega)} \leq C \|dH\|_{H^1(\Omega)}$$

- case  $\gamma_0$  is constant

$$\begin{aligned}
-\nabla \cdot (\gamma_0 \nabla \underbrace{u_i}_{known}) &= 0 \quad (\Omega), \quad u_i|_{\partial\Omega} = \underbrace{g_i}_{known} \quad (*) \\
-\nabla \cdot (\gamma_0 \nabla \underbrace{v_i}_{unknown}) &= \nabla \cdot (\gamma \nabla u_i) \quad (\Omega), \quad v_i|_{\partial\Omega} = 0 \\
\underbrace{dH_{ij}}_{known} &= \gamma \nabla u_i \cdot \nabla u_j + \gamma_0 \nabla u_i \cdot \nabla v_j + \gamma_0 \nabla u_j \cdot \nabla v_i
\end{aligned}$$

Taking  $\gamma_0 = Id$  using harmonic polynomials as solutions of  $(*)$

$$\begin{cases} u_i = x_i & 1 \leq i \leq n \\ u' = \frac{1}{2} \sum_{p=1}^n a_p x_p^2 & a_p \neq 0 \quad \sum_p a_p = 0 \end{cases}$$

Then we get n additional measurements

$$dH_i = \gamma : \nabla u_i \odot \nabla u' + \nabla u_i \odot \nabla v' + \nabla v_i \cdot \nabla u' \quad 1 \leq i \leq n$$

Together with  $dH_{ij} = \gamma \nabla u_i \cdot \nabla u_j + \nabla u_i \cdot \nabla v_j + \nabla u_j \cdot \nabla v_i \quad 1 \leq i, j \leq n$



$$\frac{1}{2}n(n+1)+n \quad \left\{ \begin{array}{ll} dH_i' = \gamma : \nabla u_i \odot \nabla u' + \nabla u_i \odot \nabla v' + \nabla v_i \cdot \nabla u' & 1 \leq i \leq n \\ dH_{ij} = \gamma \nabla u_i \cdot \nabla u_j + \nabla u_i \cdot \nabla v_j + \nabla u_j \cdot \nabla v_i & 1 \leq i, j \leq n \end{array} \right.$$

For this choice of  $(u_1, \dots, u_n)$ , the elliptic system is decoupled, hence solvable.

$$\Delta v_i = \frac{1}{a_i} \sum_{j=1}^n \partial_j (-\partial_j \sum_{p=1}^n a_p x_p dH_{ip} + \partial_j dH_i') + \frac{1}{a_i} \partial_i \sum_{p=1}^n a_p dH_{pp}$$

$$\gamma' = \underbrace{\gamma_0}_{\text{known}} + \varepsilon \gamma + o(\varepsilon^2)$$

$$u_i' = u_i + \varepsilon v_i + o(\varepsilon^2)$$

$$\gamma_{ij} = dH_{ij} - \partial_j v_i - \partial_i v_j$$

we obtain a standard estimate for  $v_i$  notice that the RHS is a linear combination of  $dH_{ij}, dH_i'$  and their first derivatives

stability:  $\|v_i\|_{H^1(\Omega)} \leq C \|dH\|_{H^1(\Omega)}$  then  $\|\gamma_{ij}\|_{L^2(\Omega)} \leq C \|dH\|_{H^1(\Omega)}$

$\Rightarrow$  we lose one derivative