

First order systems

①

Eigenvalues . Let A a $n \times n$ matrix . Then U is an eigenvector with eigenvalue λ if

$$AU = \lambda U$$

In order to get the eigenvalues, we compute

$$\det(A - \lambda I)$$

polynomial in λ

Then eigenvalues are roots of this polynomial

Once eigenvalues are obtained, the eigenvectors are computed by solving

$$(A - \lambda I)U = 0$$

lin. hom. system

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Rank or spring-mass system
we get a sys coupled
system describing x_1, x_2

eq for x_1 involves x_2
" " x_2 " x_1

2nd observation Any linear
higher ^{n -th} order eq can
be written as a system
of first diff eq. in $\mathbb{R}^n$
order

③

2nd-order example

$$y'' + \frac{1}{8} y' + y = 0 \quad \nearrow y = y(t)$$

$$\text{Set } x_1(t) = y$$

$$x_2(t) = y' \Rightarrow x_2' = y''$$

Then

$$(y)' = x_1'(t) = x_2(t) = y'$$

$$x_2'(t) + \frac{1}{8} x_2(t) + x_1(t) = 0$$

Thus

$$x_1' = x_2$$

$$x_2' = -x_1 - \frac{1}{8} x_2$$

linear syst of 1st
order eq. in $\mathbb{R}^2$

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From system in $\mathbb{R}^2$ to 2nd order diff eq

$$\begin{cases} x' = -2y \\ y' = \frac{1}{2}x \end{cases}$$

Then differentiate the 1st eq:

$$\begin{aligned} x'' &= -2y' \\ &\stackrel{\text{2nd eq}}{=} -2\left(\frac{1}{2}x\right) \\ &= -x \end{aligned}$$

The eq for x is thus

$$x'' + x = 0$$

Thus

⑤

Eq: $x'' + x = 0$

$P(\lambda) = \lambda^2 + 1$
roots: $\pm i$

Gen solution:

$$x = c_1 \cos(t) + c_2 \sin(t)$$

or

$$x = A \cos(t - \varphi)$$

In order to solve for y ,
we write (1st eq)

$$y = -\frac{1}{2} x' = \frac{1}{2} A \sin(t - \varphi)$$

Conclusion. It is equivalent to
solve

- 1st order system in $\mathbb{R}^2$
- 2nd order eq. in $\mathbb{R}$

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Graph for general solution. We have

$$\begin{cases} x = A \cos(t - \varphi) \\ y = \frac{1}{2} A \sin(t - \varphi) \end{cases}$$

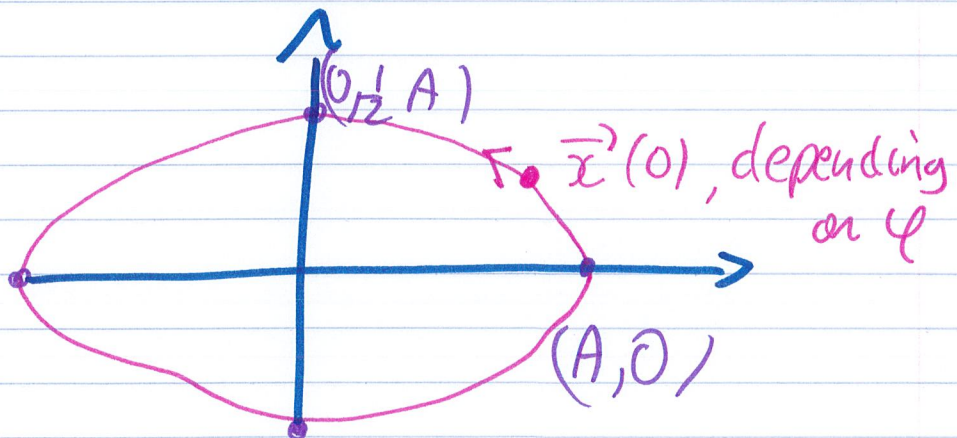
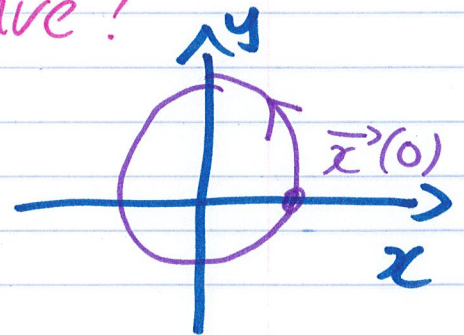
↳ curve in $\mathbb{R}^2$

Question: If we have

$$\begin{cases} x = \cos(t) \\ y = \sin(t) \end{cases}$$

→ what is the curve?

↳ $x^2 + y^2 = 1$



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Ex of 1st order system

$$\begin{cases} x' = y \\ y' = 2x + y \end{cases}$$

Differentiate 1st eq. $= x' \text{ (1st eq)}$

$$x'' = y' = 2x + \underbrace{y}_{=x'} = 2x + x'$$

we get a 2nd order diff eq

$$x'' - x' - 2x = 0$$

$$P(\lambda) = \lambda^2 - \lambda - 2$$

Gen sol: $x = c_1 e^{-t} + c_2 e^{2t}$

$$\text{Then } y = x' = -c_1 e^{-t} + 2c_2 e^{2t}$$

$\hookrightarrow$ 1st eq

$$x = c_1 e^{-t} + c_2 e^{2t}$$

$$y = -c_1 e^{-t} + 2c_2 e^{2t}$$

⑧

we get, in $\mathbb{R}^2$

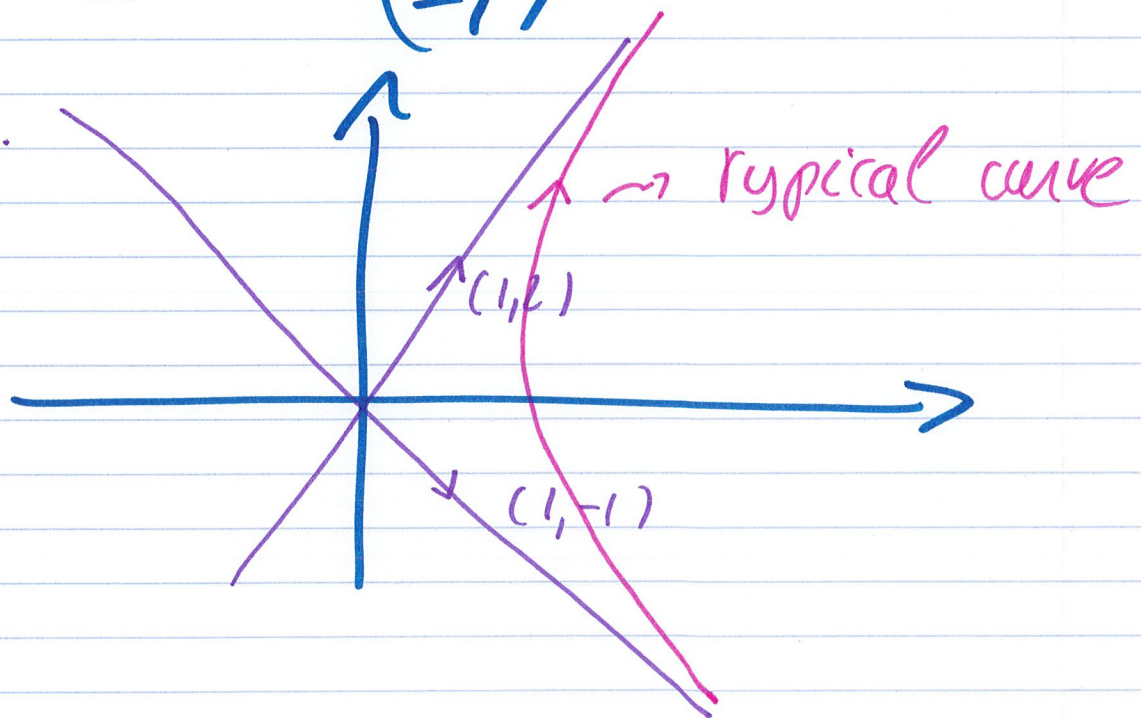
$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 e^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Dominant term as $t \rightarrow +\infty$

$$c_2 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \rightarrow \text{dominant direction}$$

Dominant term as $t \rightarrow -\infty$

$$c_1 e^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \rightarrow \text{dominant direction}$$



System as a matrix system

$$\begin{cases} x' = y \\ y' = 2x + y \end{cases}$$

can be written as

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

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Example of initial cond.

$$\begin{cases} x'_1 = x_1 + 2x_2 \\ x'_2 = 2x_1 - 2x_2 \end{cases}$$

We will see that a general sol. to this system is

$$\begin{cases} x_1 = c_1 e^{-3t} + c_2 e^{2t} \\ x_2 = -2c_1 e^{-3t} + \frac{1}{2} c_2 e^{2t} \end{cases}$$

In order to get a unique sol, we are given $x_1(0) = 1$ $x_2(0) = 0$ then we get

$$\begin{cases} 1 = c_1 + c_2 \\ 0 = -2c_1 + \frac{1}{2} c_2 \end{cases} \rightarrow \text{system for } c_1, c_2$$

Then unique sol is

$$\begin{aligned} x_1 &= \frac{1}{5} e^{-3t} + \frac{4}{5} e^{2t} \\ x_2 &= -\frac{2}{5} e^{-3t} + \frac{2}{5} e^{2t} \end{aligned}$$

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Example of Wronskian in $\mathbb{R}^2$

consider

$$\vec{x}_1(t) = \begin{pmatrix} e^t \\ 2e^t \end{pmatrix} \quad x_2(t) = \begin{pmatrix} 3\sin(t) \\ \cos(t) \end{pmatrix}$$

We wish to know if these functions are linearly dependent. We compute

$$W[x_1, x_2](t) = \begin{vmatrix} e^t & 3\sin(t) \\ 2e^t & \cos(t) \end{vmatrix}$$

$$= e^t \cos(t) - 2e^t \times 3\sin(t)$$

$$= e^t (\cos(t) - 6\sin(t))$$

At $t_0 = 0$, we have

$$W[x_1, x_2](0) = e^0 (1 - 0) = 1 \neq 0$$

$\Rightarrow$ According to Thm 2, $\{x_1, x_2\}$ are lin. indep.