

Thm: Let $f \in L^1_{loc}(a,b)$. Then

$g = f$ λ -almost everywhere, $\Leftrightarrow f' = \mu$
 for some $g \in BV[a,b]$ $|\mu|(a,b) < \infty$
 (f' is the distributional derivative of f)

Proof: \Rightarrow Assume $f = g$ λ -almost everywhere and $g \in BV([a,b])$. Then

$g = g_1 - g_2$, g_1, g_2 non-decreasing
 (WLOG assume g_1, g_2 right continuous)

Let T_1 be the distribution corresponding to g_1 . Thus:

$$T_1(\varphi) = \int_a^b g_1(x) \varphi(x) d\lambda(x)$$

and:

$$T_1'(\varphi) = -T_1(\varphi')$$

$$= - \int_a^b g_1(x) \varphi'(x) d\lambda(x); \text{ Lebesgue integral}$$

$$= - \int_a^b g_1(x) \varphi'(x) dx; \text{ Riemann integral.}$$

$$= - \int_a^b g_1(x) d\varphi; \text{ Riemann-Stieltjes integral; exercises 6.17, 6.18, 6.19 (Ziemer-Torres book).}$$

$$\therefore T_1'(\psi) = - \int_a^b g_1(x) d\psi;$$

$$d\psi = \psi' dx$$

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Riemann-Stieltjes
integral.

$$= \int_a^b \psi dg_1;$$

Exercises 6.20
Integration by parts
for Riemann-Stieltjes
integrals.

$$= \int_a^b \psi(x) g_1'(x) dx;$$

$$dg_1 = g_1' dx.$$

See for example
Rudin's book,
Chapter 6,
Theorem 6.17

$$= \int_a^b \psi(x) g_1'(x) d\lambda(x)$$

$$= \int_a^b \psi(x) d\lambda_{g_1};$$

exercise 6.21:
Riemann-Stieltjes
and Lebesgue-
Stieltjes
integrals are
in agreement.

(A) $\therefore T_1'(\psi) = \int_a^b \psi d\lambda_{g_1}$
In the same way:

$$T_2'(\psi) = \int_a^b \psi d\lambda_{g_2}, \quad \psi \in \mathcal{D}(a,b).$$

Hence:

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If T_g is the distribution corresponding to g ; since $T_g = T_1 - T_2$ then:

$$T_g' = T_1' - T_2' = \lambda g_1 - \lambda g_2; \text{ by (A)}$$

Note: If g_1, g_2 are not right continuous, then by Problem 7.10 (see also Theorem 61.2 and Problem 3.62), we can redefine g_1, g_2 to \tilde{g}_1, \tilde{g}_2 , such that $g_1 = \tilde{g}_1$, $g_2 = \tilde{g}_2$ almost everywhere and:

\tilde{g}_1, \tilde{g}_2 are non-decreasing, and right continuous.

Then:

$\tilde{g} := \tilde{g}_1 - \tilde{g}_2$ is of bounded variation (since any non-decreasing function is of bounded variation, \tilde{g}_1, \tilde{g}_2 are BV and hence \tilde{g} is BV).

$\therefore f = g = \tilde{g}$ almost everywhere, with $g, \tilde{g} \in BV$.

$$T_f = T_g = T_{\tilde{g}} = \lambda g_1 - \lambda g_2 = \lambda \tilde{g}_1 - \lambda \tilde{g}_2$$

← Suppose now that:

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$$f' = \mu ; \text{ i.e.}$$

$$-\int_a^b f \psi' d\lambda = \int_a^b \psi d\mu, \quad \forall \psi \in \mathcal{D}(a,b),$$

where:

μ is a signed measure $|\mu|(a,b) < \infty$

Then:

$$\mu = \mu_1 - \mu_2, \quad \mu_1, \mu_2 \text{ non-negative measures}$$

Define:

$$f_i(x) = \mu_i((-\infty, x]), \quad i=1,2$$

(extend μ_i by $\mu_i(\mathbb{R} \setminus (a,b)) = 0$).

(f_i are non-decreasing and right continuous)

∴ Theorem 96.1 \Rightarrow

$$\mu_i = \lambda_{f_i} \quad \left(\text{on all Borel sets} \right), \quad \lambda_{f_i} \text{ is the Lebesgue-Stieltjes measure}$$

$$\therefore T'_{f_i}(\psi) = -T_{f_i}(\psi') = -\int_a^b f_i \psi' d\lambda = \int_a^b \psi d\lambda_{f_i} = \int_a^b \psi d\mu_i$$

Define

$$\boxed{g := f_1 - f_2}$$

$$g \text{ is BV and } T'_g = T'_{f_1} - T'_{f_2} = \mu_1 - \mu_2 = \mu$$

Hence:

$$T_f' = \mu$$

$$T_g' = \mu$$

$$\therefore (T_f - T_g)' = 0$$

$$\therefore T_f = T_g + K$$

$$\therefore \int_a^b f \varphi d\lambda = \int_a^b g \varphi d\lambda + \int_a^b K \varphi d\lambda$$

$$\therefore \int_a^b (f - g - K) \varphi d\lambda = 0, \quad \forall \varphi \in \mathcal{D}(a, b)$$

$$\therefore f = g + K \text{ } \lambda\text{-almost everywhere}$$

Since $g + K$ is BV we conclude
the f is equivalent to a BV function.

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• Note: If $f = g$ λ -almost everywhere

Then $T'_f = T'_g$,

where T_f, T_g are the distributions corresponding to f and g respectively.

Def: The essential variation of a function f defined on (a, b) is:

$$\text{ess } V_a^b f = \sup \left\{ \sum_{i=1}^k |f(t_{i+1}) - f(t_i)| \right\}$$

where the supremum is taken over all finite partitions $a < t_1 < \dots < t_{k+1} < b$ such that each t_i is a point of approximate continuity of f .

Note: If $f = g$ λ -almost everywhere

Then $\text{ess } V_a^b f = \text{ess } V_a^b g$

Def: Let μ be a signed finite Radon measure, in the open set Ω .
The norm of μ , is defined as:

$$\|\mu\| := |\mu|(\Omega)$$

We have:

Thm 1: Suppose $f \in L^1(a,b)$. Then:

$f' = \mu$ (in the sense of distributions), $|\mu|(a,b) < \infty$ \iff $\text{ess } \int_a^b f < \infty$

Moreover:

$$\|f'\| = |\mu|(a,b) = \text{ess } \int_a^b f$$

The proof of this Theorem uses the fact that, if μ is a signed finite measure in Ω , then:

$$|\mu|(\Omega) = \sup \left\{ \int_{\Omega} \varphi d\mu : \varphi \in C_c(\Omega), |\varphi| \leq 1 \right\} \quad (1)$$

(1) is clear from the proof of RRT3, Local & Global version. However, we present again the proof next:

Lemma 1: Let μ be a (signed)

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finite Radon measure in a set

$E \subset \mathbb{R}^n$. Then, for every open set $\Omega \subset E$:

$$|\mu|(\Omega) = \sup \left\{ \int_{\Omega} f d\mu : f \in C_c(\Omega), |f| \leq 1 \right\}.$$

Note: If $E \subset \mathbb{R}^n$, we consider E as a metric space endowed with the induced topology from \mathbb{R}^n . Thus, $\Omega \subset E$ is open in the relative-topology

Proof:

Since $\mu \ll |\mu|$, Radon-Nikodym Theorem yields:

$\exists f \in L^1(E)$ s.t. $\mu = f|\mu|$. That is:

$$\mu(A) = \int_A f d|\mu|, \quad A \subset E \text{ measurable.}$$

Then:

$$|\mu|(A) = \int_A |f| d|\mu|, \quad A \subset E$$

and this implies $|f(x)| = 1, |\mu|$ -a.e. x .

We have therefore:

$$\boxed{\mu = f|\mu|, \quad |f| = 1 \text{ a.e. } x} \quad (2)$$

Choose now a sequence
 $\{f_k\} \subset C_c(\Omega)$ such that:

$$f_k(x) \rightarrow f(x), \quad |f_k| \text{ a.e. } x, \quad |f_k| \leq 1.$$

(We can choose f_k by applying Lusin's Theorem to f).

Since $|\mu|(\Omega) < \infty$, we can apply the Lebesgue Dominated convergence Theorem:

$$\lim_{k \rightarrow \infty} \int_{\Omega} f_k d\mu = \lim_{k \rightarrow \infty} \int_{\Omega} f_k \cdot f d|\mu|; \text{ by (2)}$$

$$= \int_{\Omega} f \cdot f d|\mu|$$

$$= \int_{\Omega} f^2 d|\mu|$$

$$= \int_{\Omega} d|\mu|; \text{ by (2)}$$

$$= |\mu|(E)$$

Therefore; for every $\epsilon > 0$, $\exists N(\epsilon)$ s.t.

$$|\mu|(E) \leq \int_{\Omega} f_k d\mu + \epsilon, \quad \forall k \geq N(\epsilon)$$

$$\leq \sup \left\{ \int_{\Omega} f d\mu, f \in C_c(\Omega), |f| \leq 1 \right\} + \epsilon$$

$$\therefore \boxed{|\mu|(E) \leq \sup \left\{ \int_{\Omega} f d\mu, f \in C_c(\Omega), |f| \leq 1 \right\}} \quad (3)$$

(since ϵ is arbitrary)

For the reverse inequality:

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$$\int_{\Omega} f d\mu \leq \int_{\Omega} |f| d|\mu| \\ \leq \|f\|_{\infty} |\mu|(\Omega)$$

$$\therefore \int_{\Omega} f d\mu \leq |\mu|(\Omega), \quad f \in C_c(\Omega), \quad |f| \leq 1$$

Hence:

$$\boxed{\sup \left\{ \int_{\Omega} f d\mu : f \in C_c(\Omega), |f| \leq 1 \right\} \leq |\mu|(\Omega)} \quad (4)$$

Actually, notice that:

$$|\mu|(\Omega) = \sup \left\{ \int_{\Omega} f d\mu : f \in C_c^{\infty}(\Omega), |f| \leq 1 \right\};$$

Since $C_c^{\infty}(\Omega)$ is dense in $C_c(\Omega)$.

Also:

$$|\mu|(\Omega) = \sup \left\{ \int_{\Omega} f d\mu : f \in C_0(\Omega), |f| \leq 1 \right\} \\ = \sup \left\{ \int_{\Omega} f d\mu : f \in C(\Omega), |f| \leq 1 \right\}$$

In fact, for $C_0(\Omega)$ or $C(\Omega)$ we can prove (3) and (4) following

the same proof as in Lemma 1;

$$\text{since: } |\mu|(E) \leq \int_{\Omega} f_k d\mu + \varepsilon, \quad \forall k \geq N(\varepsilon) \\ \leq \sup \left\{ \int_{\Omega} f d\mu, f \in C_0(\Omega), |f| \leq 1 \right\} + \varepsilon \\ \leq \sup \left\{ \int_{\Omega} f d\mu, f \in C(\Omega), |f| \leq 1 \right\} + \varepsilon$$

Alternative definitions
of functions of bounded
variation (BV) in one-dimension.

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Let $f \in L^1(a,b)$. We say that
 $f \in BV(a,b)$ iff:

(a) $\text{ess } V_a^b f < \infty$
or

(b) The distributional derivative
of f is a finite Radon
measure in (a,b)

or

(c) $\text{Sup} \left\{ \int_a^b f \varphi' d\lambda(x) : \varphi \in C_c^1(a,b), |\varphi| \leq 1 \right\} < \infty$

We can extend the definition (c)
to several variables and define the
space of functions of bounded variation
in an open set $\Omega \subset \mathbb{R}^n$:

$$BV(\Omega).$$

BV functions in \mathbb{R}^n .

Def: A function $f \in L^1(\Omega)$, Ω open, has bounded variation in Ω if

$$\sup \left\{ \int_{\Omega} f \operatorname{div} \varphi \, d\lambda(x) : \varphi \in C_c^1(\Omega; \mathbb{R}^n), |\varphi| \leq 1 \right\} < \infty$$

We write

$$BV(\Omega)$$

to denote the space of functions of bounded variation.

Def: A function $f \in L^1_{loc}(\Omega)$ has locally bounded variation in Ω if for each open set $V \subset\subset \Omega$,

$$\sup \left\{ \int_V f \operatorname{div} \varphi \, d\lambda(x) : \varphi \in C_c^1(V; \mathbb{R}^n), |\varphi| \leq 1 \right\} < \infty.$$

We write

$$BV_{loc}(\Omega)$$

to denote the space of such functions.

Thm: Structure theorem for BV_{loc} functions:

Let $f \in BV_{loc}(\Omega)$. Then there exists a Radon measure μ on Ω and a μ -measurable function $\sigma: \Omega \rightarrow \mathbb{R}^n$ such that:

(i) $|\sigma(x)| = 1$ μ -a.e., and

(ii) $\int_{\Omega} f \operatorname{div} \varphi \, d\lambda(x) = - \int_{\Omega} \varphi \cdot \sigma \, d\mu$

Moreover, (ii) asserts that the weak first partial derivatives of a BV function are Radon measures.

Proof:

Use the RRT3, local version, to prove (i) and (ii). Then show that (ii) implies that

$$\frac{\partial f}{\partial x_i} = \tilde{\mu}_i, \quad i=1, \dots, n,$$

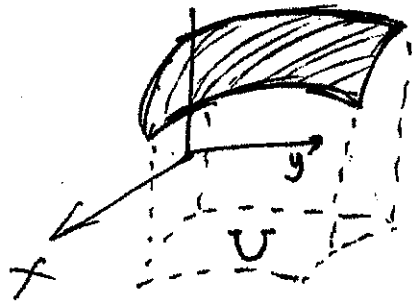
where $|\tilde{\mu}_i|(V) < \infty$, for each

$V \subset\subset \Omega$.

Complete the details of this proof from Evans' book: "Fine properties of functions..."

Ex 3: Surface area of
a graph

Let $g: \mathbb{R}^2 \rightarrow \mathbb{R}$ Lipschitz.



Define:

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$f(x, y) = (x, y, g(x, y)), \quad f \text{ is 1-1 on } U$$

Then:

$$df(x, y) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix}_{3 \times 2}$$

The Binet-Cauchy Formula (Theorem 4, "Measure Theory and fine properties of functions")

implies:

$$(Jf)^2 = \text{sum of squares of } (2 \times 2)\text{-subdeter-}$$

minants

$$= 1 + \left(\frac{\partial g}{\partial x}\right)^2 + \left(\frac{\partial g}{\partial y}\right)^2$$

$$|Jf(x,y)| = \sqrt{1 + |\nabla g(x,y)|^2}$$

From Area Formula:

$$\begin{aligned} \int_U g(\nu) d\mathcal{H}^2 &= \int_U |Jf(x,y)| dx dy \\ &= \int_U \sqrt{1 + |\nabla g|^2} \end{aligned}$$

$$\therefore \boxed{\mathcal{H}^2(U) = \text{Area of } U = \int_U \sqrt{1 + |\nabla g|^2}}$$

Recall the Plateau Problem:

Minimize $\int_U \sqrt{1 + |\nabla g|^2}$, over all

function g such that $g = \gamma$ on ∂U .

If g minimizes area, then g satisfies the minimal surface equation:

$$\boxed{\operatorname{div} \left(\frac{\nabla g}{(1 + |\nabla g|^2)^{1/2}} \right) = 0. \quad (*)}$$

Indeed, Let $\alpha(t) = \int_U \sqrt{1 + |\nabla(g + t\varphi)|^2} dx dy$

$$\therefore \alpha'(t) = \int_U \frac{1}{2} (1 + |\nabla(g + t\varphi)|^2)^{-1/2} \cdot \frac{d}{dt} (1 + (g_x + t\varphi_x)^2 + (g_y + t\varphi_y)^2)$$

$$\therefore \alpha'(t) = \int_U \frac{1}{2} (1 + |\nabla(g + t\varphi)|^2)^{-1/2} [2(g_x + t\varphi_x)\varphi_x + 2(g_y + t\varphi_y)\varphi_y]$$

$$\Rightarrow \alpha'(0) = \int_U (1 + |\nabla g|^2)^{-1/2} (\nabla g \cdot \nabla \varphi) dx dy \Rightarrow \int_U \operatorname{div} \left(\frac{\nabla g}{\sqrt{1 + |\nabla g|^2}} \right) \varphi = 0 \quad \forall \varphi \Rightarrow (*)$$