

## Lesson 2

### Linear Systems and Gaussian elimination

System of  $m$  equations in  $n$  unknowns:

$$a_{11}x_1 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$
$$a_{m1}x_1 + \dots + a_{mn}x_n = b_m$$

System is overdetermined if  $m > n$ , determined if  $m = n$ , underdetermined if  $m < n$ . In matrix form write

$$Ax = b \quad \text{where}$$

$$A = (a_{ij}) \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad b = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$$

The augmented matrix  $\tilde{A}$  is

$$\tilde{A} = \begin{pmatrix} a_{11} & \dots & a_{1n} & b_1 \\ a_{21} & \dots & a_{2n} & b_2 \\ \vdots & & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} & b_m \end{pmatrix}$$

## Elementary Row operations

There are 3 row operations:

1. Switch two rows.
2. Multiply one row by nonzero number.
3. Add multiple of a row to another row.

A is row equivalent to B if A can be obtained from B by row operations. Since row operations can be reversed, then if A is row equivalent to B it is also true that B is row equivalent to A. Write  $A \sim B$  or  $B \sim A$ .

The important fact is that if  $(A|b)$  and  $(C|d)$  are augmented matrices for two systems of equations and  $(A|b) \sim (C|d)$ , then the two systems have precisely the same solutions.

Gaussian elimination is the process of using elementary row operations on the augmented matrix to solve a system.

If  $b=0$ , the system is homogeneous and there is no need to include it in the augmented matrix since it doesn't change.

Ex.  $x_1 + 2x_2 + 3x_3 = 1$

$$4x_1 + 5x_2 + 6x_3 = 0$$

$$7x_1 + 8x_2 + 9x_3 = 1$$

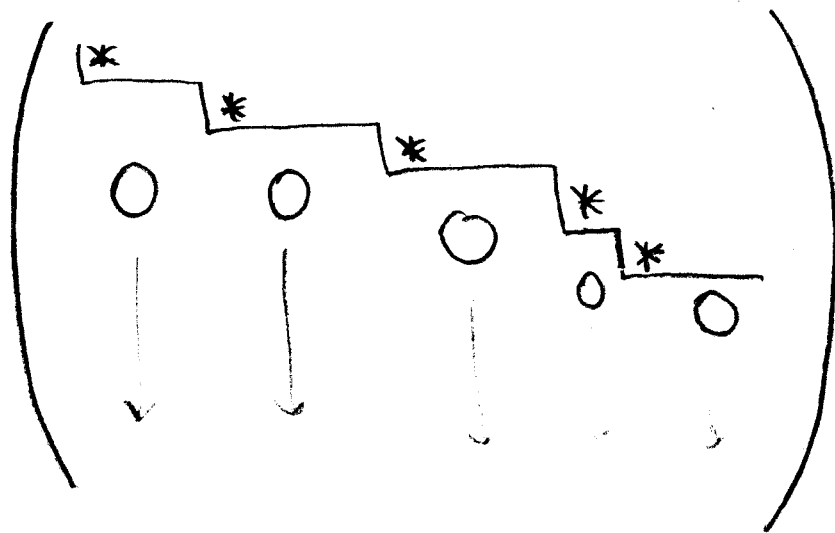
$$\begin{pmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & -3 & -6 & -4 \\ 0 & -6 & -12 & -6 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & -3 & -6 & -4 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

$\therefore$  System has no solutions.

In this algorithm we have worked the augmented matrix down to echelon form.

In this form there are corner entries (pivots) below which we have made zeros systematically.



If there is a solution, it can be found by back substituting.

Ex. Change the 9 to 10 in previous

example:

$$\begin{pmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & \cancel{9} \\ 7 & 8 & 10 & \cancel{1} \end{pmatrix}$$

The same sequence of row operations yields the echelon form

$$\begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & -3 & -6 & -4 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

Since the original system has same solution we get

$$x_3 = 2$$

$$\Rightarrow -3x_2 = 6 \cdot 2 - 4 \Rightarrow x_2 = -\frac{8}{3}$$

and

$$\begin{aligned} x_1 &= -2 \left(-\frac{8}{3}\right) - 3(2) + 1 = \frac{16}{3} - \frac{12}{3} + \frac{3}{3} \\ &= \frac{1}{3} \end{aligned}$$

Finally, let's change to 10 back to 9 and change the 1 in the lower right corner to -1.

Then,

$$\begin{pmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & -1 \end{pmatrix}$$

becomes

$$\begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & -3 & -6 & -4 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

consistent

This solution has infinitely many solutions which can be found by back substitution after assigning letters to the non corner entries which are called free variables.

Here  $x_3$  is free.

$$\text{Let } x_3 = t$$

Then,

$$-3x_2 = 6t - 4$$

$$x_2 = -2t + \frac{4}{3}$$

and

$$x_1 = -2\left(-2t + \frac{4}{3}\right) - 3t + 1$$