## Math 265, Practice Midterm 1

Name: \_\_\_\_\_

This exam consists of 8 pages including this front page.

## Ground Rules

- 1. No calculator is allowed.
- 2. Show your work for every problem unless otherwise stated.

Score						
1	16					
2	16					
3	15					
4	15					
5	15					
6	10					
7	13					
Total	100					

- 1. The following are true/false questions. You don't have to justify your answers. Just write down either T or F in the table below. A, B, C, X, b are always matrices here.
  - (a) If  $A^2$  makes sense then A is a square matrix.
  - (b) A system of linear equations can not have exactly 2 solutions.
  - (c) If AB = AC and  $A \neq 0$  then B = C.
  - (d) Let W be a subspace of  $\mathbb{R}^n$ . If  $v \in W$  then  $-v \in W$ .
  - (e)  $\det(2A) = 2 \det(A)$ .
  - (f) A square matrix A is invertible if and only if AX = b has at most one solution.
  - (g) Let  $v_1, \ldots, v_m \in \mathbb{R}^n$ . If  $m \leq n$  then  $v_1, \ldots, v_m$  is always linearly independent.
  - (h) Let  $T : \mathbb{R}^m \to \mathbb{R}^n$  is linear transformation. Then if  $v_1, \ldots, v_m$  is a basis of  $\mathbb{R}^m$  then  $T(v_1), \ldots, T(v_m)$  is a basis of  $\mathbb{R}^n$ .

	(a)	(b)	(c)	(d)	(e)	(f)	(g)	(h)
Answer	Т	Т	F	Т	F	Т	F	F

- **2.** Quick Questions, A, B, C, X, b are always matrices here:
  - (a) Suppose that  $det(A) = det(A^{-1})$ . Find det(A). Solutions: Since  $det(A) = det(A)^{-1}$ ,  $det(A)^2 = 1$ . So  $det(A) = \pm 1$ .
  - (b) Suppose AX = 2X and  $A^3X = aX$ . Then a =? Solutions: a = 8
  - (c) Let

$$A = \begin{bmatrix} 1 & 0 & -1 \\ 2 & -3 & 1 \end{bmatrix} \text{ and } B = \begin{bmatrix} 0 & -2 & 1 \\ 1 & 2 & -2 \end{bmatrix}.$$

Compute  $2I_2 - AB^T$ .

Solutions: 
$$2I_2 - AB^T = \begin{bmatrix} 3 & -3 \\ -7 & 8 \end{bmatrix}$$

(d) Let 
$$V = \left\{ \begin{pmatrix} a \\ b \end{pmatrix} | ab = 0 \right\}$$
. Is V a subspace of  $\mathbb{R}^2$ ? why?

Solutions: No. V is not closed under addition. For example,  $u = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and  $v = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  are in V. But  $u + v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is not in V. **3.** Let  $T: \mathbb{R}^2 \to \mathbb{R}^2$  be a linear transformation. Suppose that

$$T(\begin{bmatrix} 1\\1 \end{bmatrix}) = \begin{bmatrix} 1\\3 \end{bmatrix}, \ T(\begin{bmatrix} 1\\-1 \end{bmatrix}) = \begin{bmatrix} 3\\1 \end{bmatrix}.$$

(a) Find the standard matrix for T.

We easily find that 
$$\begin{bmatrix} 1\\0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1\\1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1\\-1 \end{bmatrix}$$
 and  $\begin{bmatrix} 1\\0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1\\1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1\\-1 \end{bmatrix}$ .  
So
$$T(\begin{bmatrix} 1\\0 \end{bmatrix}) = \frac{1}{2}T(\begin{bmatrix} 1\\1 \end{bmatrix}) + \frac{1}{2}T(\begin{bmatrix} 1\\-1 \end{bmatrix}) = \begin{bmatrix} 2\\2 \end{bmatrix}.$$
and

and

$$T\begin{pmatrix} 0\\1 \end{pmatrix} = \frac{1}{2}T\begin{pmatrix} 1\\1 \end{pmatrix} - \frac{1}{2}T\begin{pmatrix} 1\\-1 \end{pmatrix} = \begin{bmatrix} -1\\1 \end{bmatrix}.$$

Therefore the standard matrix of T is given by

$$(T(e_1), T(e_2)) = \begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix}$$

(b) Is T onto? Explain.

Solutions: The standard matrix of T is invertible because it has determinate  $4 \neq 0$ . So T is onto and one-to-one.

(c) Is T one-to-one? Explain.

4. Consider the following linear system

$$\begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 1 & 1 & a^2 - 4 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 7 \\ a \end{pmatrix}$$

(a) Determine all values of a such that the system has no solution.

Solutions: The augmented matrix of the above system is

$$\begin{pmatrix} 1 & 1 & 0 & 2 \\ 1 & 2 & 1 & 7 \\ 1 & 1 & a^2 - 4 & a \end{pmatrix}.$$

Then we get the echelon form:

$$\begin{pmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & a^2 - 4 & a - 2 \end{pmatrix}$$

Then the system has no solution if and only if  $a^2 - 4 = 0$  and  $a - 2 \neq 0$ . So a = -2

(b) Determine all values of a such that the system has infinitely many solutions.

Solutions: The system has infinitely many solutions if and only if  $a^2 - 4 = a - 2 = 0$ . So a = 2.

(c) Determine all values of a such that the system has a unique solution.

Solutions: The system has unique solution if and only if  $a^2 - 4 \neq 0$ . That is  $a \neq \pm 2$ . 5. (a) Compute

$$\begin{vmatrix} -2 & 0 & 0 & 0 \\ 5 & 3 & 5 & 7 \\ 3 & 0 & 2 & 1 \\ 8 & 0 & 2 & 2 \end{vmatrix}$$

Solution: By cofactor's formula, we get

$$\det(A) = -2 \begin{vmatrix} 3 & 5 & 7 \\ 0 & 2 & 1 \\ 0 & 2 & 2 \end{vmatrix} = (-2)3 \begin{vmatrix} 2 & 1 \\ 2 & 2 \end{vmatrix} = -2 \cdot 3 \cdot 2 = -12.$$

(b) Compute  $A^{-1}$ , where

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 2 & 1 & 5 \end{bmatrix}$$

Solution:

$$A^{-1} = \begin{bmatrix} -3 & -2 & 2\\ -4 & -1 & 2\\ 2 & 1 & -1 \end{bmatrix}$$

6. Solve the following linear system using Cramer's rule.

$$\begin{array}{rcl} -2x_1 + 3x_2 - x_3 &= 1\\ x_1 + 2x_2 - x_3 &= 4\\ -2x_1 - x_2 + x_3 &= -3 \end{array}$$

Solutions: By Cramer's rule.

$$|A| = \begin{vmatrix} -2 & 3 & -1 \\ 1 & 2 & -1 \\ -2 & -1 & 1 \end{vmatrix} = -2$$
$$|A_1| = \begin{vmatrix} 1 & 3 & -1 \\ 4 & 2 & -1 \\ -3 & -1 & 1 \end{vmatrix} = -4$$
$$|A_2| = \begin{vmatrix} -2 & 1 & -1 \\ 1 & 4 & -1 \\ -2 & -3 & 1 \end{vmatrix} = -6$$
$$|A_3| = \begin{vmatrix} -2 & 3 & 1 \\ 1 & 2 & 4 \\ -2 & -1 & -3 \end{vmatrix} = -8$$

 $\operatorname{So}$ 

$$x_1 = \frac{|A_1|}{|A|} = 2, \ x_2 = \frac{|A_2|}{|A|} = 3, \ x_3 = \frac{|A_3|}{|A|} = 4.$$

7. Let 
$$A = \begin{pmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{pmatrix}$$

(a) Find a basis of column space of A.Solutions The reduced echelon form of A is

$$\begin{pmatrix} 1 & -2 & 0 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Since it has pivots in first and third column, we conclude that first and third column of A, that is,  $\begin{bmatrix} -3\\1\\2\\5 \end{bmatrix}$ ,  $\begin{bmatrix} -1\\2\\5 \end{bmatrix}$  is a basis of  $\operatorname{Col}(A)$ 

(b) Find a basis of the null space of A.

Solution: From reduced echelon form of A, we can solve  $AX = \vec{0}$ . We have  $x_1 = 2x_2 + x_4 - 3x_5$  and  $x_3 = -2x_4 + 2x_5$ . Hence the general solution of  $AX = \vec{0}$  is

$$X = \begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$
  
So 
$$\begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$
 is a basis of null space.

(c) Verify dimension theorem dim NulA + rankA = n for this matrix A. Solutions: From (1) and (2), we the rank of A is 2 and dim Nul(A)=3. So we get

 $\dim \operatorname{Nul} A + \operatorname{rank} A = 3 + 2 = 5 = n.$