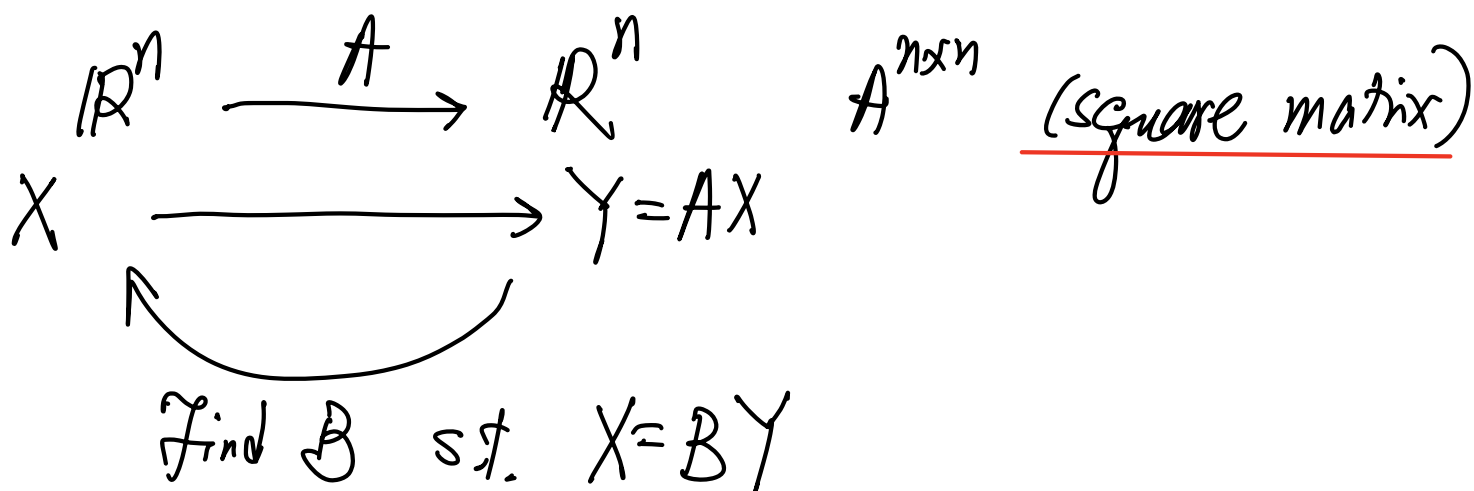


Matrix Inverse



In order for such a B to exist, we need

- (1) For any Y , there is an X s.t. $AX = Y$ → existence of soln $\forall Y$
- (2) Such an X is unique → uniqueness of soln (if exist)

↓ For any Y , $AX = Y$ is uniquely solv.

(1)' $\text{Rank}(A) = n$ (max. no. of non-zero rows)

(2)' $\text{Null}(A) = 0$ (no free variables)

In fact for square matrix, (1)' $\iff$ (2)'
Rank + Nullity = n

Note: for $A^{m \times n}$ (non-square)

$$(1) \iff \text{Rank}(A) = m$$

$$(2) \iff \text{Nullity}(A) = 0$$

$$\underline{\text{Rank} + \text{Nullity} = n}$$

For non-square matrix, $(1) \not\iff (2)$

It is possible to have (1) but not (2)
(vice versa.)

$(1) \text{ and } (2) \Rightarrow m=n, A \text{ must be square}$

$$\begin{array}{ccc} X & \xrightarrow{\quad} & Y = AX \\ & \xleftarrow{\quad} & \\ & X = BY & \end{array}$$

$$\forall X, X = BY = BAX \implies BA = I$$

$$\forall Y, Y = AX = ABX \implies AB = I$$

Def: Given $A^{n \times n}$, B is called ~~the~~ ^{an} inverse of A , henceforth denoted by A^{-1} if $AB = I$ & $BA = I$

$\rightarrow$ A is called non-singular

Note 1 (Thm 1) Inverse is unique

Pf: let $AB = I$ and $BA = I$
 $AC = I$ and $CA = I$

$$\begin{aligned} C(AB) &= C(I) \\ C(AB) &= C I \\ (CA)B &= C \\ IB &= C \\ B &= C \end{aligned}$$

(Note: $AB = I$ and $CA = I \Rightarrow B = C$)

Note 2 (Thm 2) A, B square.

$$AB = I \Leftrightarrow BA = I$$

Properties of A^{-1} (A square)

$$(1) \quad AX = b \Rightarrow A^{-1}(AX) = A^{-1}b$$

$$\underline{X = A^{-1}b}$$

$$(2) \quad \underline{(A^{-1})^{-1} = A}$$

$$\begin{matrix} (3.79) \\ (3.83) \end{matrix} \quad \begin{matrix} (A^2)^{-1} = (A^{-1})^2 \\ \vdots \end{matrix}$$

$$\begin{matrix} (3) \\ (3.80) \end{matrix} \quad \text{If } A^{-1}, B^{-1} \text{ exist, then } (AB)^{-1} \text{ exists}$$

$$\begin{matrix} (3.81) \\ (3.82) \end{matrix} \quad \text{and} \quad \underline{(AB)^{-1} = B^{-1}A^{-1}}$$

$$\begin{matrix} (4) \\ (3.84) \end{matrix} \quad \text{If } A^{-1} \text{ exists, then } (A^T)^{-1} \text{ exists}$$

$$\text{and} \quad \underline{(A^T)^{-1} = (A^{-1})^T}$$

Problems

$$3.72 \quad A = \begin{bmatrix} 1 & a & b \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A^{-1} = ?$$

$$3.74 \quad N = \begin{bmatrix} 0 & a & b \\ 0 & 0 & c \\ 0 & 0 & 0 \end{bmatrix} \quad N^3 = 0$$

$$(I - N)^{-1} \text{ exists, } = I + N + N^2$$

$$3.75 \quad A \text{ (given), } A^{-1} = \begin{bmatrix} 2 & 1 & 3 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \end{bmatrix}$$

3.76

$$\begin{array}{ll} \text{Find } X \text{ s.t.} & XA = C \\ \dots Y \dots & AY = C \end{array} \quad C = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$3.77 \quad A^2 + 3A + I = 0, \quad A^{-1} = ?$$

$$3.78 \quad A^3 + 3A^2 + 2A + 5I = 0, \quad A^{-1} = ?$$

A general fact about general LT

Let $T: \mathcal{U} \rightarrow \mathcal{V}$ be a LT

$$\text{Range}(T) = \{v: \exists u \text{ s.t. } T(u) = v\}$$

$$\text{kernel}(T) = \{u: T(u) = 0\}$$

$$(\equiv \text{Null}(T))$$

(1) $\text{Range}(T)$ is a subspace of $\mathcal{V}$ (3.24)

(2) $\text{Ker}(T) \dots \dots \mathcal{U}$ (3.23)

(3) If T^{-1} exists ($\forall v \in \mathcal{V}, \exists! u$ s.t.
 $T(u) = v$)

then T^{-1} is linear. ($v \xrightarrow{T^{-1}} u$)

$$T(u_1) = v_1, \quad T(u_2) = v_2$$

$$\Rightarrow T(\alpha u_1 + \beta u_2) = \alpha v_1 + \beta v_2$$