The Loewner Equation with complex drivers

Joan Lind, Jeffrey Utley

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Outline

Properties of the LE

▶ Hulls with complex-valued driving functions $c\sqrt{1-t}, c\sqrt{t}$

• Phase transitions for $c\sqrt{1-t}$ at time 1

Further questions

Loewner Equation

$$\partial_t g_t(z) = rac{2}{g_t(z) - \lambda(t)}, \quad g_0(z) = z.$$

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$$\mathcal{K}_t = \{z \in \mathbb{H} \cup \{\lambda(0)\} : \exists s \leq t \text{ so that } g_s(z) = \lambda(s)\}.$$

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Time *t* solution is a conformal map $g_t : \mathbb{H} \setminus K_t \to \mathbb{H}$.

Extend to the entire complex plane

$$L_{t,\lambda}=K_t\cup\overline{K_t},$$

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time *t* solution $g_t : \mathbb{C} \setminus L_{t,\lambda} \to \mathbb{C}$.

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Duality Property

$$L_{t,\lambda} = iR_{t,-i\lambda(t-\cdot)}, \quad R_{t,\lambda} = iL_{t,-i\lambda(t-\cdot)}.$$

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LE with real drivers

Theorem (Marshall, Rohde, Lind) For $\lambda(t)$ real-valued and with $Lip(\frac{1}{2})$ norm below 4, L_t is a simple curve.

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We call the blue curve the upper hull and the red curve the lower hull.

LE with complex drivers: $\lambda(t) = (3+2i) + (1-i)t$



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Theorem (Tran)

There exists $\sigma > 0$ so that when $\lambda : [0, T] \to \mathbb{C}$ has Lip(1/2) norm less than σ , then $L_t = \gamma[-t, t]$ for a simple curve $\gamma : [-t, t] \to \mathbb{C}$. Moreover,

$$\gamma(t) = \lim_{y \to 0^+} g_t^{-1}(\lambda(t) + iy) \quad \text{and} \quad \gamma(-t) = \lim_{y \to 0^-} g_t^{-1}(\lambda(t) + iy).$$

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No, we have $\sigma < 3.723$ due to phase transitions for \mathbb{C} -valued $c\sqrt{1-t}$.

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Complex-valued $c\sqrt{1-t}$: phase transition image



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Complex-valued $c\sqrt{1-t}$: simple and non-simple hulls

Examples of simple and non-simple hulls at time 1:



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Dual driving function $c\sqrt{t}$

By the Duality Property, the right hull driven by $c\sqrt{1-t}$ is a rotation of the left hull driven by $-ic\sqrt{t}$.

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The concatenation property

If $\lambda(t)$ is real-valued, then fix times t, t + s and consider

 $g_t: \mathbb{H} \setminus K_{t,\lambda} \to \mathbb{H}.$

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In fact,

$$g_t(K_{t+s,\lambda} \setminus K_{t,\lambda}) = K_{s,\lambda(t+\cdot)} \setminus \{\lambda(t)\},$$

 $K_{t+s,\lambda} = K_{t,\lambda} \cup g_t^{-1}(K_{s,\lambda(t+\cdot)} \setminus \{\lambda(t)\}).$

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The concatenation property for \mathbb{C} -valued hulls

For complex-valued driving functions, the property is not so nice:

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If we had $L_{s,\lambda(t+\cdot)} \cap R_{t,\lambda} = \{\lambda(t)\}$, then the property would be the same as in the real case.

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Simple curves before time 1

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$$\gamma(t) = \lim_{y \to 0^+} g_t^{-1}(\lambda(t) + iy) \quad \text{and} \quad \gamma(-t) = \lim_{y \to 0^-} g_t^{-1}(\lambda(t) + iy).$$

On an interval $[s, t] \subset [0, 1)$, $\lambda(t) = c\sqrt{1-t}$ has $Lip(\frac{1}{2})$ norm $|c|\sqrt{t-s}$, so the theorem applies on small enough intervals.

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Define

$$\alpha = \frac{1}{2}(1 - \frac{c}{\sqrt{c^2 - 16}}).$$

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Proposition (Lind, U)

The concatenation property becomes

$$\mathcal{L}_{t+s,\lambda} = \mathcal{L}_{t,\lambda} \cup g_t^{-1}(\mathcal{L}_{s,\lambda(t+\cdot)} \setminus \{\lambda(t)\})$$

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when $Re(\alpha) \neq 0$.

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We can build up the simple curve L_t (for any t < 1) by attaching simple curves using the concatenation property.



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Phase Transitions

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$$A = rac{c + \sqrt{c^2 - 16}}{2}, \ B = rac{c - \sqrt{c^2 - 16}}{2}.$$

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When $c \in \mathbb{R}$,

$$\begin{aligned} & \operatorname{\textit{Re}}(\alpha) > 0 \implies \gamma(1) = A, \gamma(-1) = B, \\ & \operatorname{\textit{Re}}(\alpha) < 0 \implies \gamma(1) = \gamma(-1) = B. \end{aligned}$$

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Phase Transitions: continuity in c

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The maps $c \mapsto \lim_{t\to 1} \gamma_c(t)$ and $c \mapsto \lim_{t\to 1} \gamma_c(-t)$ are continuous for $c \in \mathbb{C}$ so that $Re(\alpha) \neq 0$.

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This allows us to extend the results

$$\operatorname{Re}(\alpha) > 0 \implies \gamma(1) = A, \gamma(-1) = B,$$

 $\operatorname{Re}(\alpha) < 0 \implies \gamma(1) = \gamma(-1) = B$

to \mathbb{C} , proving our criteria for simple and non-simple hulls.

Phase Transitions: 2-segment hulls

The two points added to a hull at time *t* are given by the formulas

$$\gamma(t) = \lim_{y \to 0^+} g_t^{-1}(\lambda(t) + iy) \quad \text{and} \quad \gamma(-t) = \lim_{y \to 0^-} g_t^{-1}(\lambda(t) + iy).$$

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Driving function $\lambda(t) = (1.15 + 3.31i)\sqrt{t}$



Phase Transitions: 1-segment hulls

The limit

$$\lim_{y\to 0^-} g_t^{-1}(\lambda(t) + iy)$$

does not exist when the right hull is non-simple since it includes its interior.

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Phase Transitions: 1-segment hulls

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Driving function $\lambda(t) = (2+5i)\sqrt{t}$ 5 6 4.5 5 4 3.5 4 3 3 2.5 2 2 1.5 1 0 -0.5 1.5 2.5 0 0.40.6 0.8 1.8 0 0.5 2 3 1.4

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Further Questions

Can we find a least upper bound to σ in Theorem 1.2? This research has found that σ < 3.723, but how much smaller can we get it?

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Are there always at most 2 distinct limits

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Do all hulls grow continuously? Driving functions such as λ(t) = e^{it}, t ∈ [0, 1] which intersect themselves may lead to "jumps" in growth.

Further Questions: driving function $\lambda(t) = e^{it}$



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Thank you

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