

[M] Sec. 2.9 #2

HW #1

$$H(x,y) = \frac{1}{2}(y^2 - x^2) + xy$$

$$\dot{x} = H_y = x + y$$

$$\dot{y} = -H_x = x - y$$

$$\begin{pmatrix} x \\ y \end{pmatrix}' = \underbrace{\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}}_A \begin{pmatrix} x \\ y \end{pmatrix}$$

(Note:  $A$  is symmetric  $A^T = A$ )

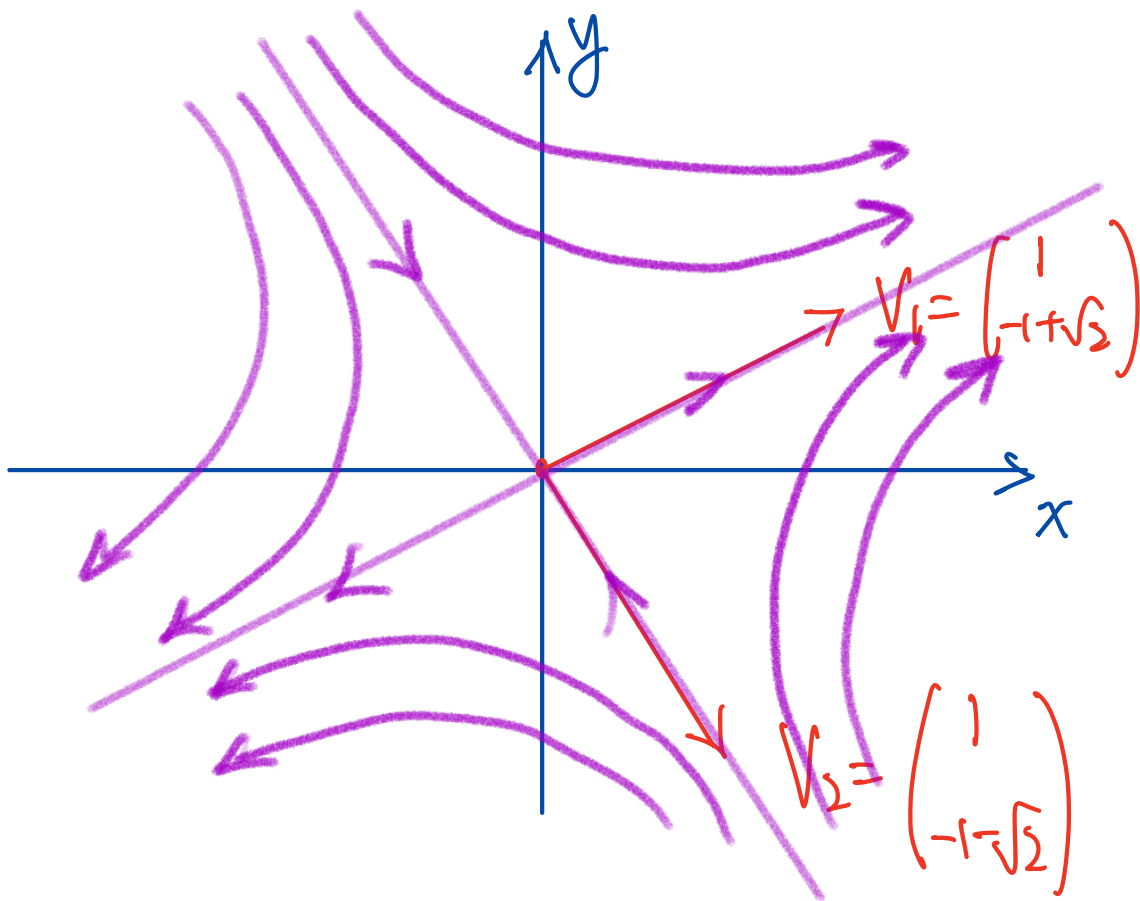
$$\det(A - \lambda I) = 0 \Rightarrow (\lambda + 1)(\lambda - 1) = 0$$
$$\lambda^2 - 1 = 0$$
$$\lambda = \pm \sqrt{2}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 + \sqrt{2} \end{bmatrix} = \sqrt{2} \begin{bmatrix} 1 \\ -1 + \sqrt{2} \end{bmatrix} \quad \leftarrow V_1$$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 - \sqrt{2} \end{bmatrix} = -\sqrt{2} \begin{bmatrix} 1 \\ -1 - \sqrt{2} \end{bmatrix} \quad \leftarrow V_2$$

(Note:  $V_1 \perp V_2$ :  $(1)^2 + (-1 + \sqrt{2})(-1 - \sqrt{2}) = 0$ )

General solution:  $\chi(t) = c_1 e^{\sqrt{2}t} V_1 + c_2 e^{-\sqrt{2}t} V_2$



$H(x,y) = C \quad \leftarrow \quad C\text{-level curve of } H$

$$\frac{1}{2} (y^2 - x^2) + xy = C$$

$$-x^2 + 2xy + y^2 = \textcircled{2C}^C$$

$$\begin{pmatrix} x & y \end{pmatrix} \underbrace{\begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}}_{M} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$M \quad (M = M^T)$$

$$\det(M - \lambda I) = \lambda^2 - 2 = 0, \quad \lambda = \pm\sqrt{2}$$

$$\begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1+\sqrt{2} \end{pmatrix} = \sqrt{2} \begin{pmatrix} 1 \\ 1+\sqrt{2} \end{pmatrix} \leftarrow U_1$$

$$\begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1-\sqrt{2} \end{pmatrix} = -\sqrt{2} \begin{pmatrix} 1 \\ 1-\sqrt{2} \end{pmatrix} \leftarrow U_2$$

Normalize  $U_1, U_2$  :  $U_1 \rightarrow \hat{U}_1 = \frac{U_1}{\|U_1\|}$

$$U_2 \rightarrow \hat{U}_2 = \frac{U_2}{\|U_2\|}$$

Diagonalize  $M$  :

$$M = \underbrace{\begin{bmatrix} \hat{U}_1 & \hat{U}_2 \end{bmatrix}}_{Q} \begin{bmatrix} \sqrt{2} & \\ & -\sqrt{2} \end{bmatrix} \underbrace{\begin{bmatrix} \hat{U}_1 & \hat{U}_2 \end{bmatrix}^T}_{Q^T}$$

$Q$  "orthogonal matrix"

$$H(x, y) = \begin{pmatrix} x & y \end{pmatrix} M \begin{pmatrix} x \\ y \end{pmatrix} = x^T M x$$

$$= x^T Q \Lambda Q^T x$$

$$= (Q^T x)^T \Lambda (Q^T x)$$

$$= \tilde{x}^T \Lambda \tilde{x}$$

$$\tilde{x} = Q^T x$$

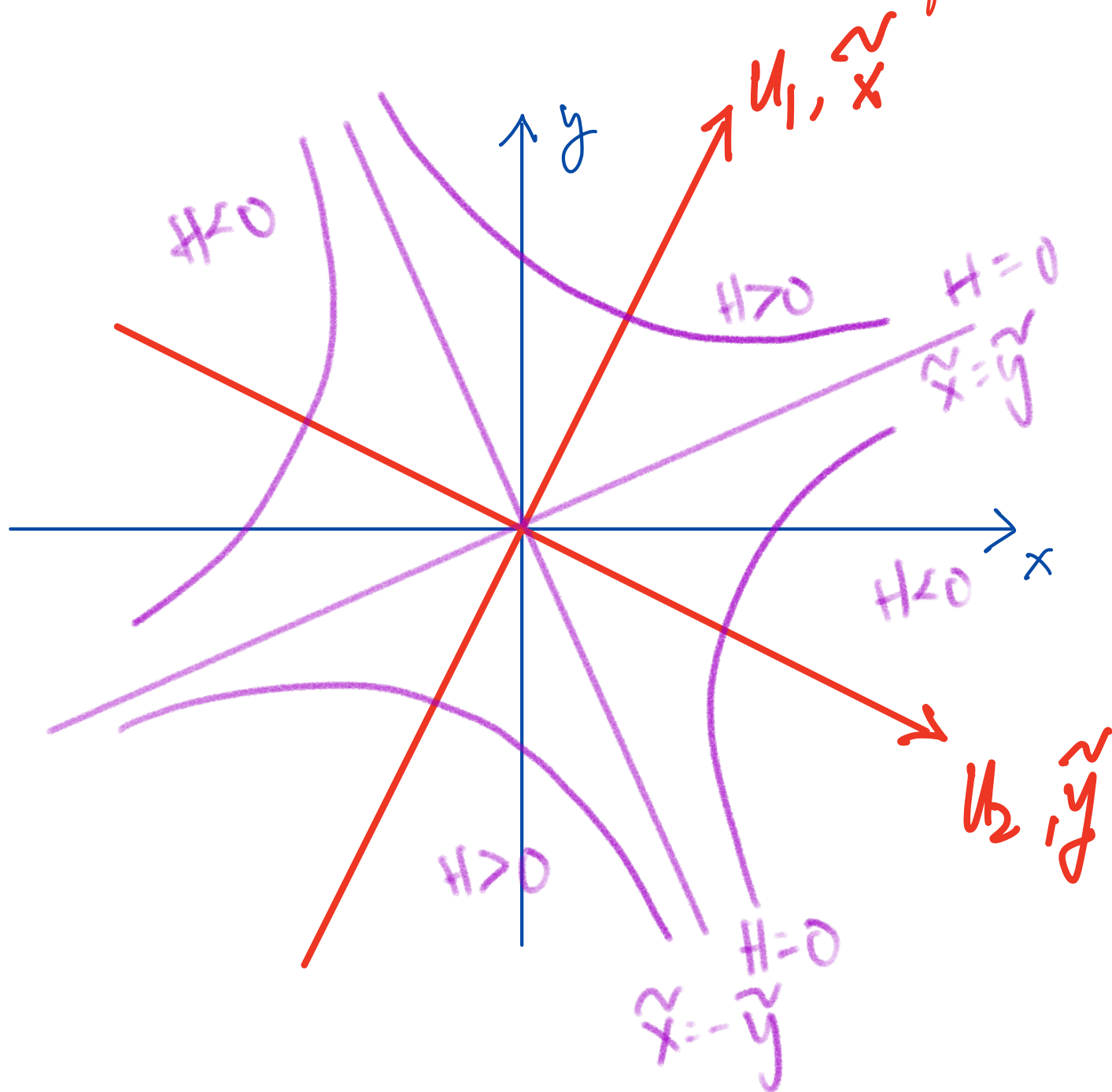
$$\text{Let } \tilde{X} = \begin{pmatrix} \tilde{x} \\ \tilde{y} \end{pmatrix} = Q^T X = Q^T \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\text{Then } H(x, y) = \frac{1}{2}(y^2 - x^2) + xy = \sqrt{2} \tilde{x}^2 - \sqrt{2} \tilde{y}^2$$

$$\text{Hence } H = c \Leftrightarrow$$

$$\tilde{x}^2 - \tilde{y}^2 = \frac{c}{2}$$

Hyperbola  
in the  $\tilde{x}\tilde{y}$ -  
plane



[M] Sec. 2.9 #19(c)  $\begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} 1 & t \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$

$$y' = -y \Rightarrow y(t) = e^{-t} y_0$$

$$\underline{x'} = x + ty = \underline{x + t e^{-t} y_0}$$

$$\Rightarrow x(t) = e^t x_0 + \int_0^t e^{(t-s)} s e^{-s} y_0 ds$$

$$= e^t x_0 + e^t y_0 \int_0^t s e^{-2s} ds$$

$$= e^t x_0 + e^t y_0 \int_0^t s \frac{d e^{-2s}}{-2} \Big|_0^t$$

$$= e^t x_0 + e^t y_0 \left[ \frac{s e^{-2s}}{-2} \Big|_0^t + \frac{1}{2} \int_0^t e^{-2s} ds \right]$$

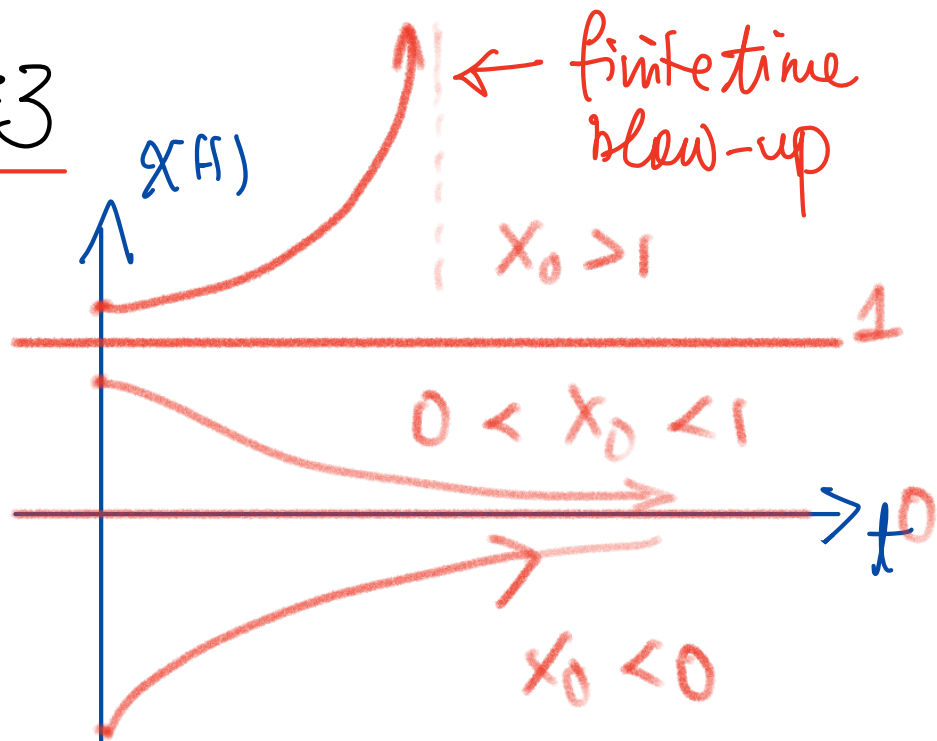
$$= e^t x_0 + e^t y_0 \left[ \frac{t e^{-2t}}{-2} - \frac{1}{4} (e^{-2t} - 1) \right]$$

$$[\Phi(t)] = e^t x_0 + \left[ -\frac{1}{2} t e^{-t} - \frac{1}{4} e^{-t} + \frac{1}{4} e^t \right] y_0$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \underbrace{\begin{pmatrix} e^t & -\frac{1}{2} t e^{-t} - \frac{1}{4} e^{-t} + \frac{1}{4} e^t \\ 0 & e^{-t} \end{pmatrix}} \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

# HW #1 Prob #3

$$\dot{x} = -x + x^2$$



$$\frac{dx}{x^2 - x} = dt$$

$$\frac{dx}{x(x-1)} = dt$$

$$\int \frac{1}{x-1} - \frac{1}{x} dx = \int dt$$

$$\ln \left| \frac{x-1}{x} \right| \Big|_{x_0}^x = t$$

$$\ln \left| \frac{x-1}{x} \right| - \ln \left| \frac{x_0-1}{x_0} \right| = t$$

①  $X_0 > 1 \Rightarrow X(t) > 1$

$$\ln\left(\frac{x-1}{x}\right) - \ln\left(\frac{x_0-1}{x_0}\right) = t$$

$$\frac{x-1}{x} = \frac{x_0-1}{x_0} e^t$$

$$x-1 = \left(\frac{x_0-1}{x_0}\right) e^t x$$

$$x = \frac{1}{1 - \left(\frac{x_0-1}{x_0}\right) e^t} = +\infty \text{ as } t = \ln\left(\frac{x_0}{x_0-1}\right)$$

finite time blow up

②  $0 < X_0 < 1 \Rightarrow 0 < X(t) < 1$

$$\ln\left(\frac{1-x}{x}\right) - \ln\left(\frac{1-x_0}{x_0}\right) = t$$

$$\frac{1-x}{x} = \frac{1-x_0}{x_0} e^t$$

$$1-x = \frac{1-x_0}{x_0} e^t x$$

$$x(t) = \frac{1}{1 + \left(\frac{1-x_0}{x_0}\right) e^t} \quad \xrightarrow{\text{as } t \rightarrow +\infty} 0$$

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$$x_0 < 0 \Rightarrow x(t) < 0$$

$$\ln\left(\frac{x-1}{x}\right) - \ln\left(\frac{x_0-1}{x_0}\right) = t$$

$$x = \frac{1}{1 - \left(\frac{x_0-1}{x_0}\right) e^t} \quad \xrightarrow{\text{as } t \rightarrow +\infty} 0$$

Note:  $\frac{x_0-1}{x_0} > 1$   
 Hence  $1 - \left(\frac{x_0-1}{x_0}\right) e^t \neq 0$  for all  $t$

## HW #1 Prob #4

(a) Let  $\frac{d\Phi}{dt} = A(t)\Phi, \quad \Phi(0) = I$

$$\frac{d\bar{\Phi}}{dt} = -\bar{\Phi}A(t), \quad \bar{\Phi}(0) = I$$

Consider

$$\begin{aligned} \frac{d}{dt}(\bar{\Phi}\Phi) &= \dot{\bar{\Phi}}\Phi + \bar{\Phi}\dot{\Phi} \\ &= -\bar{\Phi}A\Phi + \bar{\Phi}A\Phi \\ &= 0 \end{aligned}$$

Hence  $\bar{\Phi}(t)\Phi(t) = \bar{\Phi}(0)\Phi(0) = I$

$$\Rightarrow \bar{\Phi}(t) = \Phi(t)^{-1}$$

(b)  $\det(\Phi(t)) = e^{\int_0^t \text{tr} A(s) ds} \neq 0$

$$\Rightarrow \Phi(t)^{-1} \text{ exists.}$$

#2

Hw #2

(b)

$$e^{At}e^{Bt} = e^{(A+B)t} \quad \forall t$$

 $\frac{d}{dt}$ 

$$Ae^{At}e^{Bt} + e^{At}Be^{Bt} = (A+B)e^{(A+B)t}$$

 $\frac{d}{dt}$ 

$$A^2e^{At}e^{Bt} + 2Ae^{At}Be^{Bt} + e^{At}B^2e^{Bt}$$

$$= (A+B)^2 e^{(A+B)t}$$

 $t=0$ 

$$\cancel{A^2} + 2AB + \cancel{B^2} = (A+B)^2 = (A+B)(A+B)$$

$$= \cancel{A^2} + AB + BA + \cancel{B^2}$$

$$\Rightarrow \underline{AB = BA}$$

(c)

$$e^{At}e^{Bt} = e^{(A+B)t}$$

$$\left( I + At + \frac{A^2 t^2}{2} + \dots \right) \left( I + Bt + \frac{B^2 t^2}{2} + \dots \right)$$

$$= I + (A+B)t + \underline{\frac{(A+B)^2 t^2}{2}} + \dots$$

$$LHS = I + (A+B)t + \underbrace{\left(\frac{B^2}{2} + AB + \frac{A^2}{2}\right)t^2 + \dots}$$

$$\text{Hence } (A+B)^2 = B^2 + 2AB + A^2$$

$$\begin{array}{ccc} (A+B) & // & \\ (A+B) & // & \\ & // & \end{array} \Rightarrow \underline{AB=BA}$$

$$A^2 + AB + BA + B^2$$

$$\#4 \quad \begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{pmatrix} = \begin{pmatrix} -3 & a & b \\ 0 & -2 & c \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\dot{z} = -2z \Rightarrow z(t) = z_0 e^{-2t}$$

$$\dot{y} = -2y + cz = -2y + c z_0 e^{-2t}$$

$$y(t) = e^{-2t} y_0 + \int_0^t e^{-2(t-s)} c z_0 e^{-2s} ds$$

$$= e^{-2t} y_0 + c z_0 e^{-2t} \int_0^t ds$$

$$= e^{-2t} y_0 + c z_0 e^{-2t} t$$

$$\dot{x} = -3x + ay + bz$$

$$= -3x + a y_0 e^{-2t} + a c z_0 e^{-2t} t + b z_0 e^{-2t}$$

$$x(t) = e^{-3t} x_0$$

$$+ \int_0^t e^{-3(t-s)} [a y_0 e^{-2s} + a c z_0 e^{-2s} s + b z_0 e^{-2s}] ds$$

$$= e^{-3t} x_0 + e^{-3t} \int_0^t [a y_0 e^s + a c z_0 s e^s + b z_0 e^s] ds$$

$$= e^{-3t} x_0 + e^{-3t} \int_0^t (a y_0 + a c z_0 s + b z_0) e^s ds$$

$$= e^{-3t} x_0 + e^{-3t} \left[ \int (a y_0 + a c z_0 s + b z_0) de^s \right]_0^t$$

$$= e^{-3t} x_0 + e^{-3t} \left[ (a y_0 + a c z_0 t + b z_0) e^t - (a y_0 + b z_0) - \int_0^t e^s a c z_0 ds \right]$$

$$= \cancel{e^{-3t}} \underline{x_0} + e^{-3t} \left[ (\cancel{a y_0} + \cancel{a c z_0} t + \cancel{b z_0}) e^t - \cancel{(a y_0 + b z_0)} - \cancel{a c z_0} (\cancel{e^t} - \underline{1}) \right]$$

$$= (x_0 - a y_0 - b z_0 + a c z_0) e^{-3t}$$

$$+ (a y_0 + b z_0 - a c z_0 + \underline{a c z_0 t}) e^{-2t}$$

Solution:

$$\left\{ \begin{aligned} x(t) &= (x_0 - ay_0 - bz_0 + acz_0) e^{3t} \\ &\quad + (ay_0 + bz_0 - acz_0 + \underline{acz_0 t}) e^{-2t} \\ y(t) &= e^{-2t} y_0 + \underline{cz_0 e^{-2t} t} \\ z(t) &= e^{-2t} z_0 \end{aligned} \right.$$

Because of the  $t e^{-2t}$  terms

$$\left\| \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} \right\| \leq C_K \left\| \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} \right\| e^{-Kt}$$

for some  $0 < \underline{K} < 2$

Depends on  $K$ ,  $C_K \rightarrow \infty$  as  $K \rightarrow 2$

IM Sec 4.13 #9]

HW#3

$$[A^T S + S A = -I]$$

$e^{tA^T} \nearrow \nwarrow e^{tA}$

$$\underbrace{e^{tA^T} A^T S e^{tA} + e^{tA^T} S A e^{tA}} = -e^{tA^T} e^{tA}$$

$$\frac{d}{dt}(e^{tA^T} S e^{tA}) = -e^{tA^T} e^{tA}$$

$$e^{tA^T} S e^{tA} - S = -\int_0^t e^{\tau A^T} e^{\tau A} d\tau$$

$\downarrow t \rightarrow \infty$   
0

$$S = \int_0^\infty e^{\tau A^T} e^{\tau A} d\tau$$

(check

$$\begin{aligned} A^T S + S A &= \int_0^\infty (A^T e^{\tau A^T} e^{\tau A} + e^{\tau A^T} e^{\tau A} A) d\tau \\ &= \int_0^\infty \frac{d}{d\tau} (e^{\tau A^T} e^{\tau A}) d\tau = -I \\ &= e^{\tau A^T} e^{\tau A} \Big|_0^\infty = -I \end{aligned}$$

[M Sec 4.13 #10]

$$L = x^T S x$$

$$\begin{aligned}\frac{d}{dt} L &= \dot{x}^T S x + x^T S \dot{x} \\ &= (x^T A^T + g^T) S x + x^T S (Ax + g) \\ &= x^T (A^T S + S A) x + g^T S x + x^T S g \\ &= -\|x\|^2 + g^T(x) S x + x^T S g(x) \\ &\leq -\|x\|^2 + \delta \|x\|^2 \\ &\leq -(1-\delta) \|x\|^2 < 0\end{aligned}$$

$$g(x) = o(x)$$

$$\text{i.e. } \|g(x)\| \leq \delta \|x\| \text{ if } \|x\| \ll 1$$

$$0 < \delta < 1$$

#8

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 & 10 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\dot{y} = -2y \Rightarrow y(t) = y_0 e^{-2t}$$

$$\dot{x} = -x + 10y$$

$$x(t) = e^{-t} x_0 + 10 \int_0^t e^{-(t-s)} y_0 e^{-2s} ds$$

$$= e^{-t} x_0 + 10 y_0 e^{-t} \int_0^t e^{-s} ds$$

$$= e^{-t} x_0 + 10 y_0 e^{-t} (1 - e^{-t})$$

$$= (x_0 + 10 y_0) e^{-t} - 10 y_0 e^{-2t}$$

$$x^2(t) + y^2(t)$$

$$= \left( (x_0 + 10 y_0) e^{-t} - 10 y_0 e^{-2t} \right)^2 + y_0^2 e^{-4t}$$

$$= (x_0 + 10 y_0)^2 e^{-2t} - 20 (x_0 + 10 y_0) y_0 e^{-3t} + 100 y_0^2 e^{-4t} + y_0^2 e^{-4t}$$

$$= (x_0 + 10y_0)^2 e^{-2t} - 20(x_0 + 10y_0)y_0 e^{-3t} + 101y_0^2 e^{-4t}$$

$$\leq (0.1)^2 \quad \forall t > 0$$

Do some simple estimate

$$x^2(t) + y^2(t)$$

$$e^{-2t}, e^{-3t}, e^{-4t} \leq 1$$

$$\leq (|x_0| + 10|y_0|)^2 + 20(|x_0| + 10|y_0|)|y_0| + 101|y_0|^2$$

$$= |x_0|^2 + 20|x_0||y_0| + 10^2|y_0|^2$$

$$+ 20|x_0||y_0| + 200|y_0|^2 + 101|y_0|^2$$

$$= |x_0|^2 + 40|x_0||y_0| + 401|y_0|^2 \quad (2ab \leq a^2 + b^2)$$

$$\leq |x_0|^2 + 20|x_0|^2 + 20|y_0|^2 + 401|y_0|^2$$

$$= 21|x_0|^2 + 421|y_0|^2$$

$$\leq 421(|x_0|^2 + |y_0|^2) \leq 0.1^2$$

$$\underline{|x_0|^2 + |y_0|^2 \leq \sqrt{\frac{0.01}{421}}}$$

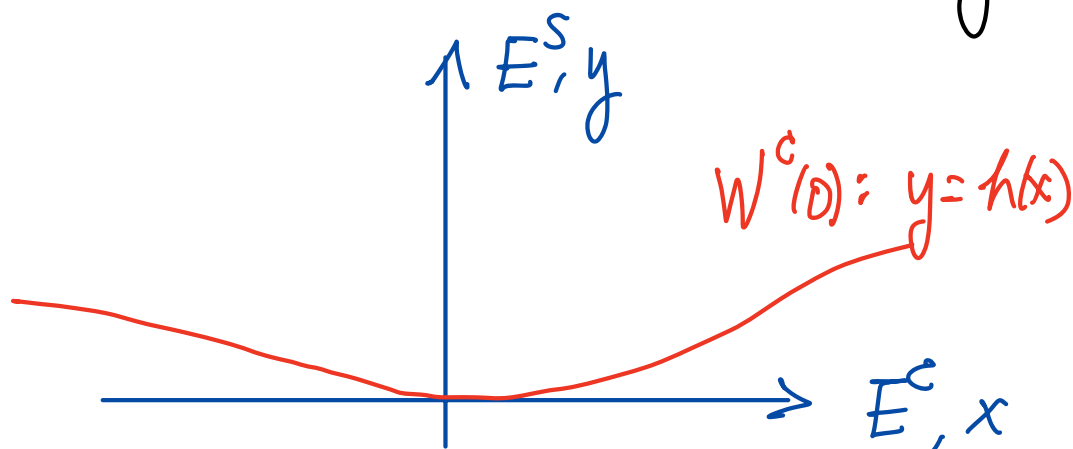
#2

$$\dot{x} = xy + ax^3 + by^2x$$

$$\dot{y} = -y + cx^2 + dx^2y$$

HW 4

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} ax^3 + by^2x \\ cx^2 + dx^2y \end{pmatrix}$$



$$h'(x)\dot{x} = -h + cx^2 + dx^2h$$

$$h' [xh + ax^3 + bh^2x] = -h + cx^2 + dx^2h$$

$$\text{Let } h(x) = \alpha x^2 + \beta x^3 + \gamma x^4 + \delta x^5 + \varepsilon x^6 + \dots$$

$$(\cancel{2\alpha x} + \cancel{3\beta x^2} + \cancel{4\gamma x^3} + \cancel{5\delta x^4} + \dots) \times$$

$$\times [\cancel{\alpha x^3} + \cancel{\beta x^4} + \gamma x^5 + \delta x^6 + \dots + ax^3$$

$$+ b x (\alpha x^2 + \beta x^3 + \gamma x^4 + \delta x^5 + \dots)^2]$$

$$= -\cancel{\alpha x^2} - \cancel{\beta x^3} - \cancel{\gamma x^4} - \delta x^5 - \dots$$

$$+ \cancel{cx^2} + dx^2 (\cancel{\alpha x^2} + \beta x^3 + \gamma x^4 + \delta x^5 + \dots)$$

$$O(x^2) \Rightarrow -x + C = 0 \Rightarrow x = C$$

$$O(x^3) \Rightarrow \beta = 0$$

$$\underline{h(x) = cx^2 + O(x^4)}$$

Dynamics on  $W^C(0)$ :

$$\dot{x} = xy + ax^3 + by^2x$$

$$= xh + ax^3 + bh^2x$$

$$= x(cx^2 + \dots) + ax^3 + bh^2x$$

$$= (a+c)x^3 + \dots$$

$$\boxed{a+c \begin{cases} > 0 \Rightarrow \text{unstable} \\ < 0 \Rightarrow \text{stable} \end{cases}}$$

If  $a+c=0$ , Compute  $O(x^4)$  in  $h$

$$2x(x+a) = -y + dx$$

$$\cancel{2c(c+a)} = -y + cd \Rightarrow y = cd$$

$$\underline{h(x) = cx^2 + cd x^4 + \dots}$$

$$\dot{x} = xy + ax^3 + by^2x$$

$$= xh + ax^3 + bh^2x$$

$$= x(\cancel{cx^2} + cd x^4 + \dots) + \cancel{ax^3} + b(cx^2 + cd x^4 + \dots)^2 x$$

$$= (cd + bc^2)x^5 + \dots$$

|                                                                                    |
|------------------------------------------------------------------------------------|
| $cd + bc^2 \begin{cases} > 0 & \text{unstable} \\ < 0 & \text{stable} \end{cases}$ |
|------------------------------------------------------------------------------------|

If  $cd + bc^2 = 0 \Rightarrow$  Compute  $O(x^5)$  in  $h$

$$O(x^5) \Rightarrow 0 = -\delta + d\beta \Rightarrow \delta = 0$$

$$O(x^6) \Rightarrow 2\alpha(\gamma + b\alpha^2) + 4\gamma(\alpha + a)$$

$$= -\varepsilon + d\gamma$$

$$2c(\cancel{cd + bc^2}) + 4\cancel{cd}(c + a) = -\varepsilon + dcd$$

$$\varepsilon = cd^2$$

$$\underline{h(x) = cx^2 + cd^2x^4 + cd^2x^6 + \dots}$$

$$\dot{x} = xy + ax^3 + by^2x$$

$$= xh + ax^3 + bh^2x$$

$$= x(cx^2 + cd^2x^4 + cd^2x^6 + \dots)$$

$$+ ax^3 + b(cx^2 + cd^2x^4 + cd^2x^6 + \dots)^2x$$

$$= \cancel{cx^3} + \cancel{cd^2x^5} + cd^2x^7 + \dots$$

$$+ \cancel{ax^3}$$

$$+ \cancel{bc^2x^5} + b2c^2d^2x^7 + \dots$$

$$= cd(d + 2bc)x^7 + \dots$$

$$cd + bc^2 = 0 \Rightarrow c(d + bc) = 0$$

assume  $c \neq 0$

$$bc = -d$$

$$\downarrow \underline{\dot{x} = -cd^2x^7 + \dots}$$

|        |       |          |
|--------|-------|----------|
| $cd^2$ | $> 0$ | stable   |
|        | $< 0$ | unstable |

(what if  $c = 0$  or even  $a, b, c, d = 0$ ?)

(The above question is from  
Carr, Appl. of Centre Manifold Theory)

#### 1.4. Examples

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where  $\gamma > 0$  is a constant.

If we substitute  $y(t) = h(x(t))$  into the second equation in (1.3.2) we obtain

$$h'(x)[Ax + f(x, h(x))] = Bh(x) + g(x, h(x)). \quad (1.3.6)$$

Equation (1.3.6) together with the conditions  $h(0) = 0$ ,  $h'(0) = 0$  is the system to be solved for the centre manifold. This is impossible, in general, since it is equivalent to solving (1.3.2). The next result, however, shows that, in principle, the centre manifold can be approximated to any degree of accuracy.

For functions  $\phi: \mathbb{R}^n \rightarrow \mathbb{R}^m$  which are  $C^1$  in a neighborhood of the origin define

$$(M\phi)(x) = \phi'(x)[Ax + f(x, \phi(x))] - B\phi(x) - g(x, \phi(x)).$$

Note that by (1.3.6),  $(Mh)(x) = 0$ .

Theorem 3. Let  $\phi$  be a  $C^1$  mapping of a neighborhood of the origin in  $\mathbb{R}^n$  into  $\mathbb{R}^m$  with  $\phi(0) = 0$  and  $\phi'(0) = 0$ .

Suppose that as  $x \rightarrow 0$ ,  $(M\phi)(x) = O(|x|^q)$  where  $q > 1$ . Then as  $x \rightarrow 0$ ,  $|h(x) - \phi(x)| = O(|x|^q)$ .

#### 1.4. Examples

We now consider a few simple examples to illustrate the use of the above results.

Example 1. Consider the system

$$\begin{aligned} \dot{x} &= xy + ax^3 + by^2x \\ \dot{y} &= -y + cx^2 + dx^2y. \end{aligned} \quad (1.4.1)$$

By Theorem 1, equation (1.4.1) has a centre manifold  $y = h(x)$ . To approximate  $h$  we set

$$(M\phi)(x) = \phi'(x)[x\phi(x) + ax^3 + bx\phi^2(x)] + \phi(x) - cx^2 - dx^2\phi(x).$$

If  $\phi(x) = O(x^2)$  then  $(M\phi)(x) = \phi(x) - cx^2 + O(x^4)$ . Hence, if  $\phi(x) = cx^2$ ,  $(M\phi)(x) = O(x^4)$ , so by Theorem 3,  $h(x) = cx^2 + O(x^4)$ . By Theorem 2, the equation which determines the stability of the zero solution of (1.4.1) is

$$\dot{u} = uh(u) + au^3 + buh^2(u) = (a+c)u^3 + O(u^5).$$

Thus the zero solution of (1.4.1) is asymptotically stable if  $a + c < 0$  and unstable if  $a + c > 0$ . If  $a + c = 0$  then we have to obtain a better approximation to  $h$ .

Suppose that  $a + c = 0$ . Let  $\phi(x) = cx^2 + \psi(x)$  where  $\psi(x) = O(x^4)$ . Then  $(M\phi)(x) = \psi(x) - cdx^4 + O(x^6)$ . Thus, if  $\phi(x) = cx^2 + cdx^4$  then  $(M\phi)(x) = O(x^6)$  so by Theorem 3,  $h(x) = cx^2 + cdx^4 + O(x^6)$ . The equation that governs the stability of the zero solution of (1.4.1) is

$$\dot{u} = uh(u) + au^3 + buh^2(u) = (cd+bc^2)u^5 + O(u^7).$$

Hence, if  $a + c = 0$ , then the zero solution of (1.4.1) is asymptotically stable if  $cd + bc^2 < 0$  and unstable if  $cd + bc^2 > 0$ . If  $cd + bc^2 = 0$  then we have to obtain a better approximation to  $h$  (see Exercise 1).

Exercise 1. Suppose that  $a + c = cd + bc^2 = 0$  in Example 1. Show that the equation which governs the stability of the zero solution of (1.4.1) is  $\dot{u} = -cd^2u^7 + O(u^9)$ .

Exercise 2. Show that the zero solution of (1.2.2) is asymptotically stable if  $a \leq 0$  and unstable if  $a > 0$ .

what if  $c = 0$   
or even  $a, b, c, d = 0$ ?

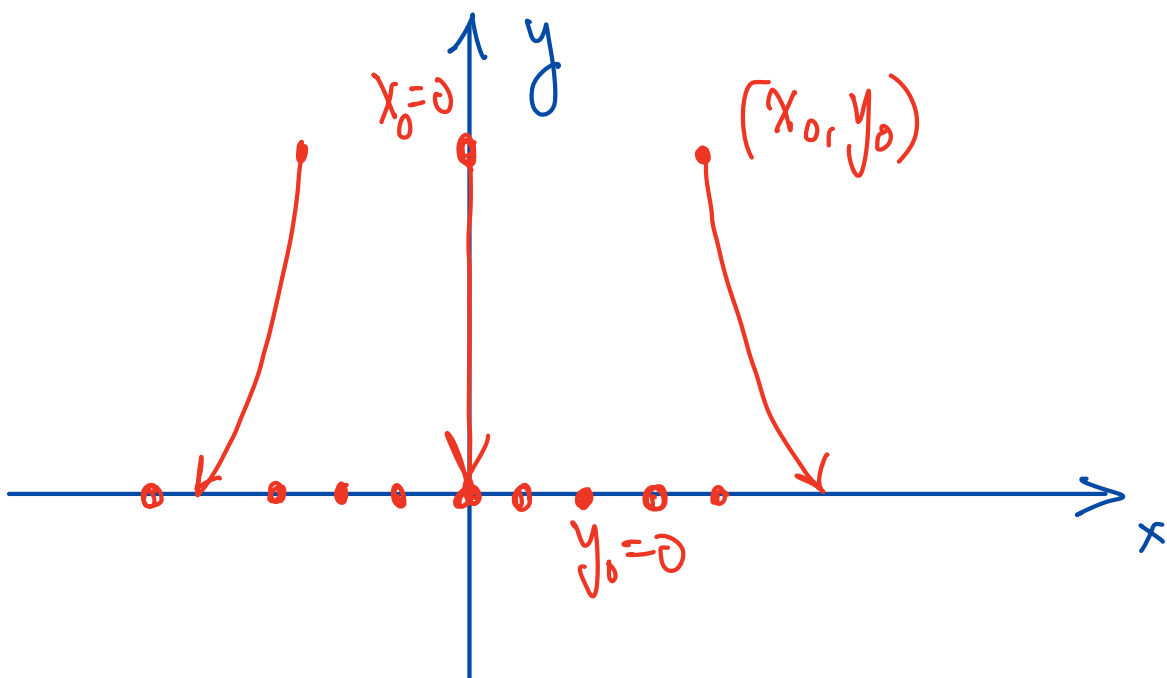
Compute  $W^s, W^c$  for  $\begin{cases} \dot{x} = xy \\ \dot{y} = -y \end{cases}$

$$\begin{aligned}\dot{x} &= xy \\ \dot{y} &= -y \Rightarrow y(t) = y_0 e^{-t}\end{aligned}$$

$$\dot{x} = y_0 e^{-t} x$$

$$x(t) = x_0 e^{\int_0^t y_0 e^{-s} ds} = x_0 e^{y_0(1-e^{-t})}$$

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} x_0 e^{y_0(1-e^{-t})} \\ y_0 e^{-t} \end{pmatrix} \begin{array}{l} \xrightarrow{t \rightarrow \infty} x_0 e^{y_0} \\ \rightarrow 0 \end{array}$$



$W^c = x\text{-axis}$ ,

$W^s = y\text{-axis}$

#3  $\dot{x} = -\nabla f(x)$  vs  $\ddot{x} = -a\dot{x} - \nabla f(x)$

$$f(x) = \frac{1}{2}\lambda x^2$$

①

$$\dot{x} = -\lambda x \implies x(t) = x_0 e^{-\lambda t}, \text{ rate} = \lambda$$

$$\ddot{x} = -a\dot{x} - \lambda x$$

$$\ddot{x} + a\dot{x} + \lambda x = 0$$

$$r^2 + ar + \lambda = 0$$

$$r = \frac{-a \pm \sqrt{a^2 - 4\lambda}}{2}$$

$$a = 2\sqrt{\lambda}$$

$$= -\sqrt{\lambda}$$

②

$$x(t) = A e^{-\sqrt{\lambda} t} + B t e^{-\sqrt{\lambda} t}, \text{ rate} \sim \sqrt{\lambda}$$

$$\underline{\sqrt{\lambda} > \lambda \text{ if } \lambda < 1}$$