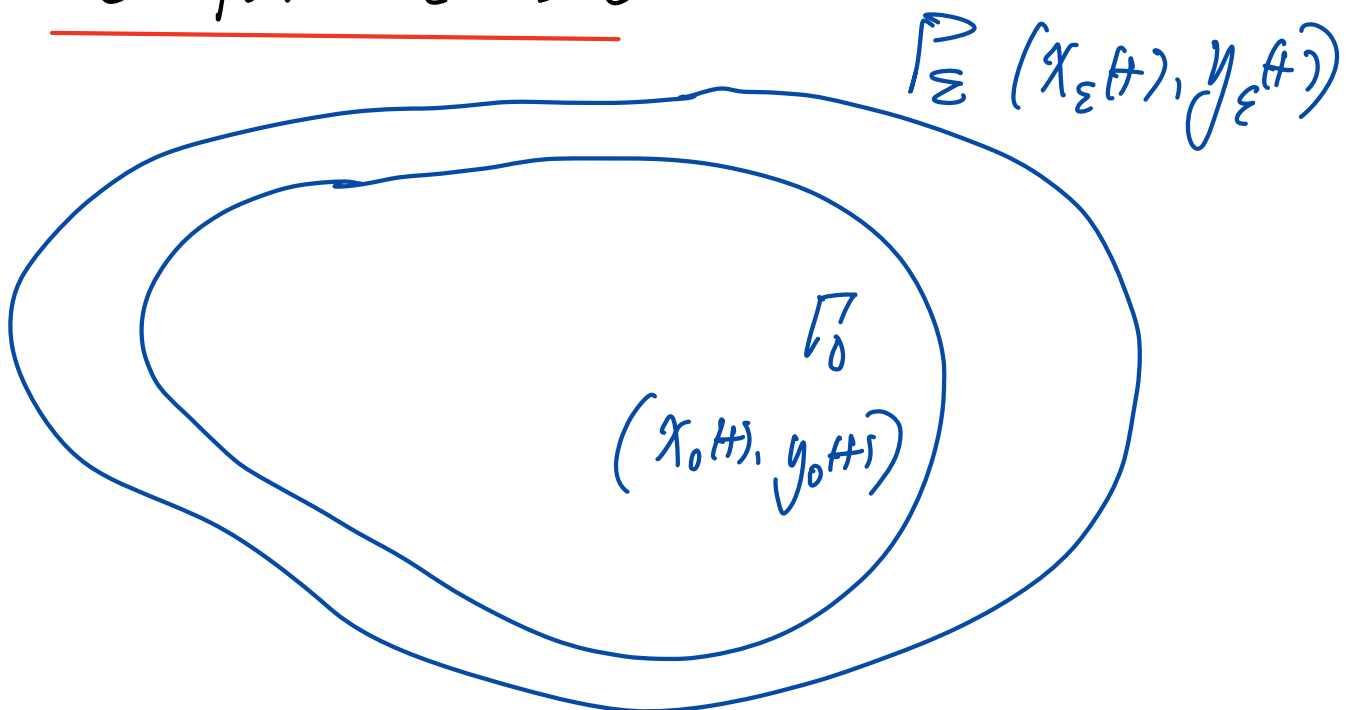


Perturbation/Persistence of Periodic Orbits (Hamiltonian System, Melnikov Integral)

$$(I)_0 \quad \begin{cases} \dot{x} = \partial_y H(x, y) = f_1(x, y) \\ \dot{y} = -\partial_x H(x, y) = f_2(x, y) \end{cases} \quad H - \text{Hamiltonian function}$$

$$(I)_\varepsilon \quad \begin{cases} \dot{x} = \partial_y H(x, y) + \varepsilon g_1(x, y) \\ \dot{y} = -\partial_x H(x, y) + \varepsilon g_2(x, y) \end{cases}$$

Suppose there are periodic orbits Γ_0
and Γ_ε for all $\varepsilon > 0$



Line Integral of H along the orbits :

$$\int_{\Gamma_0} dH = 0 \quad \text{and} \quad \int_{\Gamma_\varepsilon} dH = 0 \quad \text{for all } \varepsilon > 0$$

(In general $\int_{\text{Any closed orbit}} dH = \int \left(\frac{dH}{dt} \right) dt = 0$)

$$\begin{aligned} \int_{\Gamma_0} dH &= \int_{\Gamma_0} H_x dx + H_y dy \\ &= \int_{\Gamma_0} (H_x \dot{x} + H_y \dot{y}) dt \\ &= \int_{\Gamma_0} (H_x (H_y) + H_y (-H_x)) dt \\ &= 0 \end{aligned}$$

$$\int_{\Gamma_\varepsilon} dH = \int_{\Gamma_\varepsilon} (H_x \dot{x}_\varepsilon + H_y \dot{y}_\varepsilon) dt = 0 \quad \text{for all } \varepsilon$$

$$\begin{aligned}
 &= \int_{\Gamma_\varepsilon} H_x (\cancel{H_y} + \varepsilon g_1) + H_y (\cancel{-H_x} + \varepsilon g_2) dt \\
 &= \varepsilon \underbrace{\int_{\Gamma_\varepsilon} (H_x g_1 + H_y g_2) dt}_{=0} = 0 \text{ for all } \varepsilon
 \end{aligned}$$

i.e. $\int_{\Gamma_\varepsilon} (H_x g_1 + H_y g_2) dt = 0$

$$\varepsilon \rightarrow 0 \Rightarrow \int_{\Gamma_0} (H_x g_1 + H_y g_2) dt = 0$$

Melnikov Integral

or

$$\boxed{\int_{\Gamma_0} (g_2 f_1 - g_1 f_2) dt = 0}$$

Notation : $g_2 f_1 - g_1 f_2 = \begin{vmatrix} f_1 & g_1 \\ f_1 & g_2 \end{vmatrix} = \underbrace{\vec{f}}_{\vec{f}} \wedge \underbrace{\vec{g}}_{\vec{g}}$

van der Pol oscillator

$$\ddot{x} + \varepsilon (x^2 - 1)\dot{x} + x = 0$$

↙

$$\begin{cases} \dot{x} = y \\ \dot{y} = -x - \varepsilon (x^2 - 1)y \end{cases}$$

$$f_1 = y$$

$$g_1 = 0$$

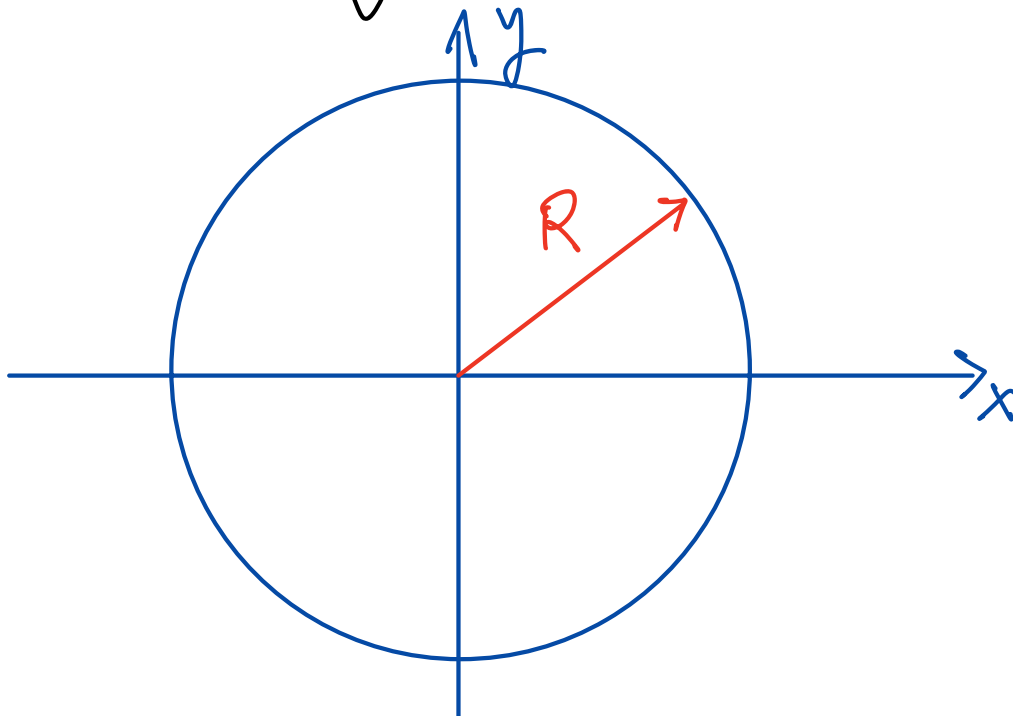
$$f_2 = -x$$

$$g_2 = -(x^2 - 1)y$$

At $\varepsilon = 0$

$$x = R \cos t$$

$$y = -R \sin t$$



$$\int (f_1 g_2 - f_2 g_1) dt$$

$$= \int (-y(x^2-1)y - (-x)(0)) dt$$

$$= \int_0^{2\pi} -y^2(t)(x^2(t)-1) dt$$

$$= \int_0^{2\pi} A^2 \sin^2 t (1 - A^2 \cos^2 t) dt$$

$$= A^2 \int_0^{2\pi} \sin^2 t dt - A^4 \int_0^{2\pi} \sin^2 t \cos^2 t dt$$

$$\cos 2\alpha = \cos^2 \alpha - \sin^2 \alpha = 2\cos^2 \alpha - 1 = 1 - 2\sin^2 \alpha$$

$$\sin 2\alpha = 2\sin \alpha \cos \alpha$$

$$\sin^2 \alpha = \frac{1 - \cos 2\alpha}{2}$$

$$\sin^2 \alpha \cos^2 \alpha = \frac{1}{4} \sin^2 2\alpha = \frac{1}{8} (1 - \cos 4\alpha)$$

$$= \frac{A^2}{2} \int_0^{2\pi} (1 - \cancel{\cos 2t}) dt - \frac{A^4}{8} \int_0^{2\pi} (1 - \cancel{\cos 4t}) dt$$

$$= \left(\frac{A^2}{2} - \frac{A^4}{8} \right) 2\pi$$

$$= \frac{\pi}{4} A^2 (4 - A^2) = 0 \Rightarrow A = 0 \text{ or } \underline{2}$$

For stability: $\dot{X} = F(X)$

$$\int_0^T \operatorname{div} F(X(t)) dt$$

$$= \int_0^T \operatorname{div} (f_1 + \varepsilon g_1, f_2 + \varepsilon g_2) dt$$

$$= \int_0^T (f_1)_x + \varepsilon (g_1)_x + (f_2)_y + \varepsilon (g_2)_y dt$$

$$= \int_0^T (\cancel{(H_y)_x} + \cancel{(-H_x)_y}) dt + \varepsilon \int_0^T ((g_1)_x + (g_2)_y) dt$$

$$= \varepsilon \int_0^T (g_1)_x + (g_2)_y \, dt$$

$$g_1 = 0, \quad g_2 = -y(x^2 - 1)$$

$$= \varepsilon \int_0^T (1 - x^2) \, dt$$

//
compute at $\varepsilon = 0$

$$\int_0^T (1 - x^2) \, dt = \int_0^{2\pi} (1 - A^2 \cos^2 t) \, dt$$

$$= \int_0^{2\pi} (1 - 4 \cos^2 t) \, dt$$

$$= \int_0^{2\pi} (1 - 2(\cos 2t + 1)) \, dt$$

$$= -2\pi < 0 \quad \underline{\text{Stable}}$$