

# Math 265 Midterm 1

Oct 2nd, 2008

Name: \_\_\_\_\_

Section: \_\_\_\_\_

This exam consists of 8 pages including this front page.

## Ground Rules

1. No calculator is allowed.
2. Show your work for every problem unless otherwise stated.
3. You may use one 4-by-6 index card, both sides.

<i>Score</i>		
1	20	
2	20	
3	10	
4	10	
5	20	
6	10	
7	10	
<i>Total</i>	100	

1. The following are true/false questions. You don't have to justify your answers. Just write down either T or F in the table below.  $A$ ,  $B$ ,  $C$ ,  $X$ ,  $b$  are always matrices here.

- (a) If  $A = A^T$  then  $A$  is a square matrix.
- (b) If  $AB = AC$  and  $A \neq 0$  then  $B = C$ .
- (c) Consider a system of linear equations  $AX = b$  where  $A$  is a square matrix. If the system is inconsistent then  $\det(A) = 0$ .
- (d) Let  $L$  be a straight line in the plane  $\mathbb{R}^2$ . Then  $L$  is a subspace of  $\mathbb{R}^2$ .
- (e) If  $A^2 = 0$  then  $A$  is singular.

	(a)	(b)	(c)	(d)	(e)
Answer	T	F	T	F	T

Explain:

1. If  $A$  is a  $m \times n$ -matrix then  $A^T$  is a  $n \times m$ -matrix. So if  $A = A^T$  then  $m = n$  and  $A$  is a square matrix.
2. Counterexample:  $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ ,  $B = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$ ,  $C = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ .
3. If  $\det(A) \neq 0$  then  $A^{-1}$  exists and  $AX = b$  has a unique solution  $X = A^{-1}b$ . Thus if  $AX = b$  is inconsistent then  $\det(A)$  must be 0.
4. A straight line in  $\mathbb{R}^2$  is a subspace if and only if the line passing through the origin.
5.  $A^2 = 0$  implies that  $\det(A)^2 = 0$ , hence  $\det(A) = 0$  and  $A$  is singular.

2. Quick Questions,  $A$ ,  $B$ ,  $C$ ,  $X$ ,  $b$  are always matrices here:

(a) Suppose that  $A$  is nonsingular and  $A^2 = A$ .  $\det(A) = ?$

$\det(A^2) = (\det(A))^2 = \det(A)$ . Since  $A$  is nonsingular,  $\det(A) \neq 0$ . So  $\det(A) = 1$ .

(b) Suppose  $AX = 2X$  and  $A^{-1}X = aX$ . Then  $a = ?$

Since  $A$  exists, times  $A^{-1}$  to  $AX = 2X$ , we get  $X = A^{-1}2X$ . Hence  $A^{-1}X = \frac{1}{2}X$  and  $a = \frac{1}{2}$ .

(c) Let  $\mathbb{R}^{2 \times 2}$  be the vector space of  $2 \times 2$ -matrices and  $W = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid abcd = 0 \right\}$ .  
Is  $W$  the subspace of  $\mathbb{R}^{2 \times 2}$ ? why?

No. Because it is not closed under addition. For example,  $A = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$   
and  $B = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$  are in  $W$ . But  $A + B = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$  are not in  $W$ .

(d) Find a matrix  $A$  such that  $Y = \begin{pmatrix} 1 \\ 2 \\ 0 \\ -1 \end{pmatrix}$  is in the null space  $N(A)$  of  $A$   
(Recall that  $N(A) = \{X \mid AX = 0\}$ ).

We may assume that  $A = (a_1 \ a_2 \ a_3 \ a_4)$  a  $4 \times 1$ -matrix. If  $Y \in N(A)$  then  $AY = 0$ . Hence we must have  $a_1 \cdot 1 + a_2 \cdot 2 + a_3 \cdot 0 + a_4 \cdot -1 = 0$ . Equivalently,  $a_1 + 2a_2 - a_4 = 0$ . So we may take  $a_1 = 1, a_2 = 2, a_3 = 3$  and  $a_4 = a_1 + 2a_2 = 5$ . Thus  $A = (1, 2, 3, 5)$ .

3. Let

$$A = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 1 & -2 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 0 & -2 & 1 \\ 1 & -2 & 1 \end{bmatrix}.$$

(a) Compute  $3A - 2B$ .

$$\text{Solution: } 3A - 2B = \begin{pmatrix} 3 & 4 & -5 \\ 4 & 7 & -8 \end{pmatrix}$$

(b) Compute  $AB^T$ .

Solution:

$$AB^T = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -2 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ -2 & -2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ -4 & -2 \end{pmatrix}$$

4. In the following linear system, determine all values of  $a$  for which the resulting linear system has

- (a) no solution.
- (b) a unique solution
- (c) infinitely many solutions

$$\begin{aligned}x + y - z &= 2 \\x + 2y + z &= 3 \\x + y + (a^2 - 5)z &= a\end{aligned}$$

Solution:

We have a augmented matrix

$$\left( \begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 1 & 2 & 1 & 3 \\ 1 & 1 & a^2 - 5 & a \end{array} \right)$$

Use row operations  $r_2 - r_1 \rightarrow r_2$  and  $r_3 - r_1 \rightarrow r_3$ , we get

$$\left( \begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & a^2 - 4 & a - 2 \end{array} \right)$$

If  $a^2 - 4 = 0$  and  $a - 2 \neq 0$  then the last leading one locates in the last column, and the system has no solution. Note that  $a^2 - 4 = 0$  if and only if  $a = \pm 2$ , and  $a - 2 \neq 0$  if and only if  $a \neq 2$ . That is, the system has no solution if and only if  $a = -2$ .

If  $a^2 - 4 \neq 0$  then the coefficients matrix is nonsingular and the system has a unique solution. That is if  $a \neq \pm 2$  then the system has a unique solution.

Finally, if  $a^2 - 4 = a - 2 = 0$  then the system has infinitely many solution. This only happens only  $a = 2$ .

5. (a) Compute

$$\begin{vmatrix} -2 & 0 & 0 & 0 \\ 5 & 3 & 5 & 7 \\ 3 & 0 & 2 & 1 \\ 8 & 0 & 2 & 2 \end{vmatrix}.$$

Solution: Use cofactor formula for the first row, we have

$$\det(A) = -2(-1)^{1+1} \begin{vmatrix} 3 & 5 & 7 \\ 0 & 2 & 1 \\ 0 & 2 & 2 \end{vmatrix}.$$

Use cofactor formula for the first column,

$$\det(A) = -2 \cdot 3 \cdot \begin{vmatrix} 2 & 1 \\ 2 & 2 \end{vmatrix} = -2 \cdot 3 \cdot 2 = -12.$$

(b) Compute  $A^{-1}$ , where

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 2 & 1 & 5 \end{bmatrix}$$

Solution: Using Gauss-Jordan method, we have  $A^{-1} = \begin{pmatrix} -3 & -2 & 2 \\ -4 & -1 & 2 \\ 2 & 1 & -1 \end{pmatrix}$ .

6. Solve the following linear system using Cramer's rule.

$$\begin{aligned}2x_1 + 4x_2 + 6x_3 &= 2 \\x_1 + 2x_3 &= 0 \\2x_1 + 3x_2 - x_3 &= -5\end{aligned}$$

Solution:

By Cramer's rule, set

$$A = \begin{pmatrix} 2 & 4 & 6 \\ 1 & 0 & 2 \\ 2 & 3 & -1 \end{pmatrix}, \quad A_1 = \begin{pmatrix} 2 & 4 & 6 \\ 0 & 0 & 2 \\ -5 & 3 & -1 \end{pmatrix},$$

$$A_2 = \begin{pmatrix} 2 & 2 & 6 \\ 2 & 0 & 2 \\ 2 & -5 & -1 \end{pmatrix} \quad \text{and} \quad A_3 = \begin{pmatrix} 2 & 4 & 2 \\ 1 & 0 & 0 \\ 2 & 3 & -5 \end{pmatrix}$$

Hence

$$x_1 = \frac{\det(A_1)}{\det(A)} = \frac{-52}{26} = -2.$$

$$x_2 = \frac{\det(A_2)}{\det(A)} = \frac{0}{26} = 0.$$

$$x_3 = \frac{\det(A_3)}{\det(A)} = \frac{26}{26} = 1.$$

7. Let  $V$  be the set of all positive real numbers; define  $u \oplus v = uv$  ( $\oplus$  is ordinary multiplication) define  $\odot$  by  $c \odot u = u^c$ . Prove that  $V$  is a vector space by the following steps:

- (a) Verify that  $V$  is closed under addition and scalar multiplication.

Let  $u, v \in V$  and  $c \in \mathbb{R}$ .  $u \oplus v = uv$  is positive thus  $u \oplus v \in V$ .  $c \odot u = u^c$  is still positive and  $c \odot u \in V$ . Thus  $V$  is closed under addition and scalar multiplication.

- (b) Verify  $u \oplus v = v \oplus u$  and  $(u \oplus v) \oplus w = u \oplus (v \oplus w)$ .

$$u \oplus v = uv = vu = v \oplus u.$$

$$(u \oplus v) \oplus w = (uv)w = u(vw) = u \oplus (v \oplus w).$$

- (c) What is zero vector in the set  $V$ , explain?

The zero vector is 1 because for any  $u \in V$ ,  $1 \oplus u = 1u = u$ .

- (d) For any  $u \in V$ , find  $-u$ .

$(-u) = \frac{1}{u}$  because  $(-u) \oplus u = \frac{1}{u}u = 1$ , which is the zero vector proved in last question.

- (e) For any real number  $c, d \in \mathbb{R}$ , and  $u, v \in V$ , Verify  $c \odot (u \oplus v) = c \odot u \oplus c \odot v$ ;  $(c + d) \odot u = c \odot u \oplus d \odot u$ ;  $c \odot (d \odot u) = (c \cdot d) \odot u$  and  $1 \odot u = u$ .

$$c \odot (u \oplus v) = c \odot (uv) = (uv)^c = u^c v^c = (c \odot u)(c \odot v) = c \odot u \oplus c \odot v.$$

$$(c + d) \odot u = u^{c+d} = u^c u^d = (u^c) \oplus (u^d) = c \odot u \oplus d \odot u$$

$$c \odot (d \odot u) = c \odot (u^d) = (u^d)^c = u^{cd} = (c \cdot d) \odot u$$

$$1 \odot u = u^1 = u.$$