

Outline

- 1 Birth processes and the Poisson process
 - Poisson process
 - Birth processes
- 2 Continuous time Markov chain
 - General definitions and transitions
 - Generators
 - Classification of states

Irreducibility of chains

Proposition 33.

Let X Markov chain with standard transition P_t

Then we have

- ① For every pair $i, j \in S$, either

$$p_{ij}(t) = 0 \text{ for all } t > 0$$

or

$$p_{ij}(t) > 0 \text{ for all } t > 0$$

from i , one can never reach j (should be seen on $G(x_1)$)

- ② Terminology: if $p_{ij}(t) > 0$ for all $t > 0$

$\hookrightarrow X$ is said to be **irreducible**

- ③ In order to know if X is irreducible

\hookrightarrow draw graph related to G

Birth process example

Recall: For the birth process,

$$G = \begin{bmatrix} -\lambda_0 & \lambda_0 & 0 & 0 & 0 & \cdots \\ 0 & -\lambda_1 & \lambda_1 & 0 & 0 & \cdots \\ 0 & 0 & -\lambda_2 & \lambda_2 & 0 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

Nature of states:

All states are transient

Graph of X



There is no closed class

\Rightarrow every state is transient

Bmk we already know that

$$\lim_{t \rightarrow \infty} N(t) = \infty$$

\Rightarrow No invariant measure

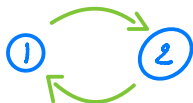
2 states example

Recall:

$$G = \begin{bmatrix} -\alpha & \alpha \\ \beta & -\beta \end{bmatrix}$$

Nature of states:

The chain is irreducible



we have a unique class

$\Rightarrow X$ irreducible

$\Rightarrow p_{ij}(t) > 0 \quad \forall i, j \quad \forall t > 0$

Rmk By solving $P'_t = P_t G$, we have
seen

$$\begin{pmatrix} p_{11}(t) \\ p_{12}(t) \end{pmatrix} = \frac{1}{\alpha + \beta} \begin{pmatrix} \beta \\ \alpha \end{pmatrix} - \frac{\alpha}{\alpha + \beta} \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{-(\alpha + \beta)t}$$

In particular, one can easily see

$$p_{11}(t) > 0, \quad p_{12}(t) > 0 \quad \forall t > 0$$

same thing for $p_{21}(t), p_{22}(t)$

Stationary distribution

Definition 34.

Let

- X Markov chain with transition P_t
- π vector

Then π is a stationary distribution if

- 1 $\pi_j \geq 0$ for all $j \in S$ and $\sum_{j \in S} \pi_j = 1$
- 2 π satisfies $\pi = \pi P_t$ for all $t \geq 0$, that is

$$\pi_j = \sum_{i \in S} \pi_i p_{ij}(t), \quad \text{for all } j \in S, \forall t \geq 0$$

Q: Can we make those conditions simpler?

Rmk If $\pi P_t = \pi$ for all t , then

$$\pi P_t - \pi \text{Id} = 0$$

$$\Rightarrow \pi \frac{(P_t - \text{Id})}{t} = \frac{0}{t}$$

As $t \rightarrow 0$ we get

$$\boxed{\pi G = 0}$$

Interpretation of stationary distribution

Proposition 35.

Let

- X Markov chain with transition P
- π invariant distribution

Then

$$X_0 \sim \pi \implies X(t) \sim \pi \text{ for all } t \geq 0$$

Otherwise stated,

$$\mathbf{P}(X(t) = j | X(0) \sim \pi) = \pi_j$$

Stationary distribution and generator

Proposition 36.

Let

- X Markov chain with transition P and generator G
- π distribution

Then

$$\pi \text{ invariant distribution} \quad \begin{matrix} \Rightarrow \\ \Leftrightarrow \end{matrix} \quad \pi G = 0$$

Proof of Proposition 36

Basic relation: We have

$$\pi G = 0 \iff \pi G^n = 0$$

Reasoning with matrix exponential: We get

$$\begin{aligned} \pi G = 0 &\iff \sum_{n=1}^{\infty} \frac{t^n}{n!} \pi G^n = 0, \quad \text{for all } t \geq 0 \\ &\iff \pi \sum_{n=1}^{\infty} \frac{t^n}{n!} G^n = 0, \quad \text{for all } t \geq 0 \\ &\iff \pi \sum_{n=0}^{\infty} \frac{t^n}{n!} G^n = \pi, \quad \text{for all } t \geq 0 \\ &\iff \pi P_t = \pi, \quad \text{for all } t \geq 0 \end{aligned}$$

Ergodic theorem

Proposition 37.

Let

- X Markov chain with transition P and generator G
- Assume X is irreducible

Then

- 1 If there exists a stationary distribution π , then

π is unique and $\lim_{t \rightarrow \infty} p_{ij}(t) = \pi_j$ for all $i, j \in S$

- 2 If there is no stationary distribution π , then

$\lim_{t \rightarrow \infty} p_{ij}(t) = 0$ for all $i, j \in S$

2 states example (1)

Recall:

$$G = \begin{bmatrix} -\alpha & \alpha \\ \beta & -\beta \end{bmatrix}$$

Invariant distribution: The chain is irreducible and we have

$$\pi = \left[\frac{\beta}{\alpha + \beta} \quad \frac{\alpha}{\alpha + \beta} \right] \implies \pi G = 0$$

$$\implies p_{ij}(t) \longrightarrow \pi_j \quad \text{for } i=1,2$$

(ergodic theorem)

2 states example (2)

$$G = \begin{pmatrix} \alpha & \alpha \\ \beta & -\beta \end{pmatrix}$$

Recall: We have seen

$$\begin{bmatrix} p_{11}(t) \\ p_{12}(t) \end{bmatrix} = \frac{1}{\alpha + \beta} \begin{bmatrix} \beta \\ \alpha \end{bmatrix} - \frac{\alpha}{\alpha + \beta} \begin{bmatrix} -1 \\ 1 \end{bmatrix} \exp(-(\alpha + \beta)t)$$

Verifying the ergodic theorem: We get

$$\lim_{t \rightarrow \infty} \begin{bmatrix} p_{11}(t) \\ p_{12}(t) \end{bmatrix} = \frac{1}{\alpha + \beta} \begin{bmatrix} \beta \\ \alpha \end{bmatrix} = \begin{bmatrix} \pi_1 \\ \pi_2 \end{bmatrix}$$

$$\begin{pmatrix} \pi_1 \\ \pi_2 \end{pmatrix}$$

Ergodic theorem is satisfied on this simple example