

# Existence of (local) Stable Manifold $W_{loc}^s(0)$ (for hyperbolic system)

$$\frac{d}{dt} X = AX + g(X)$$

$$|g(X)| \sim O(|X|^2) \ll |X| \\ \text{for } |X| \ll 1$$

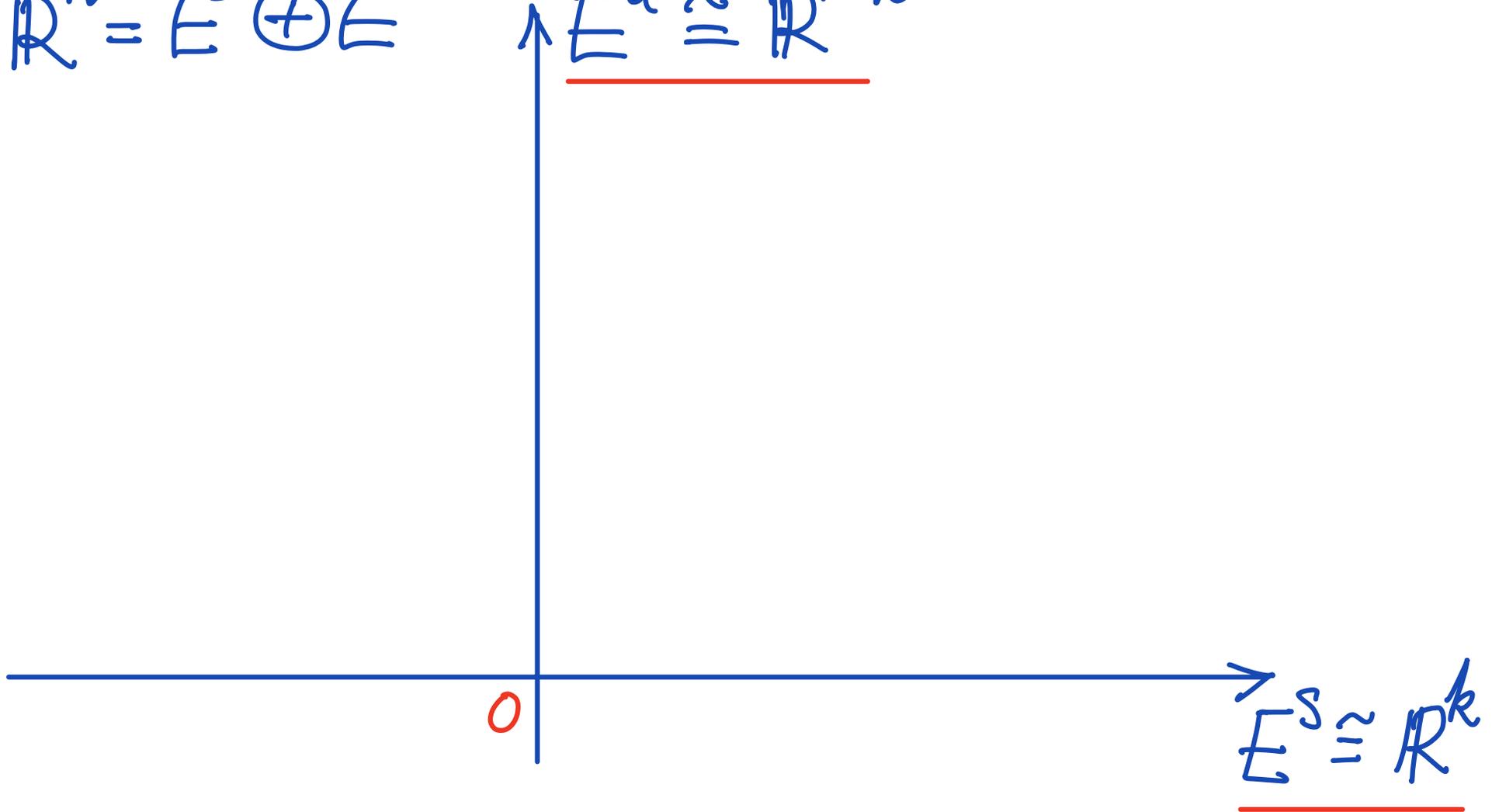
$$(X \in \mathbb{R}^n, A^{n \times n})$$

- (1)  $A$  is hyperbolic:  $\operatorname{Re}(\lambda_i(A)) \neq 0$
- (2)  $E^s =$  stable subspace:  $\dim(E^s) = k$
- (3)  $E^u =$  unstable subspace:  $\dim(E^u) = n - k$

Existence of (local) Stable Manifold  $W_{loc}^s(0)$   
(for hyperbolic system)

$$\mathbb{R}^n = E^s \oplus E^u$$

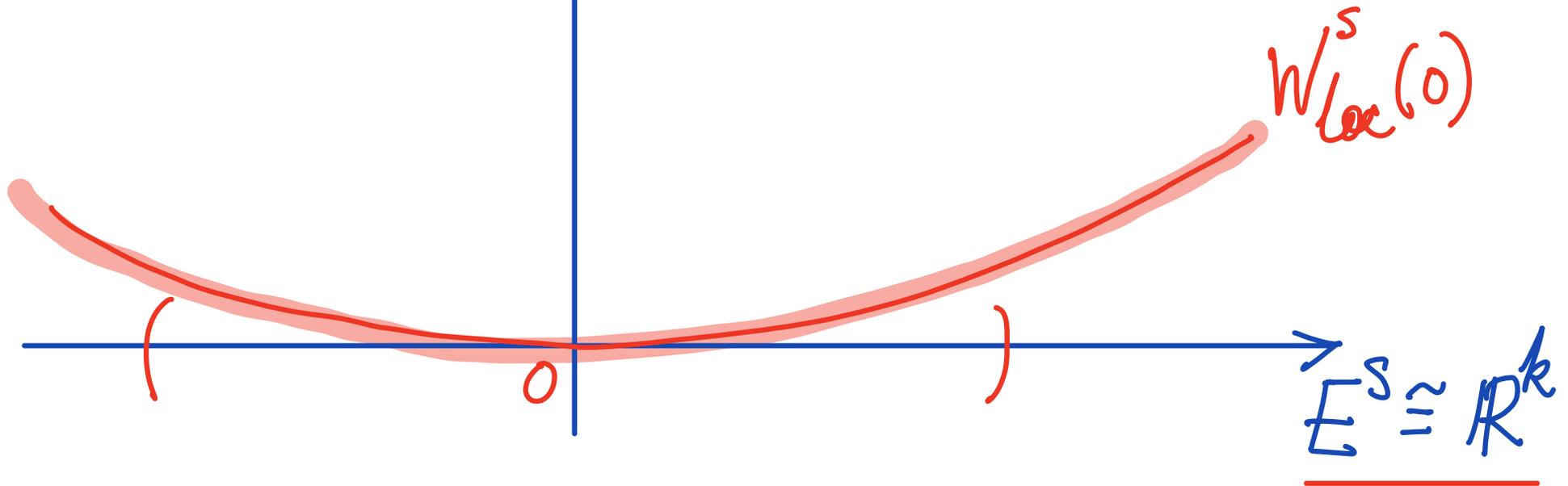
$$\underline{E^u \cong \mathbb{R}^{n-k}}$$



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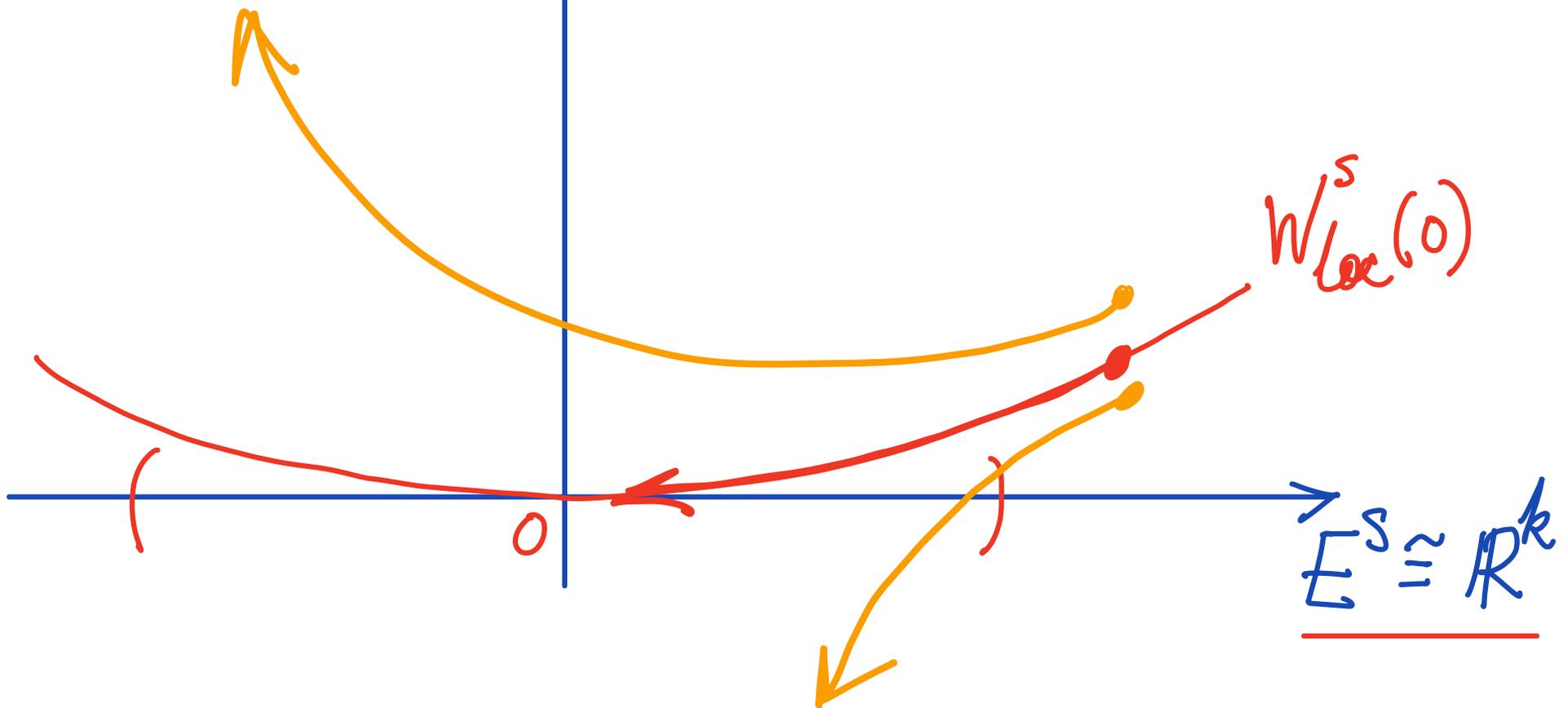
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$$\underline{E^u \cong \mathbb{R}^{n-k}}$$



## Existence of (local) Stable Manifold $W_{loc}^S(0)$

[M, Thm 5.9, p. 169] (for hyperbolic system)

There is a unique manifold  $W_{loc}^S(0)$  in a neighborhood of 0 satisfying:

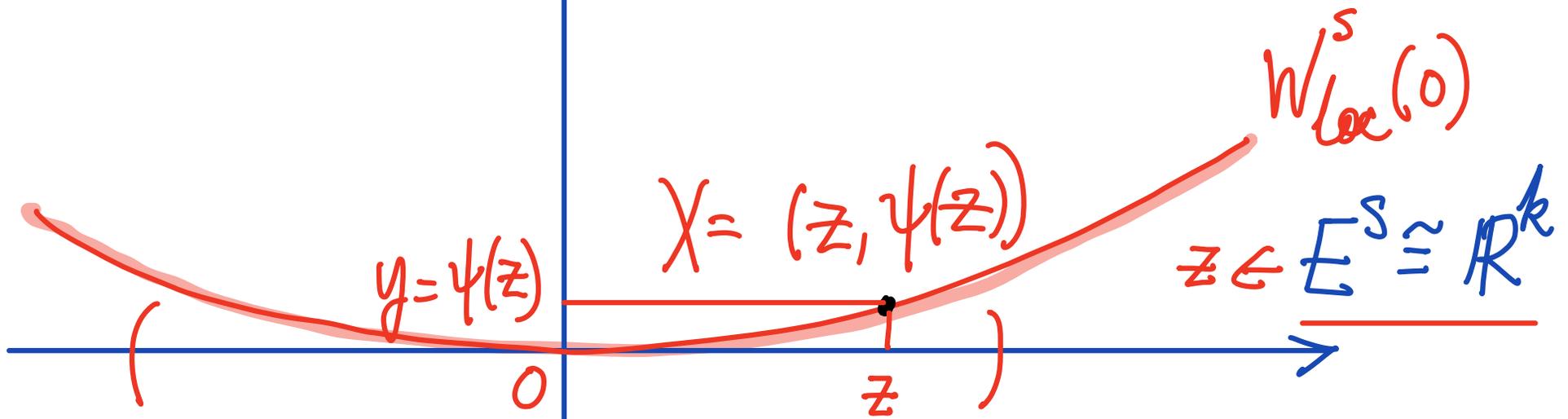
- (1)  $W^S(0)$  is invariant under the flow;  
( $x \in W^S(0) \Rightarrow \phi_t(x) \in W^S(0)$  for all  $t > 0$ )
- (2)  $W^S(0)$  passes through 0 and is tangent to  $E^S$  at 0
- (3)  $\dim(W^S(0)) = k = \dim(E^S)$
- (4) if  $x \in W^S(0)$ , then  $\phi_t(x) \xrightarrow{t \rightarrow +\infty} 0$

# Existence of (local) Stable Manifold $W_{loc}^s(0)$ (for hyperbolic system)

① Write  $W_{loc}^s(0)$  as a graph over  $E^s \cong \mathbb{R}^k$ :

$$\mathbb{R}^n = E^s \oplus E^u$$

$$E^u \cong \mathbb{R}^{n-k}$$



# Existence of (local) Stable Manifold $W_{loc}^s(0)$ (for hyperbolic system)

① Write  $W_{loc}^s(0)$  as a graph over  $E^s \cong \mathbb{R}^k$ :

$$\left\{ \begin{array}{l} W_{loc}^s(0) = \{ (z, \psi(z)) : z \in E^s \cong \mathbb{R}^k \} \\ \psi : \mathbb{R}^k (E^s) \longrightarrow \mathbb{R}^{n-k} (E^u) \\ \psi(0) = 0, \\ D\psi(0) = 0, \text{ i.e. } |\psi(z)| \leq C|z|^2 \end{array} \right.$$

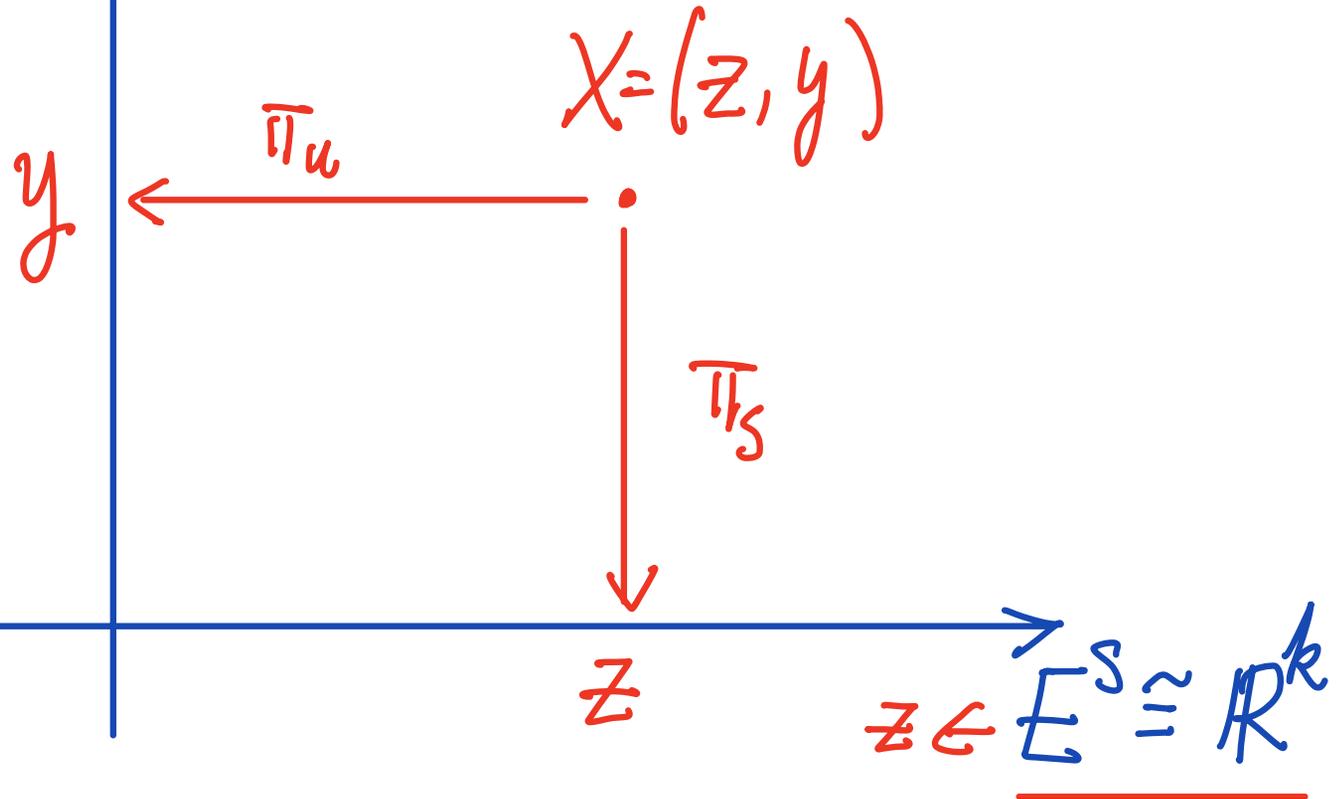
# Existence of (local) Stable Manifold $W_{loc}^s(0)$ (for hyperbolic system)

②  $\mathbb{R}^n = E^s \oplus E^u$

$E^u \cong \mathbb{R}^{n-k}$

Projection:

$$z = \pi_s X$$
$$y = \pi_u X$$



# Existence of (local) Stable Manifold $W_{loc}^s(0)$ (for hyperbolic system)

There is  $K, \lambda > 0$  such that

for any  $x_0 \in \mathbb{R}^n \cong E^s \oplus E^u$ ,

$$\|e^{At} \Pi_s x_0\| < K e^{-\lambda t} \|x_0\| \text{ for } t > 0$$

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$$\|e^{At} \Pi_u x_0\| < K e^{\lambda t} \|x_0\| \text{ for } t < 0$$

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# Existence of (local) Stable Manifold $W_{loc}^s$ (d) (for hyperbolic system)

③

(a) Consider nonlinear equation as a  
linear equation with inhomogeneous term:

$$\frac{dX(t)}{dt} = \underbrace{AX(t)}_{\text{linear equation}} + \underbrace{g(X(t))}_{\text{inhomogeneous term}}$$

(b) And then use fixed point theorem.

# Linear Inhomogeneous Equation (M, Lemma 5.8)

(I) Consider  $\dot{X} = AX + \gamma(t), \quad \Pi_s X(0) = \sigma$

(1)  $A$  is hyperbolic ( $\operatorname{Re}(\lambda_i(A)) \neq 0$ )

for all  $t \geq 0$   
↓

(2)  $\gamma: \mathbb{R}_+ \rightarrow \mathbb{R}^n$  is bounded ( $\|\gamma(t)\| \leq M < \infty$ )

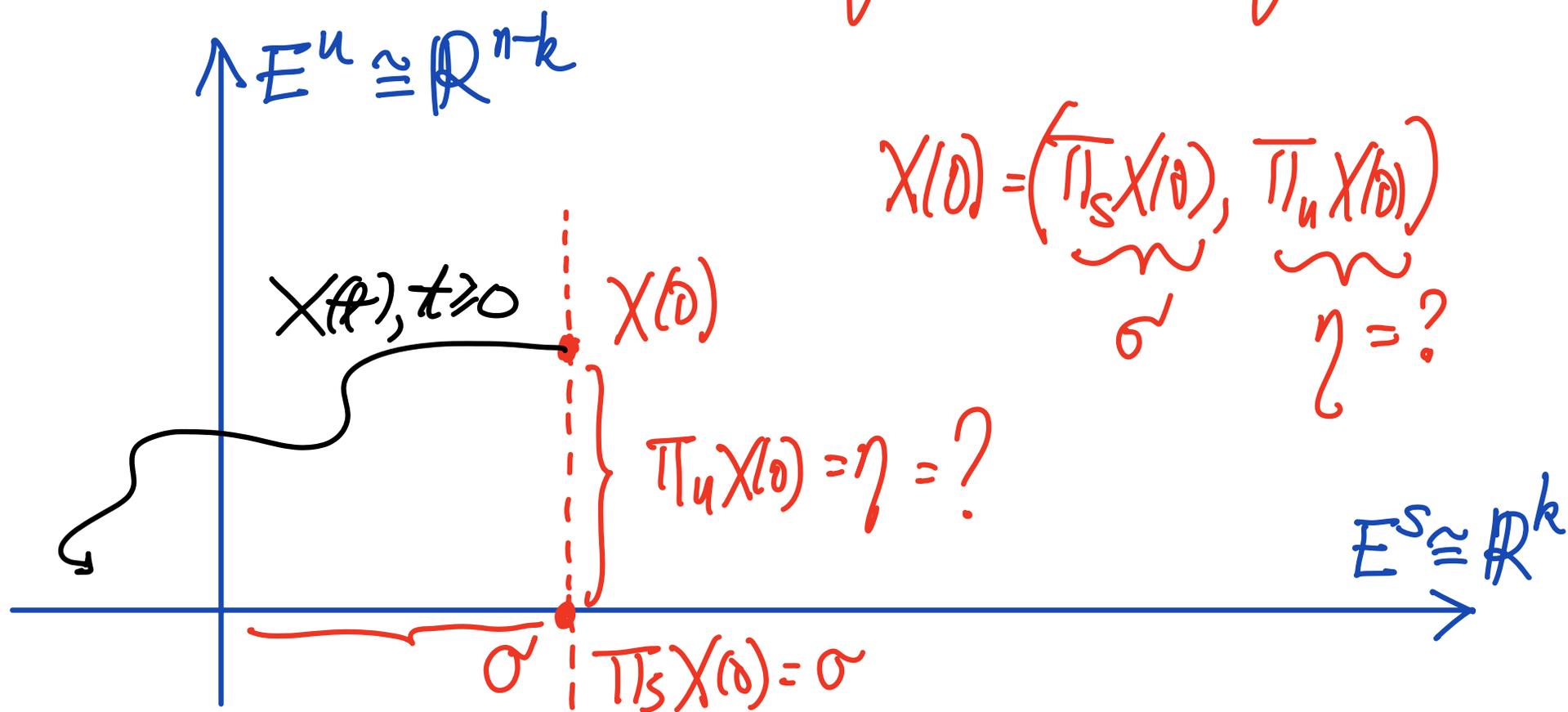
Then  $\exists!$  bounded solution  $X(t), t \geq 0$ , given by

$$X(t) = e^{tA}\sigma + \int_0^t e^{(t-s)A} \Pi_s \gamma(s) ds - \int_t^\infty e^{(t-s)A} \Pi_u \gamma(s) ds$$

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$\downarrow$   
 $t=0$

$$X(0) = \underbrace{\sigma}_{\sigma \in E^S} - \underbrace{\int_0^\infty e^{-As} \Pi_U \gamma(s) ds}_{\eta \in E^U}$$

# Nonlinear Version (II)

$$\frac{dX}{dt} = AX + \underbrace{g(X)}_{\gamma(t)}, \quad X(0) = (\underbrace{\sigma}_{\text{given}}, \underbrace{\eta}_{?})$$

$\eta = \eta(\sigma)$

Given  $\sigma$ , choose  $\eta = \eta(\sigma)$  s.t.  $X(t) \xrightarrow{t \rightarrow +\infty} 0$

$$\textcircled{1} \quad X(t) = e^{At} \sigma + \int_0^t e^{A(t-s)} \pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \pi_u g(X(s)) ds$$

$$\textcircled{2} \quad \eta = \eta(\sigma) = - \int_0^\infty e^{-As} \pi_u g(X(s)) ds$$

# Banach Fixed Point Theorem (II)

Define Let  $X: t \in \mathbb{R}_+ \longrightarrow X(t) \in \mathbb{R}^n$

$$(TX)(t) = e^{tA}\sigma + \int_0^\infty e^{A(t-s)} \pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \pi_u g(X(s)) ds$$

$$X(t) = e^{At}\sigma + \int_0^t e^{A(t-s)} \pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \pi_u g(X(s)) ds$$



X is a fixed pt. of T:

$$\text{i.e. } X = TX$$

or,  $X(t) = (TX)(t)$

# Banach Fixed Point Theorem (II)

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$$(TX)(t) = e^{tA} \sigma + \int_0^\infty e^{A(t-s)} \Pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \Pi_u g(X(s)) ds$$

Let  $\delta > 0$ .  $C_\delta = \left\{ X: X(t) \in \mathbb{R}^n, t \geq 0, \text{ continuous} \right\}$   
 $\left\{ \text{in } t, \forall \|X(t)\| < \delta \right\}$

Then there is a unique fixed pt.  $X \in C_\delta$ , i.e.  $X = TX$ ,

$$X(t) = e^{tA} \sigma + \int_0^t e^{A(t-s)} \Pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \Pi_u g(X(s)) ds$$

# Banach Fixed Point Theorem (II)

Define Let  $X: t \in \mathbb{R}_+ \longrightarrow X(t) \in \mathbb{R}^n$

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 $\left\{ \text{in } t, \forall \|X(t)\| < \delta \right\}$

- (1)  $T: C_\delta \longrightarrow C_\delta$  *contraction map*
- (2)  $\|TX - TY\| \leq C \|X - Y\|$ , for some  $0 < C < 1$

# Banach Fixed Point Theorem (II)

## Two Properties of $g(x)$

$$\|g(x)\| \leq O(|x|^2) \ll |x| \text{ for } |x| \ll 1$$

(1)  $\forall \varepsilon > 0, \exists \delta > 0$  such that

if  $\|x\| \leq \delta$ , then  $\|g(x)\| \leq \varepsilon \|x\|$

(2)  $\forall \varepsilon > 0, \exists \delta > 0$  such that

if  $\|x\|, \|y\| \leq \delta$ , then

$$\|g(x) - g(y)\| \leq \varepsilon \|x - y\|$$

# Banach Fixed Point Theorem (II)

## Recap on the notion of norms

$$\textcircled{1} X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n,$$

$$\|X\| = \sqrt{x_1^2 + \dots + x_n^2}$$

$$\textcircled{2} X = \{X(t)\} \in C^0(\mathbb{R}_+, \mathbb{R}^n)$$

$$\|X\|_{C^0(\mathbb{R}_+, \mathbb{R}^n)} = \sup_{t \in \mathbb{R}_+} \|X(t)\|$$

# Properties of the fixed point $X$ (III)

$$X(t) = e^{tA} \sigma + \int_0^t e^{A(t-s)} \Pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \Pi_u g(X(s)) ds$$

Given  $\sigma \in E$ ,

$\Rightarrow X = TX$ , fixed pt

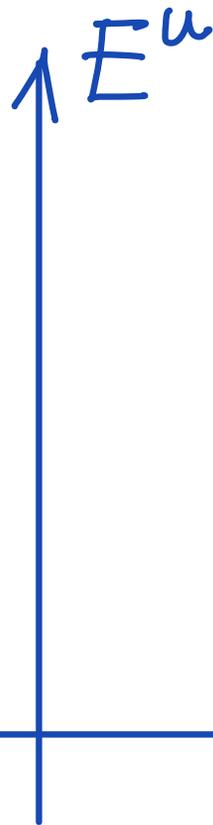
$$\Rightarrow X(0) = \sigma - \underbrace{\int_0^\infty e^{-As} \Pi_u g(X(s)) ds}_{\text{red arrow } ?}$$

$\Rightarrow$  a map:  $\sigma \rightarrow \eta = \eta(\sigma)$

# Properties of the fixed point $X$ (III)

$$X(t) = e^{tA} \sigma + \int_0^t e^{A(t-s)} \Pi_s g(X(s)) ds - \int_t^\infty e^{A(t-s)} \Pi_u g(X(s)) ds$$

$\downarrow t=0$



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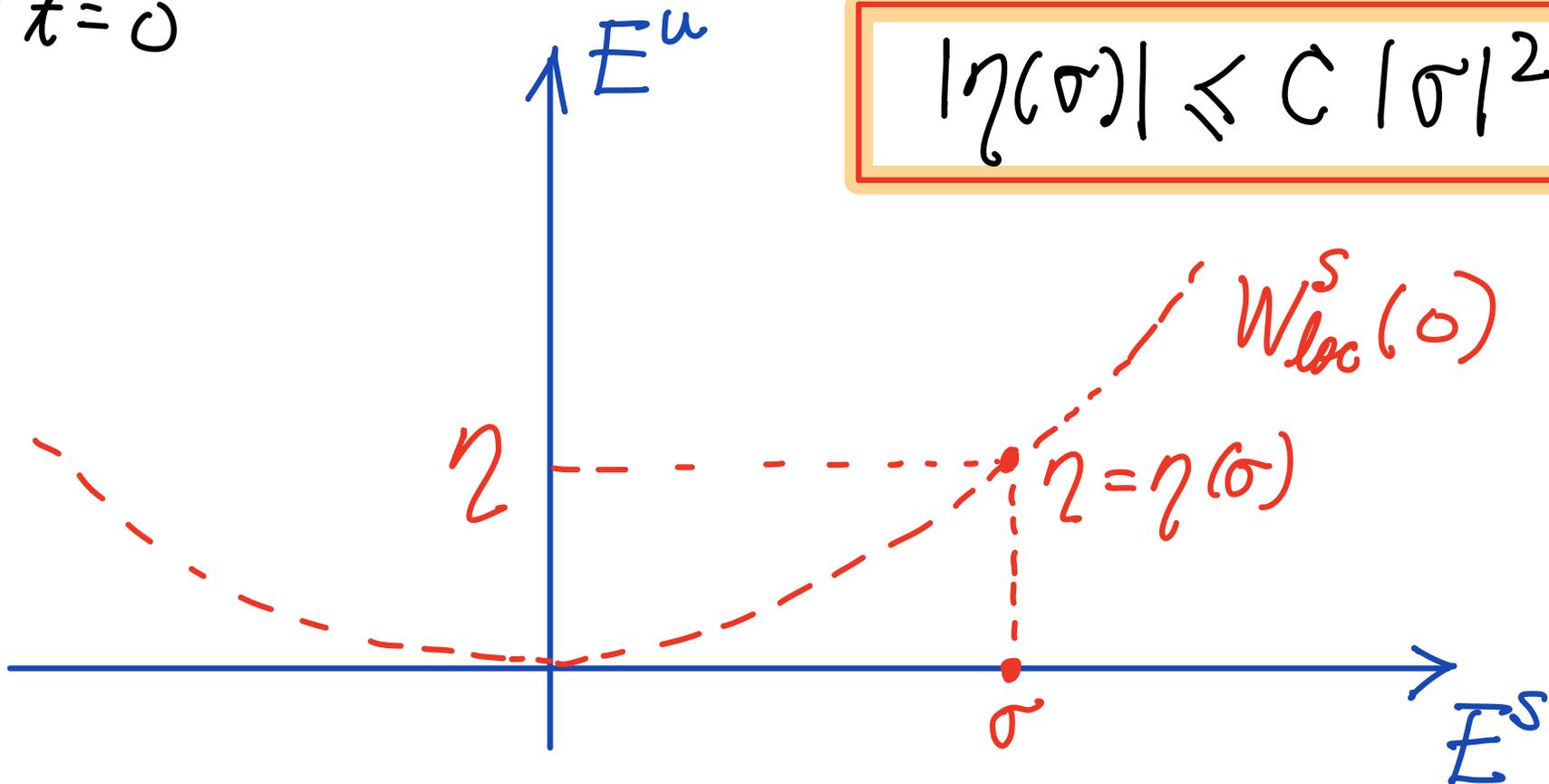
# Properties of the fixed point $X$ (III)

$$X(t) = e^{tA} \sigma + \int_0^t e^{A(t-s)} \frac{\partial}{\partial s} g(X(s)) ds - \int_t^\infty e^{A(t-s)} \frac{\partial}{\partial s} g(X(s)) ds$$

$\downarrow t=0$

$$|\eta(\sigma)| \leq C |\sigma|^2$$

(7)



# Properties of the fixed point $X$ (III)

$$X(t) = e^{tA} \sigma + \int_0^t e^{A(t-s)} \frac{1}{\Gamma(s)} g(X(s)) ds - \int_t^\infty e^{A(t-s)} \frac{1}{\Gamma(u)} g(X(s)) ds$$

$$|X(t)| \leq a e^{-bt} \text{ for } t \geq 0$$

②

for some  $a, b > 0$

# Properties of the fixed point $X$ (III)

## Generalized Gronwall (M, Lemma 3.10, P. 170)

Let  $u: \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a bounded function s.t.

$$u(t) \leq e^{-\alpha t} M + L \int_0^t e^{-\alpha(t-s)} u(s) ds + L \int_t^\infty e^{-\alpha(t-s)} u(s) ds$$

$$(\alpha, M, L > 0, L < \frac{\alpha}{3})$$

Then

$$u(t) \leq \frac{M}{\beta} e^{-(\alpha - \frac{L}{\beta})t}, \quad \beta = 1 - \frac{2L}{\alpha}$$