# Scalable and Robust Hierarchical Matrix Factorizations via Randomization

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# Fast direct solvers, preconditioners using ideas from structured matrices

Two types of structured matrices (for the purpose of this talk ...)

• "Dense"  $\rightarrow$  data-sparse

e.g., low-rank, butterfly representation

 "Sparse" → structurally-sparse becomes sparser when combining with data-sparse



## Software

- ButterflyPACK <u>https://github.com/liuyangzhuan/ButterflyPACK</u> (Yang Liu et al.)
  - Distributed-memory, OpenMP, Fortran2008
  - Support H, HODLR with LR and Butterfly
  - Dense
- STRUMPACK <a href="https://portal.nersc.gov/project/sparse/strumpack/">https://portal.nersc.gov/project/sparse/strumpack/</a>

(Pieter Ghysels et al.)

- Distributed-memory, OpenMP, C++
- Support HSS, BLR with LR, interface with most ButterflyPACK functionalities
- Dense and sparse (multifrontal + data-sparse fronts)

	H (LR/BF)	HODLR (LR/BF)	HSS	BLR	H <sup>2</sup>
ButterflyPACK	$\odot$	$\odot$			
STRUMPACK		$\odot$	$\odot$	$\odot$	WIP



# Outline

- Adaptive random sketching, error estimate, stopping criteria
  C. Gorman, G. Chavez, P. Ghysels, T. Mary, F.-H. Rouet, X.S. Li, "Robust and Accurate Stopping Criteria for Adaptive Randomized Sampling in Matrix-free Hierarchically Semiseparable Construction", SIAM J. Sci. Comput., 2019
- Butterfly compression for high frequency wave equations
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# Classes of LR structured matrices

#### Lower complexity usually requires multilevel / hierarchical approach

	Strong admissibility	Weak admissibility
Independent bases	H matrix	(Hierarchically off-diagonal low-rank) HODLR matrix
Nested bases	H <sup>2</sup> matrix Inverse FMM	HSS matrix Recursive Skeletonization HIF







Weak admissibility





Strong admissibility

## **Butterfly structured matrices**

 Butterfly factorization: generalized FFT Michielssen/Boag (1996), Li, Liu, Poulson, Yang, Ying, ...

	Strong admissibility	Weak admissibility
Independent bases	H-BF	HOD-BF
Nested bases	Directional H <sup>2</sup> ?	HSS-BF





# **Stages of operations**

- Data clustering, matrix reordering
  - minimize off-diag ranks
- Compression usually dominating cost complexity depends on two situations:

1. only black-box matvec K\*g and K'\*g are available

2. only black-box entry evaluation K(i,j) is available Goal: **O(N log**<sup>a</sup>**N)** 

- Matrix operations with compressed format
  - Matrix-vector multiplication
  - Factorization / solve, inversion, ...

Sweeping through "trees" upward / downward:

- HSS tree, butterfly tree
- Principal tools for parallelization



# LR compression mechanisms

- SVD
- RRQR
- Randomized projection (sampling, sketching) :  $O(n^2r)$
- ACA, block ACA → hierarchical blocked ACA : 0(nr<sup>2</sup>) (Liu, Sid-Lakhdar, Rebrova, Ghysels, Li, 2020)
- Interpolative Decomposition (ID) (skeletonization)
  *B* ≈ *B*(:,*J*)*X*, *B*(:,*J*) has *k* columns, *X* is called interpolation matrix
- Nearest neighbors: relies on geometry



# **Compression via randomized sketching (RS)**

... more flexible and faster than traditional rank-revealing QR

#### Approximate range of A:

- 1. Pick random matrix  $\Omega_{nx(k+p)}$ , k target rank, p small, e.g. 10
- 2. Sample matrix  $S = A \Omega$  (tall-skinny)
- 3. Compute Q = ON-basis(S) via rank-revealing QR

Can show:  $||(I - QQ^*)A||$  is small with high probability

$$E[||A - QQ^*A||] = \left(1 + \frac{4\sqrt{k+p}}{p-1}\sqrt{\min\{m,n\}}\right)\sigma_{k+1}$$

(Halko, Martinsson, Tropp, SIAM Rev. 2011)

#### **Benefits:**

- Matrix-free, only need matvec
- When embedded in sparse frontal solver, simplifies "extend-add"



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#### Practical issue: do not know target rank!



## **Earlier adaptive strategy**

 Sample based posterior error estimation (Halko, Martinsson, Tropp, SIAM Rev. 2011)

LEMMA 4.1. Let **B** be a real  $m \times n$  matrix. Fix a positive integer r and a real number  $\alpha > 1$ . Draw an independent family  $\{\omega^{(i)} : i = 1, 2, ..., r\}$  of standard Gaussian vectors. Then

$$\|\boldsymbol{B}\| \le \alpha \sqrt{\frac{2}{\pi}} \max_{i=1,...,r} \|\boldsymbol{B}\boldsymbol{\omega}^{(i)}\|$$

except with probability  $\alpha^{-r}$ .

- Drawback:
  - Only provide absolute bound, not relative

(relative is particularly desirable when B are submatrices in hierarchical matrices)



# **New: Incremental RS for robustness and performance**

Increase sample size d, build Q incrementally (block Gram-Schmidt) S =  $[S_1, S_2, S_3, ...]$ 

• Projection:

 $\hat{S} = (I - QQ^*)S_{i+1}$  (one step block Gram–Schmidt)  $\hat{S} = (I - QQ^*)^2S_{i+1}$  (in practice, "twice" to ensure orthogonality)

•  $\hat{S}$  is used to expand Q, only need internal orthogonalizing  $\hat{S}$  $[\bar{Q}, R] = QR(\hat{S})$ , augment  $Q \leftarrow [Q \ \overline{Q}]$ 

Need good error estimation to bound error for A:  $||(I - QQ^*)A||$ 

- only have S (only matvec available)
- want relative error estimate



## Stochastic norm estimation

Let  $A \in \Re^{mxn}$ , and  $x \in \Re^n$  with  $x_i \sim N(0,1)$ . Consider SVD:  $A = U\Sigma V^* = [U_1 \ U_2] \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix}$ 

Define  $\zeta = V^* x$ ,  $\zeta$  is also a Gaussian random vector.

$$\|Ax\|_{2}^{2} = \|\Sigma\xi\|_{2}^{2} = \xi_{1}^{2}\sigma_{1}^{2} + \dots + \xi_{r}^{2}\sigma_{r}^{2}$$

here,  $\sigma_1 \ge \sigma_2 \cdots \ge \sigma_r > 0$  are positive singular values. Then:  $\mathbf{E} \left\| Ax \right\|_{2}^{2} = \sigma_{1}^{2} + \dots + \sigma_{r}^{2} = \left\| A \right\|_{F}^{2}$ For *d* sample vectors:  $\mathbf{E}\left[\left\|S\right\|_{F}^{2}\right] = d\left\|A\right\|_{F}^{2}$ 

Probabilistic tail bounds: Gorman et al., SISC 2019



# Adaptive sampling: stopping criteria

Let  $[S_1 \ S_2] = A [R_1 \ R_2]$ ,  $Q = QR(S_1)$ , block size d

Absolute stopping criterion:

$$||(I - QQ^*)A||_F \approx \frac{1}{\sqrt{d}} ||(I - QQ^*)S_2||_F \le \varepsilon_a$$

Relative stopping criterion:

$$\frac{\|(I - QQ^*)A\|_F}{\|A\|_F} \approx \frac{\|(I - QQ^*)S_2\|}{\|S_2\|} \le \varepsilon_r$$

- Cost: one reduction to compute norms of the sample vectors
- Give enough samples (robustness), but not too many (performance)



#### **Example from HSS compression**

- One internal rectangular Hankel block decay (56x3544) (from the 3600x3600 dense Poisson front)
- Older strategy stops at rank 15. New strategy stops at 27 (real 22)





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# What about wave equations ?

- Low/medium frequency: inversion cost O(N log<sup>α</sup>N)
- High frequency: LR is not effective, inversion cost O(N<sup>3</sup>)
- Remedies:
  - High-frequency FMM (Rokhlin 1993)
  - L-Sweeps (Taus), approximate-inverse (Ying), Xi, Vuik, etc.
  - Butterfly factorization (this talk)





# **Butterfly factorization**



- Butterfly is a FFT-inspired compression tool for highly oscillatory kernels
- Applications
  - Special function transforms (Radon, Fourier, spherical harmonic)
  - Fast direct and iterative integral (IE) equation solvers for high-frequency Helmholtz
  - Fast direct differential equation solvers for high-frequency Helmholtz
  - Scalable machine learning algorithms





## **Physical interpretation of Butterfly**

Degree of freedom (interaction rank): 
$$2D \sim \frac{k a^s a^o}{d}$$
,  $3D \sim \left(\frac{k a^s a^o}{d}\right)^2$ 

 $a^{\circ}$ : diameter of sub-observer.  $a^{\circ}$ : diameter of sub-source.

d: distance between source observer centers. k: wave number.





## **Physical interpretation of Butterfly**

Degree of freedom (interaction rank):  $2D \sim \frac{k a^s a^o}{d}, \quad 3D \sim \left(\frac{k a^s a^o}{d}\right)^2$ 

The ranks of all submatrices are r = constant (butterfly rank)



# **Hierarchical partitioning: Butterfly trees**

Complementary low-rank property





# **Butterfly construction**

Depending on how operator A is available

- Each entry can be evaluated in O(1) time
- Fast matvec available, e.g. in O(n logn) time Examples:
  - Compression of frontal matrices in sparse multifrontal solver
  - Conversion to butterfly from other FMM-like formats
  - Recompressing the composition of Fourier integrals

• ...



## **Butterfly Construction: entry-evaluation based**

Let **B** has butterfly rank *r*, its *L*-level butterfly factorization is  $B = R^L \dots R^1$ Compute LR compression for all judiciously selected submatrices  $R_{i,j}^{\ell}$  has size at most  $r \times r$ , Memory  $O(n \log n)$ , Flops  $O(n \log n)$ 



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$$R^{l} = diag(R_{1}^{l},...,R_{2^{l-1}}^{l})$$

$$\boldsymbol{R}_{i}^{l} = \begin{pmatrix} \boldsymbol{R}_{2i-1,1}^{l} \mid \boldsymbol{R}_{2i-1,2}^{l} & & \\ & \ddots & \\ & & \boldsymbol{R}_{2i-1,2^{L-l+1}-1}^{l} \mid \boldsymbol{R}_{2i-1,2^{L-l+1}}^{l} \\ \boldsymbol{R}_{2i,1}^{l} \mid \boldsymbol{R}_{2i,2}^{l} & & \\ & \ddots & \\ & & & \boldsymbol{R}_{2i,2^{L-l+1}-1}^{l} \mid \boldsymbol{R}_{2i,2^{L-l+1}}^{l} \end{pmatrix}$$



# Hybrid form

- Column basis on the left, row basis on the right
- Meet at middle layer l = L/2



# **Butterfly Construction: random projection based**

• BF\_random\_matvec :  $O(n^{1.5} \log n)$  time,  $O(n \log n)$  memory



• For a  $n \times n$  block A,  $O(n^{0.5})$  vectors are needed

• Its *L*-level butterfly *B* satisfies:  $||A - B||_F^2 \le (L+2)\epsilon^2 ||A||_F^2$ 



# **Butterfly Construction: randomized sketching based**

Liu, Xing, Guo, Michielssen, Ghysels, Li, 2021 (with parallelization)

3D Helmholtz kernel: interaction between two semi-sphere surfaces

BF to approximate:

$$A_{i,j} = \frac{\exp(i2\pi\kappa|\rho_i - \rho_j|)}{|\rho_i - \rho_j|}$$





## After construction, can do several operations

- Matrix-vector multiplication
  - Michielssen, Boag, 1996
  - Li, Yang, Martin, Ho, Ying, 2015
  - Poulson, Demanet, Maxwell, Ying, 2014 parallelization
- Factorization / inversion
  - Liu, Guo, Michielssen, 2017
  - Liu, Xing, Guo, Michielssen, Ghysels, Li, 2020



#### **Butterfly Solver: LU with H-BF**



H. Guo, Y. Liu, J. Hu, and E. Michielssen, "A butterfly-based direct integral equation solver using hierarchical LU factorization for analyzing scattering from electrically large conducting objects", IEEE Trans. Antennas Propag., 2017

# **Distributed-memory Parallelization: BF construction via RS**

HODLR with Butterfly, symmetric bit-reversal ordering for each butterfly



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#### Sparse direct solver: STRUMPACK Embedding LR data-sparse in multifrontal sparse factorization

- Globally sparse, locally dense
  - Embed LR data-sparse in sparse multifrontal algorithm
- Baseline is a sparse multifrontal direct solver
- Nested Dissection ordering → separator tree
- In addition to structural sparsity, further apply LR datasparsity to dense frontal matrices

Nested dissection ordering



- Nested bases + randomized sampling to achieve linear scaling in sparse case
  - O(N logN) flops, O(N) memory for 3D elliptic PDEs

(as opposed to  $O(N^2)$  flops with exact factorization)

Multifrontal Separator tree



# **Sparse direct solver: combine multiple data-sparse**

- Combining BLR and HOD-
  - Large fronts: HOD-BF
  - Medium fronts: BLR
  - Small fronts: no compr



separator size(HOD-BF): 30k separator size(BLR): 300



#### **Sparse MF: HOD-BF/BLR: Finite Difference for 3D Helmholtz**

$$\left(\sum_{i} \rho(\mathbf{x}) \frac{\partial}{\partial x_{i}} \frac{1}{\rho(\mathbf{x})} \frac{\partial}{\partial x_{i}}\right) p(\mathbf{x}) + \frac{\omega^{2}}{\kappa^{2}(\mathbf{x})} p(\mathbf{x}) = -f(\mathbf{x})$$

- 27-point finite difference stencil for 3D visco-acoustic propagation
- $v(\mathbf{x}) = 4000 \text{m/s}, \rho(\mathbf{x}) = 1 \text{kg/m}^3$ , 15 points per wavelength
- Up to 64 Cori Haswell nodes (2048 cores)
- compression tolerance: 10<sup>-4</sup> usually ~10 steps of GMRES





# **Sparse MF: HOD-BF vs. HSS**

N = 250<sup>3</sup>, constant coefficients 32 Cori nodes (1024 cores)

Solver	Exact	HSS	HOD-BF	HOD-BF	HOD-BF
ε	-	$10^{-3}$	$10^{-3}$	$10^{-2}$	$10^{-3}$
$n_{\min}$	-	10K	10K	10K	7K
Compressed fronts	0	39	39	39	197
Dense fronts	1,869,841	1,869,802	1,869,802	1,869,802	1,869,644
Factor time (sec)	513	947	433	354	556
Factor flops $(10^{15})$	13.4	4.98	2.44	2.24	1.21
Flop Compression (%)	100	37.1	18.2	16.7	9.0
Factor mem $(10^3 \text{ GB})$	1.48	0.84	0.73	0.72	0.47
Mem Compression (%)	100	56.8	49.6	48.8	32.2
Max. rank	-	4698	364	153	389
Top 2 fronts					
Mem Compression (%)	-	21.9/14.6	7.29/3.54	4.4/1.89	6.3/3.6
Rank	-	4538/4698	154/242	121/213	177/255
Front time (sec)	37/108	172/195	52/88	42/60	46/70.6
GMRES its.	1	18	6	56	23
Solve flops $(10^{12})$	0.46	8.01	2.84	23.4	7.18
Solve time (sec)	0.72	19.2	3.5	30.1	13.2



#### Sparse MF: HOD-BF: 3D Helmholtz, heterogeneous media

$$\left(\sum_{i} \rho(\mathbf{x}) \frac{\partial}{\partial x_{i}} \frac{1}{\rho(\mathbf{x})} \frac{\partial}{\partial x_{i}}\right) p(\mathbf{x}) + \frac{\omega^{2}}{\kappa^{2}(\mathbf{x})} p(\mathbf{x}) = -f(\mathbf{x})$$

- 27-point finite difference stencil for 3D visco-acoustic propagation
- Marmousi2 P-wave velocity model  $190 \times 216 \times 516$ , N = 21,176,640,  $\omega = 20\pi$ Hz, 7.5 points per wavelength
- 32 Cori Haswell nodes (1024 cores)



Sparse MF: HOD-BF: 3D Helmholtz, heterogeneous media

$$\left(\sum_{i} \rho(\mathbf{x}) \frac{\partial}{\partial x_{i}} \frac{1}{\rho(\mathbf{x})} \frac{\partial}{\partial x_{i}}\right) p(\mathbf{x}) + \frac{\omega^{2}}{\kappa^{2}(\mathbf{x})} p(\mathbf{x}) = -f(\mathbf{x})$$

Differences from truth in  $Re(p(\mathbf{x}))$  with 2 tolerances





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#### **Sparse MF: HOD-BF: Finite Element for 3D Maxwell**

$$\nabla \times \nabla \times \mathbf{E} - \Omega^2 \mathbf{E} = \mathbf{f}$$

- First-order Nedelec element discretization for 3D indefinite Maxwell in a homogenous cube
- N = 14,827,904,  $\Omega = 16$ , 24 points per wavelength
- 32 Cori Haswell nodes

ε	$10^{-5}$
HOD-BF fronts	6
Dense fronts	3,773,215
Factor time $(sec)$	581.1
Factor flops	$1.30 \cdot 10^{15}$
Flops fraction of direct $(\%)$	61.3
Memory (GB)	426
Compression $(\%)$	78.8
Maximum rank / front size	955 / 78203
GMRES its.	17
Solve flops	$5.73 \cdot 10^{12}$
Solve time (sec)	23.8



 $|\mathbf{E}(\mathbf{x})|$ 

Solver breakdowns

....r

# Algorithm complexity (in bigO sense)

- Dense LU: O(N<sup>3</sup>)
- Model PDEs with regular mesh, Nested Dissection ordering

	2D problems N = k <sup>2</sup>			3D problems N = k <sup>3</sup>		
	Factor flops	Solve flops	Memory	Factor flops	Solve flops	Memory
Exact sparse LU	N <sup>3/2</sup>	N log(N)	N log(N)	N <sup>2</sup>	N <sup>4/3</sup>	N <sup>4/3</sup>
STRUMPACK With LR compression	N	Ν	Ν	$N^{\alpha}$ polylog(N) ( $\alpha < 2$ )	N log(N)	N log(N)



# **Perspectives, future directions**

- Techniques from structured matrices are very promising for preconditioning
  - LA tools: ID, randomization
  - Parallelism: coarse-grain (trees), fine-grain (dense submatrices)
- Caveat: wide spectrum of algorithms, not (yet) possible to have a decision tree of algorithm choices (e.g., iterative solution template book)
  - Problem-specific (esp. clustering)
  - Implementations are still being worked on for larger scale problems and machines
- Randomized LA is a very useful tool, rigorous error analyses are needed to understand approximation quality



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