

# Lesson 14

(14.1)

We have the following Corollary  
of the compactness theorem (theorem 2)  
proved in Lecture 13.

Corollary 1: If  $\{E_i\}_{i=1}^{\infty}$  are sets of locally finite perimeter in  $\mathbb{R}^n$  with:

$$\sup_{i \in \mathbb{N}} P(E_i; B_R) < \infty, \quad \forall R > 0$$

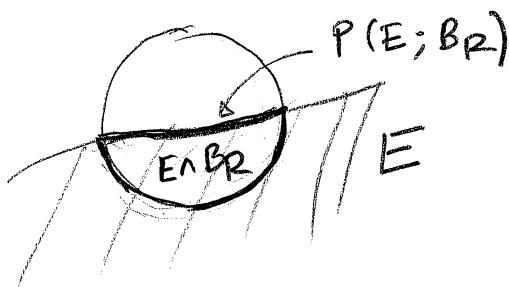
then  $\exists E$  of locally finite perimeter and a subsequence  $\{E_{i_k}\}_{k=1}^{\infty}$  such that:

$$E_{i_k} \rightarrow E \text{ in } L^1_{loc}(\mathbb{R}^n), \quad \mu_{E_{i_k}} \xrightarrow{*} \mu_E.$$

Proof:

Step one: If  $E$  is of locally finite perimeter and  $R > 0$ , then:

$$P(E \cap B_R) \leq P(E; B_R) + P(B_R).$$



- Given  $R' < R$ , let  $v_\varepsilon \in C_c^\infty(B_{R'})$   
be such that:

$0 \leq v_\varepsilon \leq 1$ ,  $v_\varepsilon \rightarrow \chi_{B_{R'}}$  in  $L^1(\mathbb{R}^n)$ ,  $\int_{\mathbb{R}^n} |\nabla v_\varepsilon| \rightarrow P(B_{R'})$ .

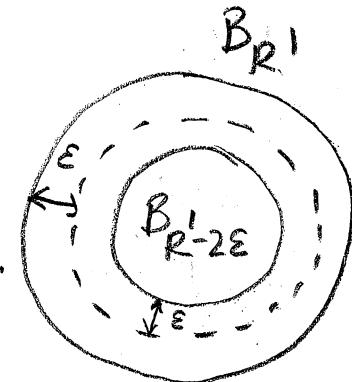
14.2

For example, we can define:

$$\tilde{v}_\varepsilon(x) = 1 - \min_{\varepsilon} \left\{ \text{dist}(x, \bar{B}_{R'-2\varepsilon}), \varepsilon \right\}$$

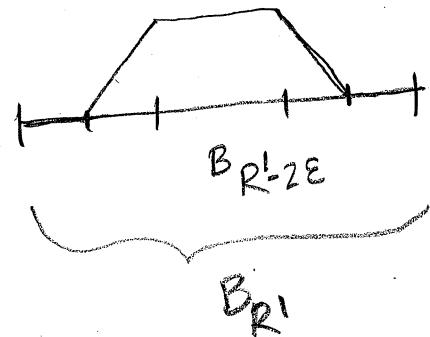
$\tilde{v}_\varepsilon$  is Lipschitz. Let  $d(x) = \text{dist}(x, \bar{B}_{R'-2\varepsilon})$ .

$$|\nabla \tilde{v}_\varepsilon(x)| \leq \frac{1}{\varepsilon} \text{ for } \mathcal{L}^n\text{-a.e. } x \in \mathbb{R}^n$$



By coarea formula (we will prove it next lecture) we have:

$$\int_{\mathbb{R}^n} |\nabla \tilde{v}_\varepsilon(x)| dx = \frac{1}{\varepsilon} \int_0^{\varepsilon} |\nabla d(x)|$$



$$= \frac{1}{\varepsilon} \int_0^\varepsilon x^{n-1}(\delta^{-1}(t)) dt$$

$$= \frac{1}{\varepsilon} \cdot \varepsilon x^{n-1}(\delta^{-1}(t_\varepsilon)), \quad 0 < t_\varepsilon < \varepsilon$$

$$= x^{n-1}(\delta^{-1}(t_\varepsilon)), \quad \text{some } 0 < t_\varepsilon < \varepsilon.$$

We have  $\delta^{-1}(t_\varepsilon) \subset B_{R'-\varepsilon} \setminus \bar{B}_{R'-2\varepsilon}$  and:

$$x^{n-1}(\delta^{-1}(t_\varepsilon)) \rightarrow x^{n-1}(\partial B_{R'}) \text{ as } \varepsilon \rightarrow 0.$$

We can convolve  $\tilde{v}_\varepsilon$  to produce a smooth function  $v_\varepsilon$ . Clearly,  $0 \leq v_\varepsilon \leq 1$  and  $v_\varepsilon \rightarrow \chi_{B_{R'}}$  in  $L^1(\mathbb{R}^n)$  and  $\int_{\mathbb{R}^n} |\nabla v_\varepsilon| \rightarrow P(B_{R'})$  (A)

14.3

- Now, define  $u_\varepsilon = \chi_E * \rho_\varepsilon$

By Remark, Lecture 13 we have:

$$\int_{\mathbb{R}^n} |\nabla u_\varepsilon| \rightarrow P(E); \text{ moreover, } u_\varepsilon \rightarrow \chi_E \text{ in } L^1(\mathbb{R}^n) \text{ (B)}$$

We use (A) and (B) to compute, for every  $T \in C_c^1(\mathbb{R}^n, \mathbb{R}^n)$ ,  $|T| \leq 1$ :

$$\int_{E \cap B_{R'}} \operatorname{div} T = \int_{\mathbb{R}^n} \chi_{E \cap B_{R'}} \operatorname{div} T(x) dx$$

$$= \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^n} u_\varepsilon v_\varepsilon \operatorname{div} T(x) dx, \quad \text{Since } u_\varepsilon v_\varepsilon \rightarrow \chi_{E \cap B_{R'}} \text{ in } L^1(\mathbb{R}^n)$$

$$= - \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^n} T \cdot \nabla (u_\varepsilon v_\varepsilon) dx$$

$$\leq \lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^n} |\nabla (u_\varepsilon v_\varepsilon)| dx$$

$$\leq \limsup_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^n} |\nabla v_\varepsilon| + \int_{\mathbb{R}^n} |\nabla u_\varepsilon| ; \quad \begin{aligned} & \text{since } 0 \leq u_\varepsilon \leq 1 \\ & \nabla(u_\varepsilon v_\varepsilon) = u_\varepsilon \nabla v_\varepsilon + v_\varepsilon \nabla u_\varepsilon \end{aligned}$$

$$= P(B_{R'}) + \limsup_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^n} v_\varepsilon |\nabla u_\varepsilon| ; \quad \text{by (A)}$$

$$= P(B_{R'}) + \limsup_{\varepsilon \rightarrow 0} \int_{B_{R'}} |\nabla u_\varepsilon| ; \quad \operatorname{spt} v_\varepsilon \subset B_{R'}$$

$$\leq P(B_{R'}) + P(E, \bar{B}_{R'}); \quad \begin{aligned} & \text{since } \|\nabla u_\varepsilon\|_f^n \xrightarrow{\star} \|u_E\|_f^n \\ & \text{and hence} \end{aligned}$$

$$\leq P(B_R) + P(E, B_R) \quad \limsup_{\varepsilon \rightarrow 0} \int_{B_{R'}} |\nabla u_\varepsilon| \leq \|u_E\|_f(\bar{B}_{R'})$$

Taking sup over all  $T$  gives:

(14.4)

$$P(E \cap B_{R'}) \leq P(B_R) + P(E, B_R)$$

Since  $E \cap B_{R'} \rightarrow E \cap B_R$  in  $L'_{loc}(\mathbb{R}^n)$  as  $R' \rightarrow R$ ,  
by lower semicontinuity:

$$P(E, B_R) \leq \liminf_{R' \rightarrow R} P(E \cap B_{R'}) \leq P(B_R) + P(E, B_R)$$

We conclude step 1. ■

Step two:

We apply the compactness theorem (Theorem 2)  
proved in Lecture 13 to the sequence:

$$\{E_i \cap B_j\}_{i=1}^{\infty}, \text{ fixed } j$$

By step 1:  $P(E_i \cap B_j) \leq P(B_j) + P(E_i, B_j) \leq M, \forall i^0$   
 $\Rightarrow \exists \{E_{i_\ell}\}_{\ell=1}^{\infty}$  and  $F_j \subset B_j$  such that  $E_{i_\ell} \rightarrow F_j$  in  $L'(\mathbb{R}^n)$

Apply the same argument to  $\{E_{i_\ell}\}_{\ell=1}^{\infty}$  and  $B_{j+1}$  to  
obtain another subsequence  $\{E_{i_{\ell_p}}\}_{p=1}^{\infty}$  and  $F_{j+1} \subset B_{j+1}$  such  
that  $E_{i_{\ell_p}} \rightarrow F_{j+1}$ . Continue in this way and then  
take the diagonal of sets, say  $\{E_{i_k}\}_{k=1}^{\infty}$ . Then:

$F_j \subset F_{j+1}$  (up to null sets) and  $E_{i_k} \rightarrow E := \bigcup_{j=1}^{\infty} F_j$  in  $L'_{loc}(\mathbb{R}^n)$ , as  $k \rightarrow \infty$ .

By lower semicontinuity,  $E$  is of locally  
finite perimeter and  $\mu_{E_{i_k}} \xrightarrow{*} \mu_E$ . (see  
lower semicontinuity theorem in Lecture 12, Page 12.9) ■.

14.5

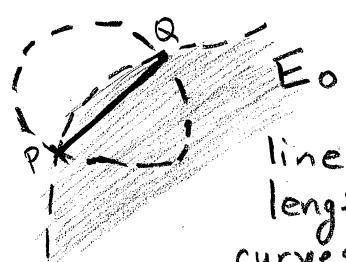
## Existence of minimizers in geometric variational problems:

Problem 1: Let  $A \subset \mathbb{R}^n$  open and  $E_0 \subset \mathbb{R}^n$  be of finite perimeter. The Plateau-type problem in  $A$  with boundary data  $E_0$  amounts to minimizing  $P(E)$  among those sets of finite perimeter  $E$  that coincide with  $E_0$  outside  $A$ . More precisely:

$$\delta(A, E_0) = \inf \{P(E) : E \setminus A = E_0 \setminus A\}. \quad (*)$$

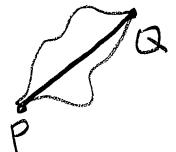
- Roughly speaking,  $E \setminus A = E_0 \setminus A$  means we impose  $E_0 \cap \partial A$  as a "boundary condition" for the admissible sets  $E$  in  $(*)$ .
- The set  $A$  may act as an obstacle.
- In general, we do not expect uniqueness.

Ex 1:



line minimizes length among all curves with fixed  $P$  and  $Q$

Ex 2:



The curve that touches the obstacle minimizes length among all competitors.

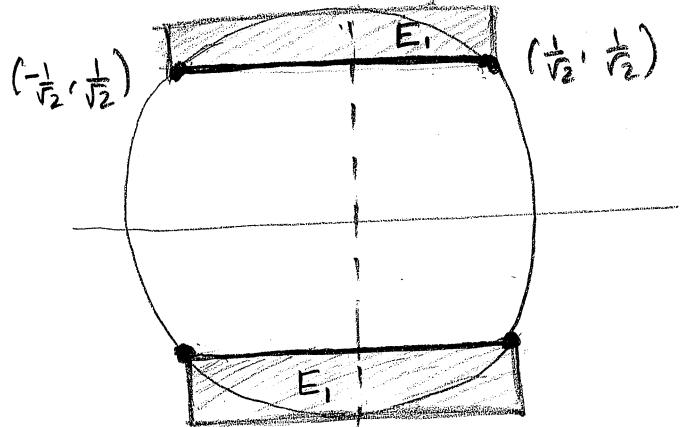
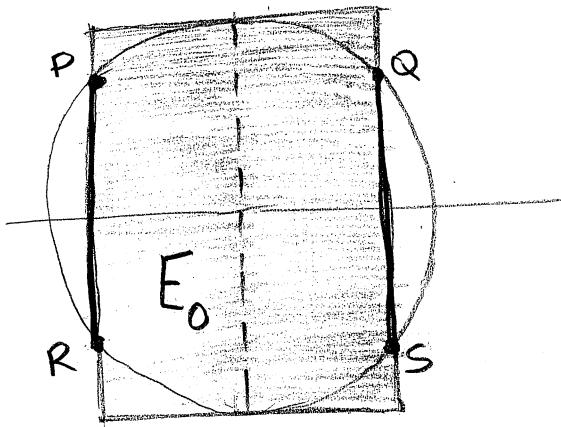
Ex: Non-uniqueness.

(14.6)

Let  $E_0 = \{x \in \mathbb{R}^2 : |x_2| < 1, |x_1| < \frac{1}{\sqrt{2}}\}$

$A = B(0, 1)$

$E_1 = E_0 \cap \{x \in \mathbb{R}^2 : \frac{1}{\sqrt{2}} < x_2 < 1\}$



$$P = \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), R = \left(-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right), Q = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), S = \left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right)$$

Both  $E_0$  and  $E_1$  (grey regions) are minimizers.

Proposition 1 (Existence of minimizers for the Plateau-type problem), Let  $A \subset \mathbb{R}^n$  bounded open,  $E_0 \subset \mathbb{R}^n$  set of finite perimeter in  $\mathbb{R}^n$ . Then, there exists a set of finite perimeter  $E$  such that :

$$E \setminus A = E_0 \setminus A \text{ and } P(E) \leq P(F) \quad \forall F, F \setminus A = F \setminus E_0$$

In particular  $E$  is a minimizer in the variational problem 1.

## Proof of Proposition 4 :

14.7

$E_0$  is itself admissible  $\Rightarrow \gamma := \gamma(A, E_0) < \infty$

Let  $\{E_i\}_{i=1}^{\infty}$  be a minimizing sequence;  
that is:

$$P(E_i) \rightarrow \gamma, \quad P(E_i) \leq P(E_0), \quad E_i \setminus A = E_0 \setminus A.$$

Define:

$$M_i := E_i \Delta E_0 = (E_i \setminus E_0) \cup (E_0 \setminus E_i)$$

Applying Lemma 1, Lecture 13 ( $P(E \cap F, A) + P(E \cap F, A) \leq P(E, A) + P(F, A)$ ), we have:

$$\begin{aligned} P(E_i \Delta E_0) &= P(E_i \setminus E_0) + P(E_0 \setminus E_i) \\ &= P(E_i \cap E_0^c) + P(E_0 \cap E_i^c) \\ &\leq P(E_i) + P(E_0^c) + P(E_0) + P(E_i^c); \quad \text{here } A = \mathbb{R}^n \end{aligned}$$

$$\begin{aligned} &= P(E_i) + P(E_0) + P(E_0) + P(E_i); \quad \text{since } \\ &\quad E \text{ loc. fin. per.} \Rightarrow \\ &\quad \mathbb{R}^n \setminus E \text{ is loc. fin. per. and} \\ &\quad P(E) = P(\mathbb{R}^n \setminus E) \\ &\leq P(E_0) + P(E_0) + P(E_0) + P(E_0) \\ &= 4 P(E_0) \end{aligned}$$

Since  $M_i \subset A$ , bounded open set, we can apply the compactness theorem (Lecture 13, Page 13-6) to obtain  $M$  such that, up to extracting a subsequence, we have  $M_i \rightarrow M$  in  $L^1(\mathbb{R}^n)$ .

Since

$$E_i = (E_0 \cup M_i) \setminus (E_0 \cap M_i)$$

14.8

and:

$$M_i \rightarrow M \text{ in } L^1(\mathbb{R}^n)$$

then:  $E_i \rightarrow E \text{ in } L^1(\mathbb{R}^n), E := (E_0 \cup M) \setminus (E_0 \cap M)$

Note that:

$$E \setminus A = E_0 \setminus A$$

and by lower semicontinuity:

$$\gamma \leq P(E) \leq \liminf_{i \rightarrow \infty} P(E_i) = \gamma$$

$\therefore \gamma = P(E)$ ,  $E$  is a minimizer.  $\blacksquare$

Problem 2: Relative isoperimetric problems. Given an open set  $A \subset \mathbb{R}^n$ , the relative isoperimetric problem in  $A$  amounts to the volume-constrained minimization of the relative perimeter in  $A$ , namely:

$$\alpha(A, m) = \inf \{P(E; A) : E \subset A, |E| = m\}$$

Note: The case  $A = \mathbb{R}^n$  is the Euclidian isoperimetric problem, which can not be studied using the Direct-Method (compactness + lower semicontinuity).

(14.9)

Problem 2 is strictly related to the study of equilibrium shapes of a liquid confined in a given container (see Chapter 19 from textbook).

Proposition 2 : (Existence of relative isoperimetric sets). Let  $A$  open bounded set of finite perimeter and  $m \in (0, |A|)$ , then  $\exists E \subset A$ , set of finite perimeter such that:

$$P(E; A) = \alpha(A, m), \quad |E| = m$$

Proof : Let  
 $E_t = A \cap \{x: x_1 < t\}$ ,  $t \in \mathbb{R}$ .  $\Rightarrow \exists t$  s.t.  
 $|E_t| = m$   
 $\therefore \alpha := \alpha(A, m) < \infty$ .

Let  $\{E_i\}$  be a minimizing sequence; that is.  
 $E_i \subset A$ ,  $|E_i| = m$ ,  $P(E_i; A) \rightarrow \alpha$

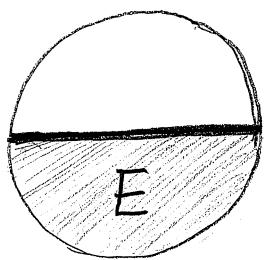
By Step one of Corollary 1 in this Lesson we have:

$$P(E_i) = P(E_i \cap A) \leq P(E_i; A) + P(A)$$

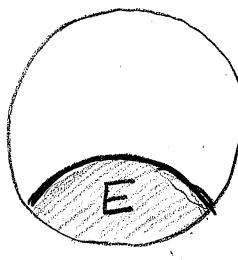
(Note: we proved this for  $A = B_2$ , the general case for  $A$  will be proved later; see Thm 16-3 in textbook).

Ex:

$$A = B, m = \frac{|B|}{2}$$

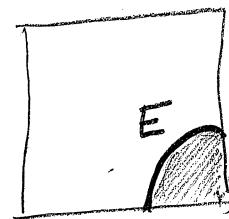


$$A = B, m < \frac{|B|}{2}$$



(14,10)

$A = Q, m$  small



Hence:

$$\sup_i P(E_i) < \infty$$

A bounded, Compactness Thm from Lecture 13  $\Rightarrow$

$\exists \{E_{i_k}\}, \exists E \subset A$  s.t.  $E_{i_k} \rightarrow E$  as  $k \rightarrow \infty$ . Also,  $|E| = \lim_{k \rightarrow \infty} |E_{i_k}| = m$ , so  $E$  is a competitor and:

$$\alpha \leq P(E; A) \leq \liminf_{k \rightarrow \infty} P(E_{i_k}; A) = \alpha$$

$\therefore \alpha = P(E; A)$  and  $E$  is a minimizer.

Problem 3: Problems involving potential energies (prescribed mean-curvature problems) arise from the interaction between perimeter and potential energy terms. Given  $g: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\pm\infty\}$  Leb. meas., we define the potential energy of  $E$  associated with  $g$  as:

$$G(E) = \int_E g(x) dx$$

$\left\{ \begin{array}{l} \text{Ex. } g = \text{gravitational} \\ \text{potential, } -\nabla g \text{ is} \\ \text{gravitational force field,} \\ \text{orthogonal to level} \\ \text{Sets of } g \end{array} \right.$

Consider the variational problem:

$$\inf \{ P(E) + G(E) : E \subset A \},$$

(14.11)

where  $A$  is open. See chapter 19 for examples of physical interest. Also, we will see later that if  $g \in C(A)$  and  $E$  is a minimizer, and  $\partial E \cap A$  is  $C^2$  then the mean curvature  $H_E$  of  $E$  is equal to  $-g$  in  $A$  (see chapter 17). For these problems, in order to apply the direct method, one needs to prove lower-semicontinuity results for  $g$ ; for example:

Proposition 3 : Let  $g: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  Leb-meas.

Assume  $g^- \in L^1(F)$ ,  $F \subset \mathbb{R}^n$  Leb-meas, and  $E_i \rightarrow E$  in  $L^1(\mathbb{R}^n)$ . Then

$$\int_{E \cap F} g(x) dx \leq \liminf_{i \rightarrow \infty} \int_{E_i \cap F} g(x) dx.$$

Proof: Let  $g = g^+ - g^-$

$$\lim_{i \rightarrow \infty} \int_{E_i \cap F} g(x) dx = \int_{E \cap F} g^-(x) dx = \lim_{i \rightarrow \infty} \int_{E_i \cap F} g^-(x) dx ; \quad g^- \in L^1(F),$$

using dominated convergence thm.

$$\int_{E \cap F} g^+(x) dx = \int_{E \cap F} \lim_{i \rightarrow \infty} g^+(x) dx$$

$$\leq \liminf_{i \rightarrow \infty} \int_{E_i \cap F} g^+(x) dx ; \quad \text{by Fatou's lemma}$$

$$\therefore \int_{E \cap F} g(x) dx = \int_{E \cap F} (g^+ - g^-) dx = \liminf_{i \rightarrow \infty} \int_{E_i \cap F} g^+ - \lim_{i \rightarrow \infty} \int_{E_i \cap F} g^-$$

$$\leq \liminf_{i \rightarrow \infty} \int_{E_i \cap F} g^+ + \lim_{i \rightarrow \infty} \int_{E_i \cap F} (-g^-) \leq \liminf_{i \rightarrow \infty} \int_{E_i \cap F} g^+ - g^- dx$$