

MA 421: Linear Programming and Optimization Techniques
Fall 2024, Final Exam

Instructor: Yip

- This test booklet has SIX QUESTIONS, totaling 100 points for the whole test. You have 120 minutes to do this test. **Plan your time well. Read the questions carefully.**
- This test is **closed book, closed note, with no electronic devices.**
- In order to get full credits, you need to give **correct** and **simplified** answers and explain in a **comprehensible way** how you arrive at them.
- **As a rule of thumb, you should give explicit and useful answers.** No points will be given for just writing down some generically true statements. In other words, your answers should try to make use of all the information given in the question.
- **As a rule of thumb, you should only use those methods that have been covered in class.** If you use some other methods “for the sake of convenience”, at our discretion, we might not give you any credit. You have the right to contest. In that event, **you will be asked to explain your answer using only what has been covered in class up to the point of time of this exam.**

Name: Answer Key (Major: _____)

Question	Score
1.(10 pts)	_____
2.(10 pts)	_____
3.(10 pts)	_____
4.(20 pts)	_____
5.(20 pts)	_____
6.(30 pts)	_____
Total (100 pts)	_____

Formula sheet

1. Matrix form of simplex method [V, p.91, 92].

Given the following linear program problem and its dual in their standard forms:

$$(P) : \begin{cases} \text{maximize} & \zeta(x) = c^T x \\ \text{subject to} & Ax \leq b; \\ & x \geq 0. \end{cases} \quad (D) : \begin{cases} \text{minimize} & \xi(y) = b^T y \\ \text{subject to} & A^T y \geq c; \\ & y \geq 0. \end{cases}$$

During simplex iterations, the above can be transformed into the following matrix form:

$$\begin{aligned} \zeta &= c_B^T (B^{-1}b) - ((B^{-1}N)^T c_B - c_N)^T X_N \\ X_B &= B^{-1}b - (B^{-1}N)X_N \end{aligned}$$

with the following dual form:

$$\begin{aligned} -\xi &= -c_B^T (B^{-1}b) - (B^{-1}b)^T Z_B \\ Z_N &= ((B^{-1}N)^T c_B - c_N) + (B^{-1}N)^T Z_B \end{aligned}$$

where in the above

- (a) \mathcal{B} and \mathcal{N} are the basic and non-basic variable indices;
 - (b) c_B and c_N are the coefficients in the objective function corresponding to the basic and non-basic variables;
 - (c) B and N are matrices formed by the collecting the columns from the augmented matrix $[A \ I]$ corresponding to the basic and non-basic variables.
 - (d) X_B and X_N are the basic and non-basic primal variables, and Z_B and Z_N are the basic and non-basic dual variables.
2. Infinitesimal change of matrix inverse. Let M be an invertible matrix. Then

$$\delta(M^{-1}) = -M^{-1}(\delta M)M^{-1}$$

(where δ refers to infinitesimal change in a quantity).

3. Caratheodory Theorem [V, p.162].

THEOREM 10.3. *The convex hull $\text{conv}(S)$ of a set S in \mathbb{R}^m consists of all convex combinations of $m + 1$ points from S :*

$$\text{conv}(S) = \left\{ z = \sum_{j=1}^{m+1} t_j z_j : z_j \in S \text{ and } t_j \geq 0 \text{ for all } j, \text{ and } \sum_j t_j = 1 \right\}.$$

4. Farkas Lemma [V, p. 165].

LEMMA 10.5. *The system $Ax \leq b$ has no solutions if and only if there is a y such that*

$$(10.8) \quad \begin{aligned} A^T y &= 0 \\ y &\geq 0 \\ b^T y &< 0. \end{aligned}$$

5. Separation Theorem [V, p.163].

THEOREM 10.4. *Let P and \tilde{P} be two disjoint nonempty polyhedra in \mathbb{R}^n . Then there exist disjoint half-spaces H and \tilde{H} such that $P \subset H$ and $\tilde{P} \subset \tilde{H}$.*

If $P = \{x : Ax \leq b\}$ and $\tilde{P} = \{x : \tilde{A}x \leq \tilde{b}\}$, then

$$H = \{x : y^T Ax \leq y^T b\}, \quad \text{and} \quad \tilde{H} = \{x : \tilde{y}^T \tilde{A}x \leq \tilde{y}^T \tilde{b}\},$$

where y and \tilde{y} are found by Farkas Lemma:

$$(10.5) \quad \begin{bmatrix} A^T & \tilde{A}^T \end{bmatrix} \begin{bmatrix} y \\ \tilde{y} \end{bmatrix} = A^T y + \tilde{A}^T \tilde{y} = 0$$

$$(10.6) \quad \begin{bmatrix} y \\ \tilde{y} \end{bmatrix} \geq 0$$

$$(10.7) \quad \begin{bmatrix} b^T & \tilde{b}^T \end{bmatrix} \begin{bmatrix} y \\ \tilde{y} \end{bmatrix} = b^T y + \tilde{b}^T \tilde{y} < 0.$$

(Note that the form of \tilde{H} given here is equivalent to the one given in [V, p.164] but it looks nicer and is easier to remember.)

6. Distance formula. The distance from a point (x_0, y_0) to the straightline $ax + by + c = 0$ is given by

$$\left| \frac{ax_0 + by_0 + c}{\sqrt{a^2 + b^2}} \right|.$$

7. Variables of network flows. Given a network $(\mathcal{N}, \mathcal{A})$ (where \mathcal{N} and \mathcal{A} denote the nodes and arcs), and a spanning tree \mathcal{T} of the network, we have the following set of variables [V, p.231]:

(a) Flow variables: x_{ij} (found by balance equations)

(b) Dual variables y_j and dual slacks z_{ij} which satisfy:

$$y_j - y_i + z_{ij} = c_{ij}, \quad \text{for } (i, j) \in \mathcal{A}.$$

Note that for $(i, j) \in \mathcal{T}$, we have (by complementary slackness) that $z_{ij} = 0$. The usual way to find y_i and z_{ij} is to *first* solve for y_i using $y_j - y_i = c_{ij}$ for $(i, j) \in \mathcal{T}$ and *then* use $z_{ij} = c_{ij} - y_j + y_i$ for $(i, j) \notin \mathcal{T}$.

8. Bellman's equation for the label (or value function) for finding the shortest distance/path from (any) node i to a root node (r) is given by [V, p.261, 262]

$$v_i = \min_j \{c_{ij} + v_j : (i, j) \in \mathcal{A}\}, \quad \text{for } i \neq r \quad v_r = 0.$$

The function v can be found by the following iteration procedure:

3.2.1. Method of Successive Approximation. Bellman's equation is an implicit system of equations for the values v_i , $i \in \mathcal{N}$. Implicit equations such as this arise frequently and beg to be solved by starting with a guess at the solution, using this guess in the right-hand side, and computing a new guess by evaluating the right-hand side. This approach is called the *method of successive approximations*. To apply it to the shortest-path problem, we initialize the labels as follows:

$$v_i^{(0)} = \begin{cases} 0 & i = r \\ \infty & i \neq r. \end{cases}$$

Then the updates are computed using Bellman's equation:

$$v_i^{(k+1)} = \begin{cases} 0 & i = r \\ \min\{c_{ij} + v_j^{(k)} : (i, j) \in \mathcal{A}\} & i \neq r. \end{cases}$$

9. Dijkstra algorithm for finding the shortest path (with non-negative costs c_{ij}) [V, p.263].

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Initialize:
   $\mathcal{F} = \emptyset$ 
   $v_j = \begin{cases} 0 & j = r, \\ \infty & j \neq r. \end{cases}$ 
while ( $|\mathcal{F}^c| > 0$ ){
   $j = \operatorname{argmin}\{v_k : k \notin \mathcal{F}\}$ 
   $\mathcal{F} \leftarrow \mathcal{F} \cup \{j\}$ 
  for each  $i$  for which  $(i, j) \in \mathcal{A}$  and  $i \notin \mathcal{F}$  {
    if  $(c_{ij} + v_j < v_i)$  {
       $v_i = c_{ij} + v_j$ 
       $h_i = j$ 
    }
  }
}

```

10. Greedy algorithm for finding minimum spanning tree [Berkasimas-Tsitsiklis, Intro. Lin. Opt., p.344].

Greedy algorithm for the minimum spanning tree problem

1. The input to the algorithm is a connected undirected graph $G = (\mathcal{N}, \mathcal{E})$ and a coefficient c_e for each edge $e \in \mathcal{E}$. The algorithm is initialized with a tree $(\mathcal{N}_1, \mathcal{E}_1)$ that has a single node and no edges (\mathcal{E}_1 is empty).
2. Once $(\mathcal{N}_k, \mathcal{E}_k)$ is available, and if $k < n$, we consider all edges $\{i, j\} \in \mathcal{E}$ such that $i \in \mathcal{N}_k$ and $j \notin \mathcal{N}_k$. Choose an edge $e^* = \{i, j\}$ of this type whose cost is smallest. Let

$$\mathcal{N}_{k+1} = \mathcal{N}_k \cup \{j\}, \quad \mathcal{E}_{k+1} = \mathcal{E}_k \cup \{e^*\}.$$

11. Karush-Kuhn-Tucker (KKT) condition [Chong-Zak]

Theorem 21.1 Karush-Kuhn-Tucker (KKT) Theorem. *Let $f, \mathbf{h}, \mathbf{g} \in \mathcal{C}^1$. Let \mathbf{x}^* be a regular point and a local minimizer for the problem of minimizing f subject to $\mathbf{h}(\mathbf{x}) = \mathbf{0}$, $\mathbf{g}(\mathbf{x}) \leq \mathbf{0}$. Then, there exist $\boldsymbol{\lambda}^* \in \mathbb{R}^m$ and $\boldsymbol{\mu}^* \in \mathbb{R}^p$ such that:*

1. $\boldsymbol{\mu}^* \geq \mathbf{0}$.
2. $Df(\mathbf{x}^*) + \boldsymbol{\lambda}^{*\top} Dh(\mathbf{x}^*) + \boldsymbol{\mu}^{*\top} D\mathbf{g}(\mathbf{x}^*) = \mathbf{0}^\top$.
3. $\boldsymbol{\mu}^{*\top} \mathbf{g}(\mathbf{x}^*) = 0$.
4. $\mathbf{h}(\mathbf{x}^*) = \mathbf{0}$.
5. $\mathbf{g}(\mathbf{x}^*) \leq \mathbf{0}$.

1. Consider the following (linear programming) problem:

$$\begin{array}{ll}
 \text{maximize} & 5x_1 + 5x_2 + 3x_3 \\
 \text{subject to} & x_1 + 3x_2 + x_3 \leq 3 \\
 & -x_1 + 3x_3 \leq 2 \\
 & 2x_1 - x_2 + 2x_3 \leq 4 \\
 & 2x_1 + 3x_2 - x_3 \leq 2 \\
 & x_1, x_2, x_3 \geq 0.
 \end{array}$$

$$\begin{array}{l}
 2 < 3 \Rightarrow w_1 > 0 \\
 2 < 2 \Rightarrow w_2 > 0 \\
 4 = 4 \Rightarrow w_3 = 0 \\
 2 = 2 \Rightarrow w_4 = 0
 \end{array}$$

Someone claims that $x_1 = \frac{4}{3}$, $x_2 = 0$, $x_3 = \frac{2}{3}$ is an optimal solution. Prove or disprove this claim.

$$\begin{array}{l}
 x_1 > 0 \Rightarrow z_1 = 0 \\
 x_3 > 0 \Rightarrow z_3 = 0
 \end{array}$$

$$\begin{array}{l}
 w_1 > 0 \Rightarrow y_1 = 0 \\
 w_2 > 0 \Rightarrow y_2 = 0
 \end{array}$$

Dual Problem:

$$\begin{array}{r}
 y_1 - y_2 + 2y_3 + 2y_4 \geq 5 = 5 \\
 3y_1 - y_3 + 3y_4 \geq 5 \\
 y_1 + 3y_2 + 2y_3 - y_4 \geq 3 = 3
 \end{array}$$

$$\begin{array}{l}
 \Rightarrow 2y_3 + 2y_4 = 5 \\
 2y_3 - y_4 = 3
 \end{array}$$

$$\Rightarrow y_4 = \frac{2}{3}, \quad y_3 = \frac{1}{2} \left(3 + \frac{2}{3} \right) = \frac{11}{6}$$

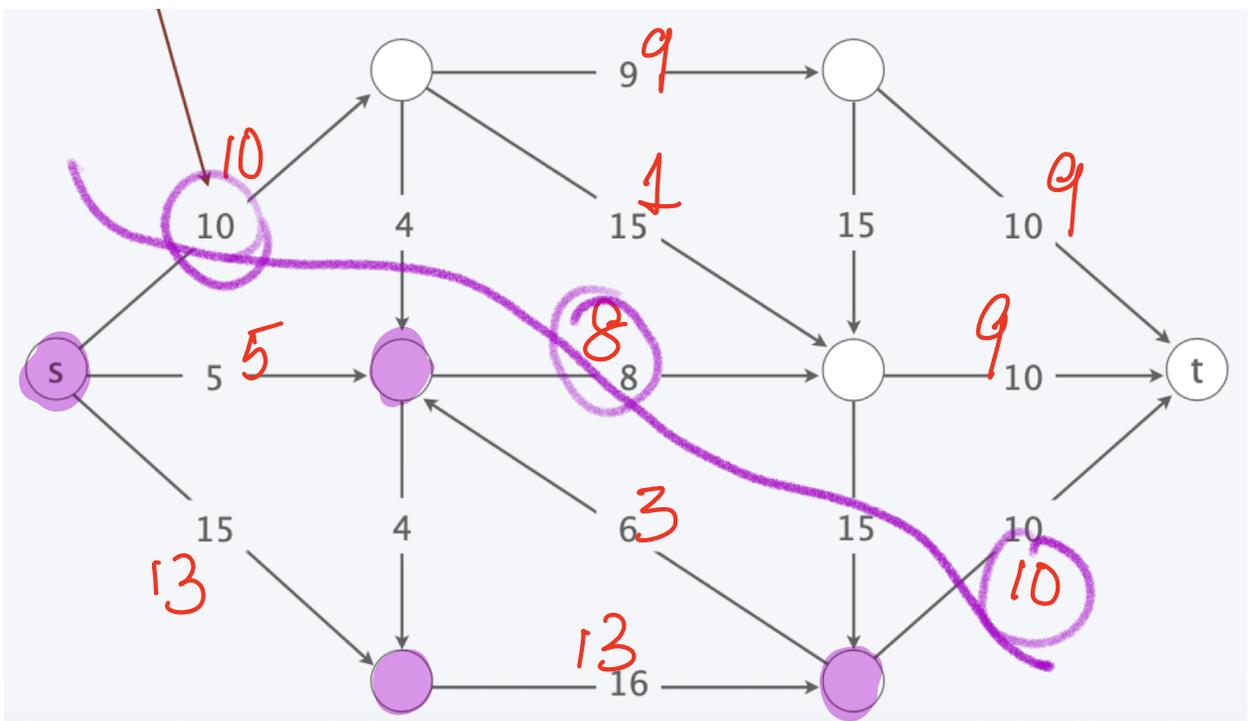
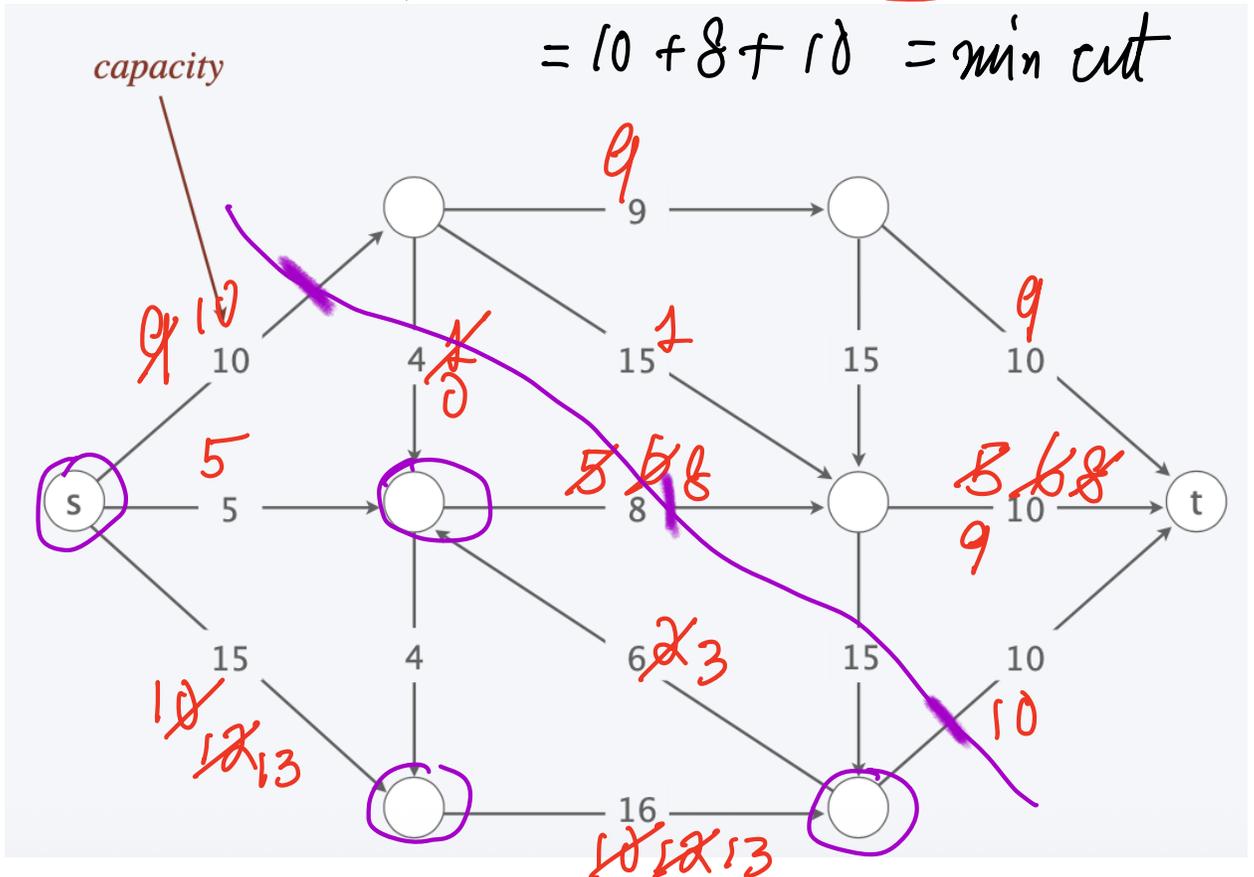
$$-y_3 + 3y_4 = -\frac{11}{6} + 2 < 5 \quad \underline{\underline{!!}}$$

Not opt.!

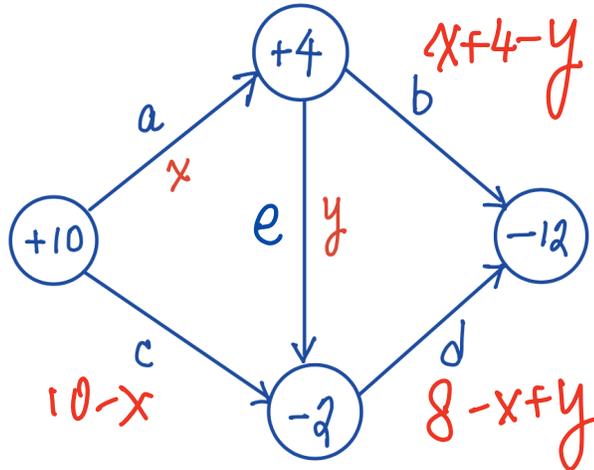
2. Find the maximum flow and minimum cut for the following network. (The node s is the source and t is the sink. The extra graph copies in the next pages can be used for scrap work.)

$$\text{Max flow} = 10 + 5 + 13 = \mathbf{28} (= 9 + 9 + 10)$$

$$= 10 + 8 + 10 = \text{min cut}$$



3. Consider the following network:



where the numbers inside each node is the production level (supply if positive/demand if negative) and $a, b, c, d \geq 0$ are the unit transportation costs between the nodes. Find the optimal transshipment scheme for any values of a, b, c, d .

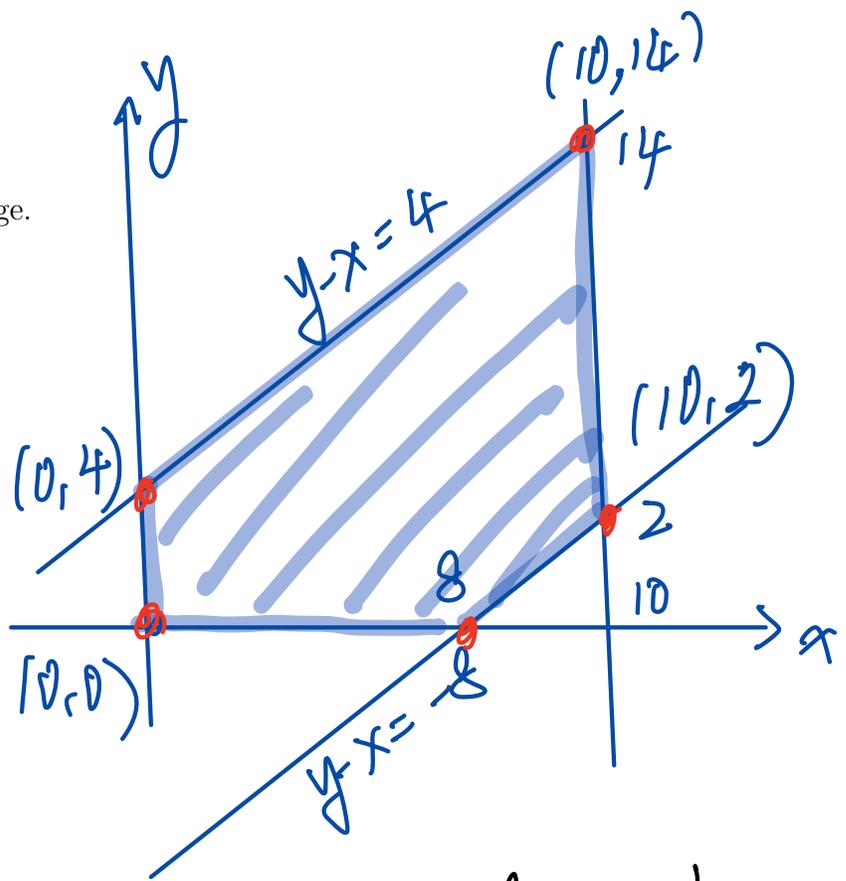
(Hint: you can set up the problem using the x and y variables which represent the flows between the respective nodes. Make sure you identify the feasible region for x and y . The use of graphical method is permissible.)

$$\begin{aligned} \text{Cost } f(x, y) &= ax + b(x+4-y) + c(10-x) \\ &\quad + d(8-x+y) + ey \\ &= (a+b-c-d)x + (-b+d+e)y \\ &\quad + 4b + 10c + 8d \end{aligned}$$

$$\text{Constraints: } \begin{cases} x \geq 0, y \geq 0 \\ 10-x \geq 0, 4+x-y \geq 0, 8-x+y \geq 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} 0 \leq x \leq 10 \\ -8 \leq y-x \leq 4 \end{cases}$$

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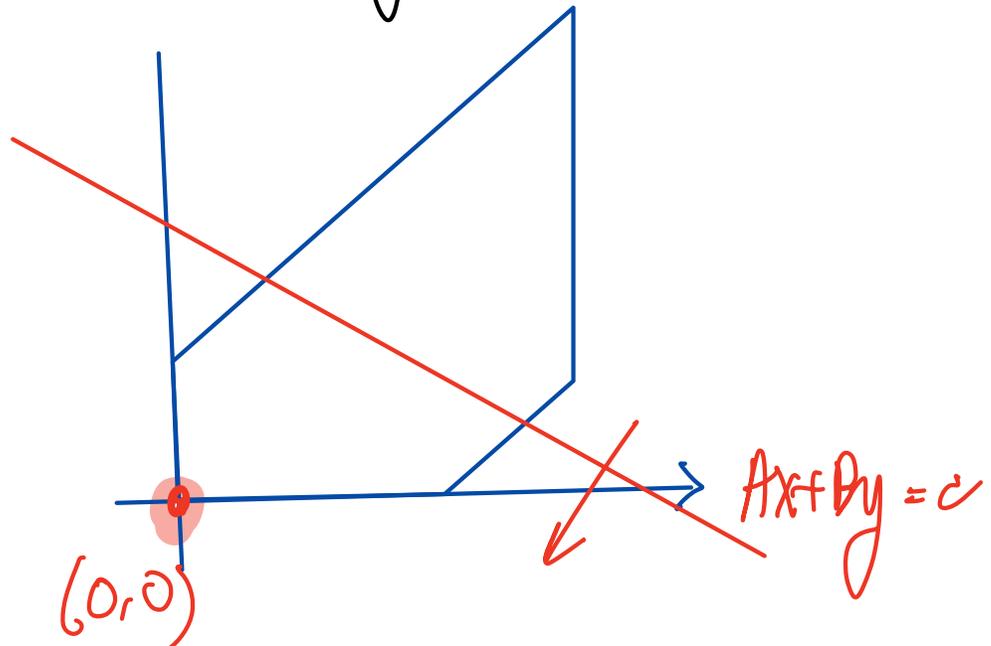
$$\min f(x,y) = Ax + By + C$$

$$A = a + b - c - d$$

$$B = -b + d + e$$

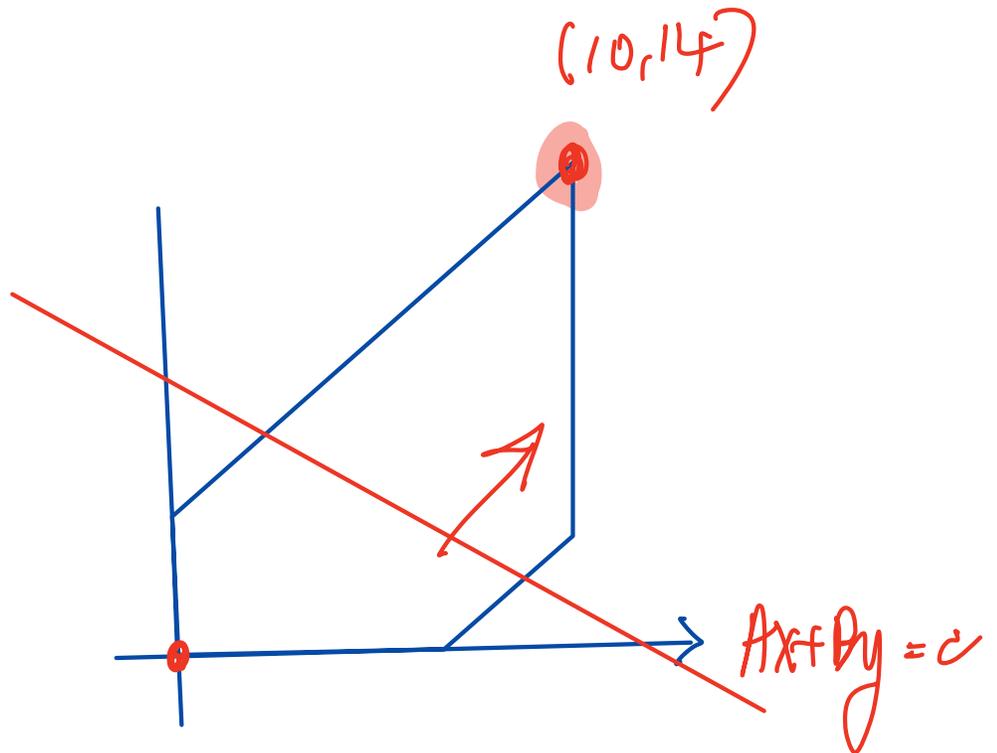
$$C = 4b + 10c + 8d$$

① $A, B \geq 0 \Rightarrow x^* = 0, y^* = 0$

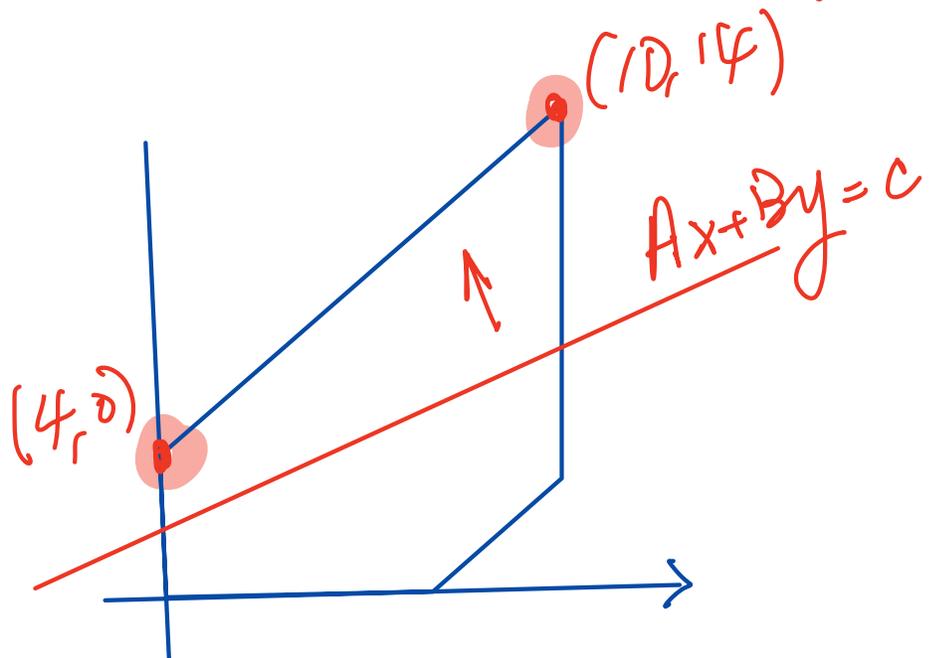


(2) $A, B < 0 \Rightarrow x^* = 10, y^* = 14$

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(3) $A \geq 0, B < 0$
(eg $x-y=c$)

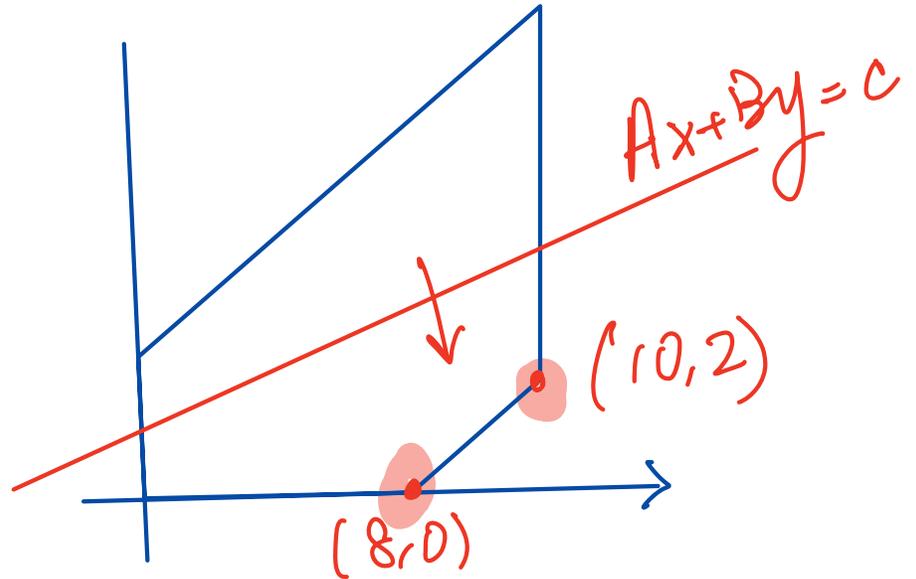


If $|\frac{A}{B}| < 1 \Rightarrow x^* = 10, y^* = 14$

If $|\frac{A}{B}| > 1 \Rightarrow x^* = 0, y^* = 4$

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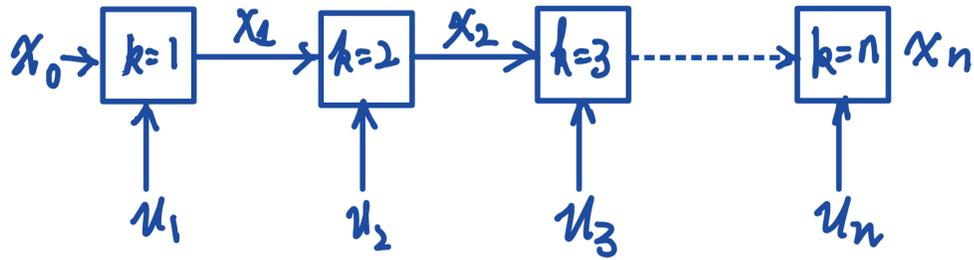
④ $A < 0, B \geq 0$
(eg $-x + y = c$)



If $\left| \frac{A}{B} \right| < 1 \Rightarrow x^* = 8, y^* = 0$

If $\left| \frac{A}{B} \right| > 1 \Rightarrow x^* = 10, y^* = 2$

4. Consider the following input-output-control system:



where $x_0, x_1, x_2 \dots$ are the initial and subsequent state variables and $u_1, u_2 \dots$ are the control variables. The x_k 's are determined by the following rule:

$$x_{k+1} = ax_k + bu_{k+1}, \text{ for } 0 \leq k \leq n-1 \text{ (and } x_0 \text{ is given/prescribed)}. \quad (1)$$

The objective is to find the controls so as to

$$\min_{u_1, u_2, \dots, u_n} x_n^2 + \sum_{k=1}^n u_k^2, \quad (2)$$

i.e. you want the end state and the controls to be as small as possible.

(a) Solve (1)–(2) for $x_0 = 1$, $a = -1$, $b = 2$, $n = 2$.

(b) Now suppose (2) is changed to

$$\min_{u_1, u_2, \dots, u_n} |x_n| + \sum_{k=1}^n |u_k|. \quad (3)$$

Formulate the problem as a linear programming problem for the same parameters:

$x_0 = 1$, $a = -1$, $b = 2$, $n = 2$.

Write your formulation in *standard form* and produce an *initial feasible dictionary*.

$$(a) \quad \left. \begin{array}{l} x_1 = -x_0 + 2u_1 \\ x_2 = -x_1 + 2u_2 \end{array} \right\} \Leftrightarrow \begin{array}{l} x_1 - 2u_1 = -1 \\ x_2 + x_1 - 2u_2 = 0 \end{array}$$

$$\begin{array}{ll} \min & x_2^2 + u_1^2 + u_2^2 \\ \text{s.t.} & x_1 - 2u_1 = -1 \\ & x_2 + x_1 - 2u_2 = 0 \end{array}$$

M1

$$L(x_1, x_2, u_1, u_2, \lambda_1, \lambda_2)$$

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$$= x_2^2 + u_1^2 + u_2^2 + \lambda_1(x_1 - 2u_1 - 1) + \lambda_2(x_2 + x_1 - 2u_2)$$

$$\left. \begin{aligned} \partial_{x_1} = 0 &\Rightarrow \lambda_1 + \lambda_2 = 0 \\ \partial_{x_2} = 0 &\Rightarrow 2x_2 + \lambda_2 = 0 \\ \partial_{u_1} = 0 &\Rightarrow 2u_1 - 2\lambda_1 = 0 \\ \partial_{u_2} = 0 &\Rightarrow 2u_2 - 2\lambda_2 = 0 \end{aligned} \right\} \Rightarrow \begin{aligned} u_1 = \lambda_1, u_2 = \lambda_2 = -\lambda_1 \\ x_2 = -\frac{\lambda_2}{2} = \frac{\lambda_1}{2}, \end{aligned}$$

$$\begin{aligned} x_1 - 2u_1 &= -1 \\ x_2 + x_1 - 2u_2 &= 0 \end{aligned} \Rightarrow \begin{aligned} x_1 &= -1 + 2u_1 = -1 + 2\lambda_1 \\ \frac{\lambda_1}{2} - 1 + 2\lambda_1 + 2\lambda_1 &= 0 \\ \lambda_1 &= \frac{2}{9} \\ \lambda_2 &= -\frac{2}{9} \end{aligned}$$

$$\begin{aligned} x_1 &= -1 + \frac{4}{9} = -\frac{5}{9}, & u_1 &= \frac{2}{9}, & \min &= \left(\frac{1}{9}\right)^2 + \left(\frac{2}{9}\right)^2 \\ x_2 &= \frac{1}{9}, & u_2 &= -\frac{2}{9}, & &= \frac{1}{9} \end{aligned}$$

M2

$$\begin{aligned} \min \quad & x_2^2 + u_1^2 + u_2^2 \\ \text{s.t.} \quad & x_1 - 2u_1 = -1 \\ & x_2 + x_1 - 2u_2 = 0 \end{aligned}$$

$$x_2 = -x_1 + 2u_2 = -2u_1 + 1 + 2u_2$$

$$\min (1 - 2u_1 + 2u_2)^2 + u_1^2 + u_2^2$$

$$\begin{aligned} \partial_{u_1} = 0 \Rightarrow (1 - 2u_1 + 2u_2)(-2) + u_1 &= 0 \\ 5u_1 - 4u_2 &= 2 \end{aligned}$$

$$\begin{aligned} \partial_{u_2} = 0 \Rightarrow (1 - 2u_1 + 2u_2)(2) + u_2 &= 0 \\ -4u_1 + 5u_2 &= -2 \end{aligned}$$

$$u_1 = \frac{\begin{vmatrix} 2 & -4 \\ -2 & 5 \end{vmatrix}}{\begin{vmatrix} 5 & -4 \\ -4 & 5 \end{vmatrix}} = \frac{2}{9}, \quad u_2 = \frac{\begin{vmatrix} 5 & 2 \\ -4 & -2 \end{vmatrix}}{\begin{vmatrix} 5 & -4 \\ -4 & 5 \end{vmatrix}} = -\frac{2}{9}$$

$$x_1 = -\frac{5}{9}, \quad x_2 = \frac{1}{9}$$

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$$(b) \quad \min |x_2| + |u_1| + |u_2|$$

$$\text{s.t.} \quad x_1 - 2u_1 = -1$$

$$x_2 + x_1 - 2u_2 = 0$$

$$\min t_1 + t_2 + t_3$$

$$-t_1 \leq x_2 \leq t_1$$

$$-t_2 \leq u_1 \leq t_2$$

$$-t_3 \leq u_2 \leq t_3$$

$$x_1 - 2u_1 = -1 \quad \left. \vphantom{x_1 - 2u_1 = -1} \right\} w_1 = 1 + x_1 - 2u_1 \geq 0$$

$$x_1 + x_2 - 2u_2 = 0 \quad \left. \vphantom{x_1 + x_2 - 2u_2 = 0} \right\} w_2 = x_1 + x_2 - 2u_2 \geq 0$$

$$\min t_1 + t_2 + t_3 + w_1 + w_2$$

s.t.

$$x_2 - t_1 \leq 0, \quad -x_2 - t_1 \leq 0$$

$$u_1 - t_2 \leq 0, \quad -u_1 - t_2 \leq 0$$

$$u_2 - t_3 \leq 0, \quad -u_2 - t_3 \leq 0$$

$$w_1 = 1 + x_1 - 2u_1$$

$$w_2 = x_1 + x_2 - 2u_2$$

$$t_1, t_2, t_3, w_1, w_2 \geq 0$$

feasible!

$$\max -t_1 - t_2 - t_3 - w_1 - w_2$$

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$$= -t_1 - t_2 - t_3 - 1 - x_1 + 2u_1 - x_1 - x_2 + 2u_2$$

$$= -1 - t_1 - t_2 - t_3 - 2x_1 - x_2 + 2u_1 + 2u_2$$

$$\text{LP: } \max \int = -1 - t_1 - t_2 - t_3 - 2x_1 - x_2 + 2u_1 + 2u_2$$

$$\text{s.t. } w_1 = 1 + x_1 - 2u_1$$

$$w_2 = x_1 + x_2 - 2u_2$$

$$w_3 = t_1 - x_2$$

$$w_4 = t_1 + x_2$$

$$w_5 = t_2 - u_1$$

$$w_6 = t_2 + u_1$$

$$w_7 = t_3 - u_2$$

$$w_8 = t_3 + u_2$$

$$t_1, t_2, t_3, w_1, \dots, w_8 \geq 0$$

$u_1 \rightarrow \frac{1}{2}$ 1st iteration
exchange $u_1 \leftrightarrow w_1$

5. Consider the following quadratic programming problem:

$$\begin{aligned} \min_{x_1, x_2, x_3} \quad & f(x_1, x_2, x_3) = x_1^2 + x_2^2 + x_3^2 - 7x_3 \\ \text{s.t.} \quad & x_1 + x_2 + x_3 = 1, \\ & 4x_1 + 5x_2 + 2x_3 = 3, \\ & x_1, x_2, x_3 \geq 0. \end{aligned}$$

- (a) Relate the above to a linear programming problem and write down a corresponding feasible dictionary (plus any extra rule(s)).
- (b) Solve the above minimization problem. You can use the linear programming formulation in (a) or any other method of your choice.

$$\begin{aligned} L(x_1, x_2, x_3, \lambda_1, \lambda_2, \mu_1, \mu_2, \mu_3) \\ = x_1^2 + x_2^2 + x_3^2 - 7x_3 + \lambda_1(x_1 + x_2 + x_3 - 1) \\ + \lambda_2(4x_1 + 5x_2 + 2x_3 - 3) \\ - \mu_1 x_1 - \mu_2 x_2 - \mu_3 x_3 \end{aligned}$$

$$\frac{\partial L}{\partial x_1} = 0 \Rightarrow 2x_1 + \lambda_1 + 4\lambda_2 - \mu_1 = 0$$

$$\frac{\partial L}{\partial x_2} = 0 \Rightarrow 2x_2 + \lambda_1 + 5\lambda_2 - \mu_2 = 0$$

$$\frac{\partial L}{\partial x_3} = 0 \Rightarrow 2x_3 - 7 + \lambda_1 + 2\lambda_2 - \mu_3 = 0$$

$$x_1 + x_2 + x_3 - 1 = 0$$

$$4x_1 + 5x_2 + 2x_3 - 3 = 0$$

$$x_1, x_2, x_3, \mu_1, \mu_2, \mu_3 \geq 0$$

$$x_1 \mu_1 = 0, \quad x_2 \mu_2 = 0, \quad x_3 \mu_3 = 0$$

(a) LP Formulation: introduce auxiliary variables:

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$$\begin{cases} w_1 = -2x_1 - \lambda_1 - 4\lambda_2 + \mu_1 \\ w_2 = -2x_2 - \lambda_1 - 5\lambda_2 + \mu_2 \\ w_3 = 7 - 2x_3 - \lambda_1 - 2\lambda_2 + \mu_3 \\ w_4 = 1 - x_1 - x_2 - x_3 \\ w_5 = 3 - 4x_1 - 5x_2 - 2x_3 \end{cases}$$

$$w_1, \dots, w_5, x_1, x_2, x_3, \mu_1, \mu_2, \mu_3 \geq 0$$

$$\underline{x_1 \mu_1 = 0, x_2 \mu_2 = 0, x_3 \mu_3 = 0}$$

$$\min w_1 + w_2 + w_3 + w_4 + w_5$$

$$= -7x_1 - 8x_2 - 5x_3 - 3\lambda_1 - 11\lambda_2 + \mu_1 + \mu_2 + \mu_3$$

$$\max 7x_1 + 8x_2 + 5x_3 + 3\lambda_1 + 11\lambda_2 - \mu_1 - \mu_2 - \mu_3$$

(b) Solve for

You can use this blank page.

$$\begin{cases} x_1 + x_2 + x_3 - 1 = 0 \\ 4x_1 + 5x_2 + 2x_3 - 3 = 0 \end{cases}$$

$$\begin{cases} x_1 + x_2 = 1 - x_3 \\ 4x_1 + 5x_2 = 3 - 2x_3 \end{cases}$$

$$x_1 = 2 - 5x_3 + 2x_2 = 2 - 3x_3$$

$$x_2 = 3 - 4 - 2x_3 + 4x_3 = -1 + 2x_3$$

$$\min x_1^2 + x_2^2 + x_3^2 - 7x_3$$

$$= (2 - 3x_3)^2 + (-1 + 2x_3)^2 + x_3^2 - 7x_3$$

$$= 4 - 12x_3 + 9x_3^2 + 1 - 4x_3 + 4x_3^2 + x_3^2 - 7x_3$$

$$= 14x_3^2 - 23x_3 + 5$$

$$\begin{cases} x_1 > 0 \Rightarrow x_3 \leq \frac{2}{3} \\ x_2 > 0 \Rightarrow x_3 \geq \frac{1}{2} \\ x_3 > 0 \Rightarrow x_3 \geq 0 \end{cases} \quad \left. \vphantom{\begin{cases} x_1 > 0 \\ x_2 > 0 \\ x_3 > 0 \end{cases}} \right\} \frac{1}{2} \leq x_3 \leq \frac{2}{3}$$

You can use this blank page.

$$\min f(x_3) = 14x_3^2 - 23x_3 + 5$$

$$\text{s.t. } \frac{1}{2} \leq x_3 \leq \frac{2}{3}$$

Try interior pt.

$$f'(x_3) = 0 \Rightarrow 28x_3 = 23 \Rightarrow x_3 = \frac{23}{28}$$

$> \frac{2}{3}!$

Try end pt:

$$x_3 = \frac{1}{2} \Rightarrow f\left(\frac{1}{2}\right) = \frac{14}{4} - \frac{23}{2} = -8$$

$$x_3 = \frac{2}{3} \Rightarrow f\left(\frac{2}{3}\right) = 14\left(\frac{4}{9}\right) - \frac{23(2)}{3} = -\frac{82}{9}$$

$$(x_1 = 0, x_2 = \frac{1}{3}) \quad (56 - 138 = -82) \quad \underline{\underline{\text{min}}}$$

6. Now, as a veteran data scientist in a renowned company, you attempt an internal technical evaluation to seek for a promotion. You are presented the following problem and its solution:

$$\begin{aligned}
 &\text{maximize} && 17x_1 + 12x_2 \\
 &\text{subject to} && 10x_1 + 7x_2 \leq 40 \\
 &&& x_1 + x_2 \leq 5 \\
 &&& x_1 - x_2 \leq 3 \\
 &&& x_1, x_2, x_3 \geq 0
 \end{aligned}$$

<p>maximize $\zeta = 0 + 17x_1 + 12x_2$</p> <p>subject to: $w_1 = 40 - 10x_1 - 7x_2$</p> <p style="margin-left: 20px;">$w_2 = 5 - 1x_1 - 1x_2$</p> <p style="margin-left: 20px;">$w_3 = 3 - 1x_1 - 1x_2$</p> <p style="text-align: center; margin-top: 10px;">$x_1 \ x_2 \ w_1 \ w_2 \ w_3 \geq 0$</p>	<p>maximize $\zeta = 205/3 + (-1/3)w_2 + (-5/3)w_1$</p> <p>subject to: $x_2 = 10/3 - 10/3w_2 - 1/3w_1$</p> <p style="margin-left: 20px;">$w_3 = 14/3 - 17/3w_2 - 2/3w_1$</p> <p style="margin-left: 20px;">$x_1 = 5/3 - 7/3w_2 - 1/3w_1$</p> <p style="text-align: center; margin-top: 10px;">$x_1 \ x_2 \ w_1 \ w_2 \ w_3 \geq 0$</p>
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You are asked to use *the final dictionary* as so to incorporate each of the following separate new scenarios of the original problem¹

- (a) The problem is changed to a “mixed interger” programming where variable x_1 is further constrained to be an integer. Create an initial feasible dictionary to demonstrate how you would continue the problem.
- (b) Suppose the right hand side of the constraints are changed to $40 + a, 5 + b, 3 + c$.
 - i. Assuming a, b, c are small enough so that the optimal dictionary remains optimal. Find the rate of change of the optimal objective functional value ξ^* with respect to a, b, c , i.e. find $\frac{\partial \xi^*}{\partial a}, \frac{\partial \xi^*}{\partial b}, \frac{\partial \xi^*}{\partial c}$.
 - ii. Find condition(s) on the constants a, b, c such that the optimal dictionary remains optimal.
- (c) Suppose the coefficients in the objective function are changed to $17 + d, 12 + e$.
 - i. Assuming d, e are small enough so that the optimal dictionary remains optimal. Find the rate of change of the optimal objective functional value ξ^* with respect to d, e , i.e. find $\frac{\partial \xi^*}{\partial d}, \frac{\partial \xi^*}{\partial e}$.
 - ii. Find condition(s) on the constants d, e such that the optimal dictionary remains optimal.

¹You are told that your promotion will not go through if you only know how to start from scratch, i.e. the beginning dictionary.

19) (MI) Use Branch and Bound

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$$x_1 = 5/3$$

$$x_1 = 5/3 \Rightarrow \text{introduce } x_1 \leq 1, \quad x_2 \geq 2$$

$$z = \frac{205}{3} - \frac{1}{3}w_2 - \frac{5}{3}w_1$$

← try dual

$$x_2 = \frac{10}{3} - \frac{10}{3}w_2 + \frac{1}{3}w_1 \leftarrow y_1$$

$$w_3 = \frac{14}{3} - \frac{17}{3}w_2 + \frac{2}{3}w_1 \leftarrow y_2$$

$$x_1 = \frac{5}{3} + \frac{7}{3}w_2 - \frac{1}{3}w_1 \leftarrow y_3$$

$$x_1 \leq 1$$

$$\Rightarrow w_4 = 1 - x_1 = 1 - \frac{5}{3} - \frac{7w_2}{3} + \frac{w_1}{3}$$

$$w_4 = -\frac{2}{3} - \frac{7w_2}{3} + \frac{w_1}{3} \leftarrow y_4$$

< 0
not feasible

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\min \frac{10}{3}y_1 + \frac{14}{3}y_2 + \frac{5}{3}y_3 - \frac{2}{3}y_4$$

s.t.

$$\frac{10}{3}y_1 + \frac{17}{3}y_2 - \frac{7}{3}y_3 + \frac{7}{3}y_4 \geq -\frac{1}{3}$$

$$-\frac{1}{3}y_1 - \frac{2}{3}y_2 + \frac{1}{3}y_3 - \frac{1}{3}y_4 \geq -\frac{5}{3}$$

$$y_1, y_2, y_3, y_4 \geq 0$$

M2

Use Gomory cut.

You can use this blank page.

$$x_1 = \frac{5}{3} + \frac{7}{3}w_2 - \frac{1}{3}w_1$$

$$x_1 - \frac{7}{3}w_1 + \frac{1}{3}w_2 = \frac{5}{3}$$

$$x_1 - 3w_1 + 0w_2 = \frac{5}{3} - \frac{2}{3}w_1 - \frac{1}{3}w_2 \leq \frac{5}{3} \quad (\text{int}) \leq 1$$

$$\begin{aligned} w_4 &= 1 - \left(\frac{5}{3} - \frac{2}{3}w_1 - \frac{1}{3}w_2 \right) \\ &= -\frac{2}{3} + \frac{2}{3}w_1 + \frac{1}{3}w_2 \end{aligned}$$

$$z = \frac{205}{3} - \frac{1}{3}w_2 - \frac{5}{3}w_1$$

$$x_2 = \frac{10}{3} - \frac{10}{3}w_2 + \frac{1}{3}w_1$$

$$w_3 = \frac{14}{3} - \frac{17}{3}w_2 + \frac{2}{3}w_1$$

$$x_1 = \frac{5}{3} + \frac{7}{3}w_2 - \frac{1}{3}w_1$$

$$w_4 = -\frac{2}{3} + \frac{2}{3}w_1 + \frac{1}{3}w_2$$

$$\begin{aligned} \min \quad & \frac{10}{3}y_1 + \frac{14}{3}y_2 + \frac{5}{3}y_3 - \frac{2}{3}y_4 \\ \text{s.t.} \quad & \frac{10}{3}y_1 + \frac{17}{3}y_2 - \frac{7}{3}y_3 - \frac{2}{3}y_4 \\ & \geq -\frac{1}{3} \\ & -\frac{1}{3}y_1 - \frac{2}{3}y_2 + \frac{1}{3}y_3 - \frac{1}{3}y_4 \\ & \geq -\frac{5}{3} \\ & y_1, y_2, y_3, y_4 \geq 0 \end{aligned}$$

not feasible \Rightarrow try dual

You can use this blank page.

$$(b) \begin{matrix} x_1 & x_2 & w_1 & w_2 & w_3 \\ \begin{bmatrix} 10 & 7 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 1 \end{bmatrix} \end{matrix} \begin{bmatrix} x_1 \\ x_2 \\ w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} 40 + a \\ 5 + b \\ 3 + c \end{bmatrix}$$

$$B = \{x_2, w_3, x_1\}, \quad N = \{w_2, w_1\}$$

$$B = \begin{bmatrix} 7 & 0 & 10 \\ 1 & 0 & 1 \\ -1 & 1 & 1 \end{bmatrix}, \quad N = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$B^{-1}: \begin{bmatrix} 7 & 0 & 10 & | & 1 & 0 & 0 \\ 1 & 0 & 1 & | & 0 & 1 & 0 \\ -1 & 1 & 1 & | & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 7 & 0 & 10 & | & 1 & 0 & 0 \\ -1 & 1 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 3 & | & 1 & -7 & 0 \\ 0 & 1 & 2 & | & 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 2 & | & 0 & 1 & 1 \\ 0 & 0 & 1 & | & \frac{1}{3} & -\frac{7}{3} & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{3} & \frac{10}{3} & 0 \\ 0 & 1 & 0 & | & \frac{1}{3} & -\frac{5}{3} & 1 \\ 0 & 0 & 1 & | & \frac{1}{3} & -\frac{7}{3} & 0 \end{bmatrix}$$

$\underbrace{\left[\frac{1}{3} \quad \frac{10}{3} \quad 0 \right]}_{w_1 + w_2 + w_3} \quad \underbrace{\left[\frac{1}{3} \quad -\frac{5}{3} \quad 1 \right]}_{w_1 + w_2 + w_3} \quad \underbrace{\left[\frac{1}{3} \quad -\frac{7}{3} \quad 0 \right]}_{w_1 + w_2 + w_3}$

$\leftarrow B^{-1}$

You can use this blank page

$$B^{-1}N = \begin{pmatrix} -1 & \omega_1 \\ \omega_1 - \omega_2 & \omega_1 \\ \omega_1 - \omega_2 & \omega_1 \\ 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \omega_1 \\ \omega_1 + \omega_2 \\ \omega_1 \\ \omega_1 - \omega_2 \\ \omega_1 \end{pmatrix}$$

the same as given in the opt. dict.

(ii)

$$\begin{aligned} \Delta Z^* &= C_B^T B^{-1} \Delta b - ((B^{-1}N)^T C_B - C_N)^T X_N \\ &= \underbrace{\begin{pmatrix} 12 & 0 & 17 \end{pmatrix}}_{C_B} \begin{pmatrix} -1 & \omega_1 \\ \omega_1 - \omega_2 & \omega_1 \\ \omega_1 - \omega_2 & \omega_1 \\ 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \\ &= \begin{pmatrix} \omega_1 & \omega_1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \omega_1 2a + \omega_1 b \end{aligned}$$

y_1^*

y_2^*

shadow price

$\frac{\partial Z^*}{\partial a} = \frac{15}{3}$	$\frac{\partial Z^*}{\partial b} = \frac{1}{3}$	$\frac{\partial Z^*}{\partial c} = 0$
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(ii) We need $B^{-1}b \geq 0$

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$$\begin{pmatrix} \frac{1}{3} & \frac{10}{3} & 0 \\ -\frac{2}{3} & \frac{17}{3} & 1 \\ \frac{1}{3} & -\frac{7}{3} & 0 \end{pmatrix} \begin{pmatrix} 40+a \\ 5+b \\ 3+c \end{pmatrix} \geq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\left. \begin{aligned} \frac{40+a}{3} + \frac{10(5+b)}{3} &\geq 0 \\ -\frac{2(40+a)}{3} + \frac{17(5+b)}{3} + (3+c) &\geq 0 \\ \frac{1}{3}(40+a) - \frac{7}{3}(5+b) &\geq 0 \end{aligned} \right\}$$

$$\Leftrightarrow \begin{cases} a+10b \geq -90 \\ -2a+17b+3c \geq 80-85-9 = -14 \\ a-7b \geq 35-40 = -5 \end{cases}$$

$$\Leftrightarrow \begin{cases} a+10b \geq -90 \\ -2a+17b+3c \geq -14 \\ a-7b \geq -5 \end{cases}$$

$$J^* = C_B^T B^{-1} b - (C_B^T B^{-1} C_N - C_N^T) x_N$$

You can use this blank page.

$$\Delta J^* = (\Delta C_B^T) B^{-1} b$$

$$= (e \quad 0 \quad d) \begin{pmatrix} 10 \\ 3 \\ 14 \\ 3 \\ 5 \\ 3 \end{pmatrix} = \frac{10}{3}e + \frac{d5}{3}$$

$$\frac{\partial J^*}{\partial d} = \frac{5}{3}, \quad \frac{\partial J^*}{\partial e} = \frac{10}{3}$$

Shadow prices

We need $(B^{-1} C_B)^T C_B - C_N \geq 0$

$$\begin{pmatrix} \frac{10}{3} & \frac{17}{3} & -\frac{7}{3} \\ -\frac{1}{3} & \frac{1}{2} & \frac{1}{3} \end{pmatrix} \begin{pmatrix} 12+e \\ 0 \\ 17+d \end{pmatrix} \geq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} 120 + 10e - 119 - 7d &\geq 0 \\ -12 - e + 17 + d &\geq 0 \end{aligned} \iff \begin{cases} 10e - 7d \geq -1 \\ -e + d \geq -5 \end{cases}$$