

Section 3.5, continuation

Method of undetermined coefficients

Recall from previous class that if we are solving:

$$ay'' + by' + cy = g(t) = g_1(t) + g_2(t), \quad (**)$$

then the general solution is:

$$y(t) = c_1 y_1 + c_2 y_2 + Y(t),$$

where $y_H(t) = c_1 y_1 + c_2 y_2$ is the general solution to the corresponding homogeneous equation:

$$ay'' + by' + cy = 0,$$

and $Y(t)$ is a particular solution to the non-homogeneous equation; that is:

$$aY'' + bY' + cY = g(t).$$

If $g(t)$ is the sum of $g_1(t)$ and $g_2(t)$, then, if Y_1 and Y_2 are solutions to:

$$aY_1'' + bY_1' + cY_1 = g_1(t),$$

$$aY_2'' + bY_2' + cY_2 = g_2(t),$$

we have:

$$Y = Y_1 + Y_2$$

Indeed, $Y_1 + Y_2$ is a solution to the non-homogeneous equation (***) since:

$$\begin{aligned}
a(Y_1 + Y_2)'' + b(Y_1 + Y_2)' + c(Y_1 + Y_2) &= \\
a(Y_1'' + Y_2'') + b(Y_1' + Y_2') + cY_1 + cY_2 &= \\
(aY_1'' + bY_1' + cY_1) + (aY_2'' + bY_2' + cY_2) &= \\
= g_1(t) + g_2(t) = g(t) &
\end{aligned}$$

Notes: If $g = g_1 + g_2 + \dots$

Note: If $g(t) = g_1(t) + g_2(t) + \dots + g_n(t)$, then $Y(t) = Y_1 + Y_2 + \dots + Y_n$, where Y_i solves:

$$aY_i'' + bY_i' + cY_i = g_i(t) \quad (***)$$

The method of undetermined coefficients only works if g_i is an exponential, polynomial, sine or cosine, or a multiplication of these function.

The proof of this theorem is explained in page 139 of your book. Given $g_i(t)$, the theorem gives the form of $Y_i(t)$ that guarantees a solution for the different constants. There is a summary of the method in page 138, which I explained in class with multiple examples.

The particular solution of $ay'' + by' + cy = g_i(t)$.

$g_i(t)$	$Y_i(t)$
$P_n(t) = a_0 t^n + a_1 t^{n-1} + \dots + a_n$	$t^s (A_0 t^n + A_1 t^{n-1} + \dots + A_n)$
$P_n(t) e^{\alpha t}$	$t^s (A_0 t^n + A_1 t^{n-1} + \dots + A_n) e^{\alpha t}$
$P_n(t) e^{\alpha t} \sin \beta t$ or $P_n(t) e^{\alpha t} \cos \beta t$	$t^s \left[(A_0 t^n + A_1 t^{n-1} + \dots + A_n) e^{\alpha t} \cos \beta t \right.$ $\left. + (B_0 t^n + B_1 t^{n-1} + \dots + B_n) e^{\alpha t} \sin \beta t \right]$

s is the smallest non-negative integer ($s=0, 1, \text{ or } 2$) that will ensure that no term in $Y_i(t)$ is a solution of the corresponding homogeneous eq.

Ex: Determine a suitable form for $Y(t)$ if the method of undetermined coefficients is to be used (do not solve the equation).

$$y'' + 3y' = \underbrace{2t^4}_{g_1} + \underbrace{t^2 e^{-3t}}_{g_2} + \underbrace{\sin 3t}_{g_3}$$

$$y'' + 3y' = 0$$

$$r^2 + 3r = 0 \quad r(r+3) = 0 \quad r_1 = 0, r_2 = -3$$

$$y_H(t) = C_1 + C_2 e^{-3t}$$

$$Y(t) = t (A_0 t^4 + A_1 t^3 + A_2 t^2 + A_3 t + A_4)$$

$$+ t (B_0 t^2 + B_1 t + B_2) e^{-3t}$$

$$+ D \sin 3t + E \cos 3t$$

Ex: Find the form of Y (do not solve the equation):

$$y'' + y = t(1 + \sin t)$$

We have:

$$y'' + y = t + t \sin t = g_1(t) + g_2(t)$$

$$y'' + y = 0$$

$$r^2 + 1 = 0 \quad r = \pm i$$

$$y_H(t) = C_1 \cos t + C_2 \sin t$$

$$Y(t) = \underbrace{A_0 t + A_1}_{Y_1(t)} + t \underbrace{[(B_0 t + B_1) \sin t + (D_0 t + D_1) \cos t]}_{Y_2(t)}$$

Ex: Find the form of $Y(t)$ (do not solve the equation).

$$y'' + 9y = t^2 e^{3t} + 6$$

$$y'' + 9 = 0, \quad r^2 + 9 = 0 \quad r = \pm 3i$$

$$y_H(t) = C_1 \cos 3t + C_2 \sin 3t$$

$$Y(t) = (At^2 + Bt + C)e^{3t} + D$$

Ex: Find the general solution to:

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$$y'' + 2y' + y = 2e^{-t}$$

$$y(t) = y_H(t) + Y(t),$$

where $y_H(t)$ is the general solution of:

$$y'' + 2y' + y = 0$$

$$r^2 + 2r + 1 = 0$$

$$(r+1)^2 = 0, \quad r = -1, \quad \text{repeated root}$$

$$\Rightarrow y_H(t) = c_1 e^{-t} + c_2 t e^{-t}. \quad (\perp)$$

Following the theorem:

$$Y(t) = At^2 e^{-t}$$

Note: if you choose $Y(t) = Ae^{-t}$, then we

have:

$$Y'' + 2Y' + Y = 0 \neq 2e^{-t},$$

because Ae^{-t} is a solution to the homogeneous equation (see (\perp) above).

If you choose $Y(t) = At e^{-t}$, the same thing happens:

$$Y'' + 2Y' + Y = 0 \neq 2e^{-t},$$

because $At e^{-t}$ solves the homogeneous equation.

Hence, the correct form is:

$$Y(t) = At^2 e^{-t}.$$

$$Y(t) = At^2 e^{-t}$$

$$Y'(t) = 2At e^{-t} - At^2 e^{-t}$$

$$Y''(t) = 2A e^{-t} - 2At e^{-t} - 2At e^{-t} + At^2 e^{-t}$$
$$= 2A e^{-t} - 4At e^{-t} + At^2 e^{-t}$$

We plug:

$$Y''(t) + 2Y' + Y = 2A e^{-t} - 4At e^{-t} + At^2 e^{-t}$$
$$+ 4At e^{-t} - 2At^2 e^{-t} + At^2 e^{-t}$$
$$= 2A e^{-t} = 2e^{-t}$$

Hence $A = 1$

$$\Rightarrow Y(t) = t^2 e^{-t}$$

\Rightarrow The general solution of $y'' + 2y' + y = 2e^{-t}$ is:

$$y(t) = y_H(t) + Y(t)$$

$$y(t) = c_1 e^{-t} + c_2 t e^{-t} + t^2 e^{-t}$$

Ex: Find the general solution of:

$$y'' + 2y' = \underbrace{3}_{g_1} + \underbrace{4 \sin 2t}_{g_2}$$

$$y'' + 2y' = 0 \quad r^2 + 2r = 0 \quad r(r+2) = 0$$
$$r_1 = 0, r_2 = -2$$

$$\Rightarrow y_H(t) = c_1 e^{0t} + c_2 e^{-2t} = c_1 + c_2 e^{-t}$$

We have:

$$Y(t) = At + B \sin 2t + C \cos 2t$$

$$\Rightarrow Y'(t) = A + 2B \cos 2t - 2C \sin 2t$$

$$Y''(t) = -4B \sin 2t - 4C \cos 2t$$

We plug:

$$Y'' + 2Y' = -4B \sin 2t - 4C \cos 2t + 2A + 4B \cos 2t - 4C \sin 2t = 3 + 4 \sin 2t$$

Hence:

$$2A + (-4B - 4C) \sin 2t + (4B - 4C) \cos 2t = 3 + 4 \sin 2t$$

$$\Rightarrow 2A = 3 \Rightarrow A = 3/2$$

$$-4B - 4C = 4$$

$$4B - 4C = 0 \Rightarrow B = C$$

$$\Rightarrow -8B = 4 \Rightarrow B = -1/2 = C$$

Hence:

$$Y(t) = \frac{3}{2}t - \frac{1}{2} \sin 2t - \frac{1}{2} \cos 2t$$

The general solution of $y'' + 2y' = 3 + 4 \sin 2t$ is:

$$y(t) = y_H(t) + Y(t)$$

$$y(t) = C_1 + C_2 e^{-2t} + \frac{3}{2}t - \frac{1}{2} \sin 2t - \frac{1}{2} \cos 2t$$

Ex: Find the general solution of:

$$y'' - 2y' - 3y = -3te^{-t}$$

$$y'' - 2y' - 3y = 0$$

$$r^2 - 2r - 3 = 0$$

$$(r-3)(r+1) = 0$$

$$r_1 = 3 \quad r_2 = -1$$

$$y_H(t) = c_1 e^{3t} + c_2 e^{-t}$$

$$Y(t) = t(At + B)e^{-t}$$

by theorem for the method of undetermined coefficient we need to multiply by t.

$$Y(t) = (At^2 + Bt)e^{-t}$$

$$Y'(t) = (2At + B)e^{-t} - (At^2 + Bt)e^{-t}$$

$$Y''(t) = 2Ae^{-t} - (2At + B)e^{-t} - (2At + B)e^{-t} + (At^2 + Bt)e^{-t}$$
$$= 2Ae^{-t} - 2(2At + B)e^{-t} + (At^2 + Bt)e^{-t}$$

We plug:

$$Y''(t) - 2Y' - 3Y = 2Ae^{-t} - 2(2At + B)e^{-t} + \cancel{(At^2 + Bt)e^{-t}} - 2(2At + B)e^{-t} + \cancel{2(At^2 + Bt)e^{-t}} - 3\cancel{(At^2 + Bt)e^{-t}}$$
$$= 2Ae^{-t} - 4(2At + B)e^{-t} = -3te^{-t}$$

We need:

$$2Ae^{-t} - 8At e^{-t} - 4B e^{-t} = -3t e^{-t}$$

$$\Rightarrow (2A - 4B)e^{-t} - 8At e^{-t} = -3t e^{-t}$$

Hence:

$$2A - 4B = 0$$

$$-8A = -3, \quad A = 3/8$$

$$\Rightarrow 4B = 2A \quad \Rightarrow B = \frac{1}{2}A = \frac{1}{2}\left(\frac{3}{8}\right) = \frac{3}{16}$$

We found:

$$Y(t) = \left(\frac{3}{8}t^2 + \frac{3}{16}t\right)e^{-t}$$

The general solution of $y'' - 2y' - 3y = -3te^{-t}$ is:

$$y(t) = y_H(t) + Y(t)$$

$$y(t) = c_1 e^{3t} + c_2 e^{-t} + \left(\frac{3}{8}t^2 + \frac{3}{16}t\right)e^{-t}$$