

## Section 1.1

### Direction fields.

Differential equations are equations containing derivatives. In these equations, the unknown is a function.

Ex: Find the function  $y(t)$  such that:

$$(*) \quad y'(t) = 2y(t)$$

Note: We are familiar with equations for numbers. For example: Find  $x$  such that  $x^2 = 2x$ . We have  $x^2 - 2x = 0$ , that is,  $x(x-2) = 0$ , and  $x_1 = 0$ ,  $x_2 = 2$ .

Trivially, we note that the function  $y(t) \equiv 0$  solves equation (\*). It is the function identically zero (not the number 0).

Since the exponential is a function whose derivative is again the same function, we see that:

$$y(t) = e^{2t} \text{ solves } (*).$$

Indeed:

$$y'(t) = 2e^{2t} = 2y(t), \text{ for every } t.$$

But:

$y(t) = 2e^{2t}$  also solves (\*),

(2)

because:

$$y'(t) = 4e^{2t} = 2(2e^{2t}) = 2y(t),$$

for every  $t$ .

Actually, there is a family of solutions: any function of the form:

$$y(t) = Ce^{2t}, \quad C \text{ any real number,}$$

is a solution of (\*) because if we plug  $y(t)$  in (\*), the equation holds:

$$y'(t) = 2Ce^{2t} = 2(Ce^{2t}) = 2y(t), \text{ for every } t$$

Conclusion: We have found an infinite number of solutions to  $y' = 2y$ . The solutions form a family:

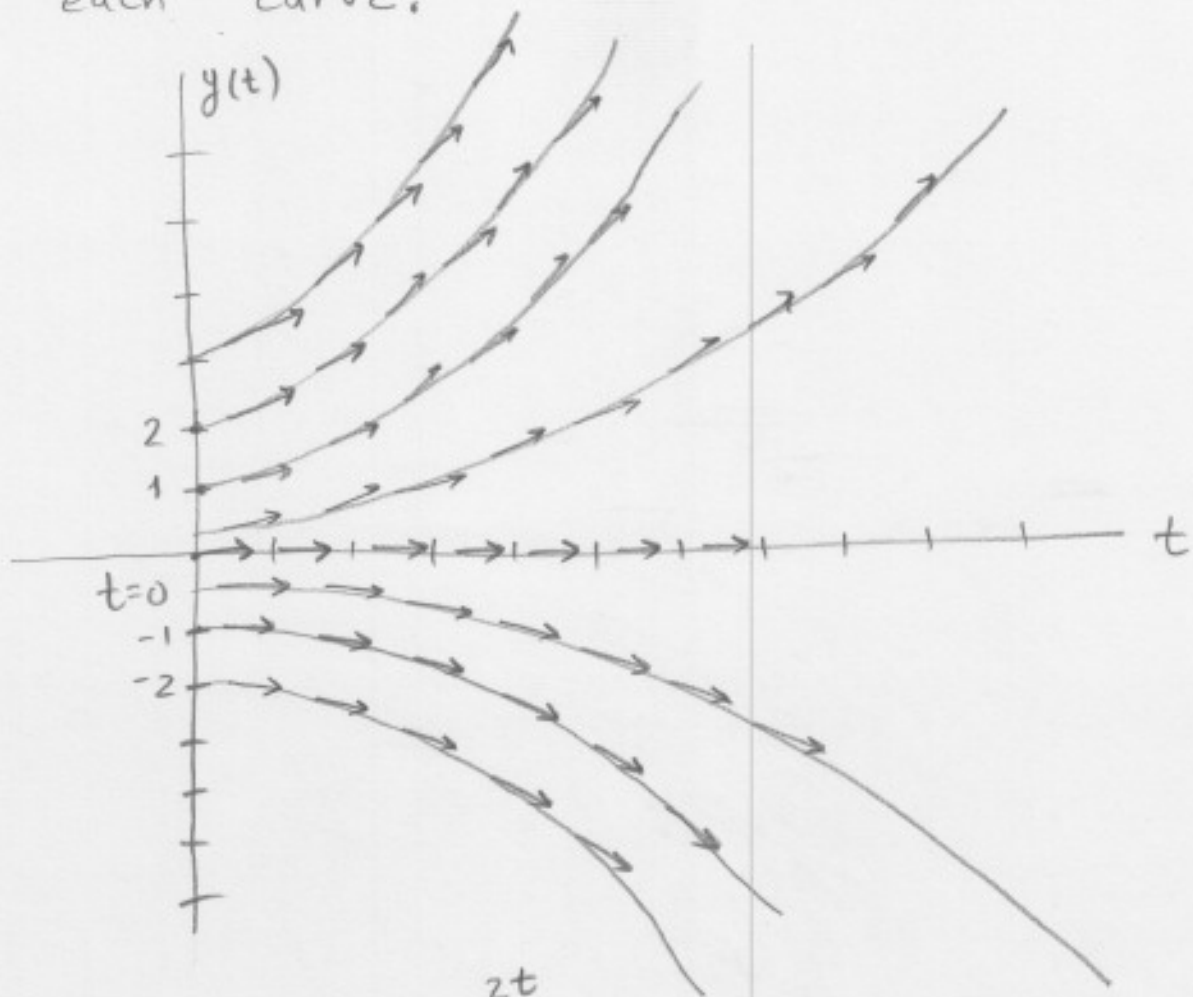
$$y(t) = Ce^{2t}, \quad C \text{ any real number.}$$

Question: Are these the only solutions of (\*). Could we find another function (that is not of the form  $y = Ce^{2t}$ ) that solves (\*)?

The answer is no, but this needs to be proven mathematically.

(3)

We can now draw this family of solutions together with tangent vectors to each curve.



$$y(t) = ce^{2t}$$

$y(0) = ce^{2(0)} = C$ , this is the initial condition, the value of  $y$  at  $t=0$ .

$$C=1 \Rightarrow y = e^{2t}$$

$$C=2 \Rightarrow y = 2e^{2t}$$

$$C=0 \Rightarrow y(t) \equiv 0, \text{ for every } t$$

$$C=-1 \Rightarrow y = -e^{2t}$$

$$C=-2 \Rightarrow y = -2e^{2t}$$

Note: Two solution curves never intersect, this fact of differential equations needs to be proved mathematically.

## Direction field

A direction field is the graph  $t$  versus  $y$  with all the arrows that are tangent to the solution curves.

If we only have the arrows, we can draw the solution curves, starting at some initial condition  $y(0)$ , and following the direction given by the arrows. From the direction field corresponding to  $y' = 2y$  we see the following:

$$\lim_{t \rightarrow \infty} y(t) = \infty, \text{ if } y(0) > 0$$

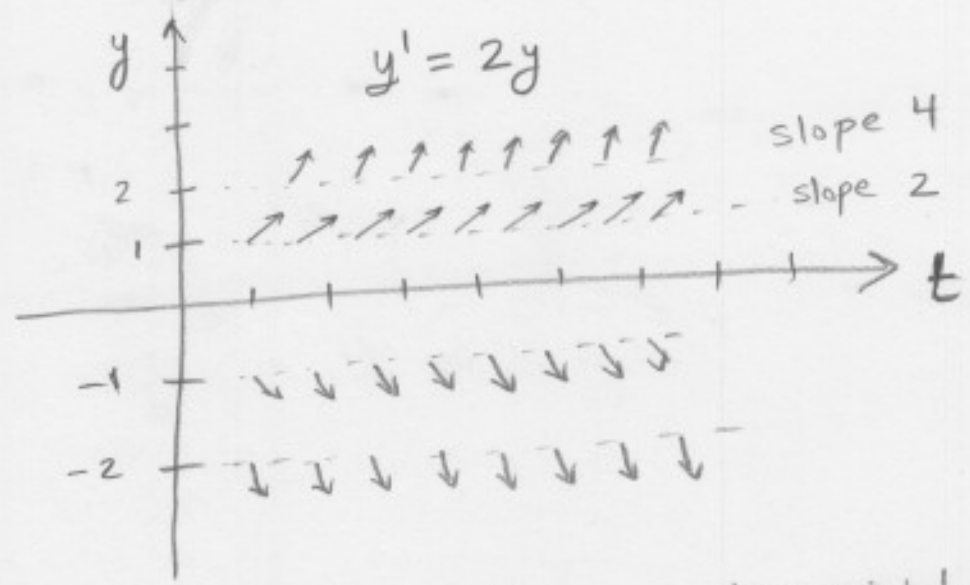
$$\lim_{t \rightarrow \infty} y(t) = -\infty, \text{ if } y(0) < 0$$

The solution  $y(t) \equiv 0$  is called an equilibrium solution because it is a constant solution (horizontal curve).

In real applications, we may only know that solutions to a differential equation exist, but it might be impossible (or very hard) to have a formula for the solution. In these cases, we can always draw the direction field, using only the equation.

How to draw the direction field using only the equation? Given a  $t$  and a  $y$ , we plug them in the equation to find  $y'(t)$ , and we draw an arrow with slope  $y'(t)$  at  $(t, y)$

$y$	$y'(t)$
2	4
1	2
0	0
-1	-2
-2	4



Since  $y' = 2y$  does not have  $t$ 's on the right side, note that all the arrows have the same slope in a horizontal row of arrows (independent of the value of  $t$ ).

However, if we had the equation, say,  $y' = y^2 + e^t$ , we would need to consider the  $t$ :

$t$	$y$	$y'(t)$
1	1	$y' = 1 + e^1$
2	0	$y' = 0 + e^2$
3	-1	$y' = 1 + e^3$

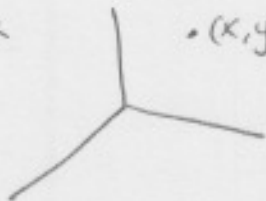
Matlab can plug many values of  $t, y$  in the equation and draw the arrows very fast.

Differential equation are divided in 2 major groups:

Ordinary differential equations: The word ordinary refers to the fact that the unknown is a function of 1 variable,  $y(t)$ .

Ex:  $y' = y^2 + \sin t$   
 $y''(t) - 2y'(t) + y(t) = e^t$

Partial differential equations: The word partial refers to the fact that the unknown is a function of more than 1 variable.

Ex   $(x, y, z)$   $u(t, x, y, z)$  is the temperature of the room at time  $t$ , and at the location  $(x, y, z)$

The heat equation is:

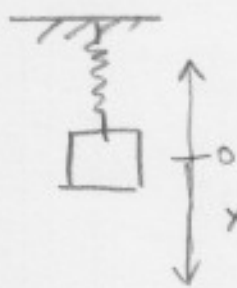
$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \text{ or } u_t = u_{xx} + u_{yy} + u_{zz}$$

To find a  $u$  that solves this equation is more advanced (see section 10.5 in your book).

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We can use ordinary differential equations to model physical phenomena that can be described with only one variable

Ex.



$x(t)$  = displacement from equilibrium at time  $t$

If you have a spring with a block, you pull down the block and let the spring move up and down in one line. The displacement can be measured with a function  $x(t)$  of one variable  $t$ .

In general, many fundamental differential equations that model fluid flow, electro-magnetism, heat, waves, etc, are partial since we live in more than one dimension.