

Remarks:

① For  $A \in \mathbb{R}^{n \times n}$ , eigenvectors are not unique for a given eigenvalue.

Example: If  $A \in \mathbb{R}^{3 \times 3}$  satisfies  $A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = z \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$\forall a \neq 0$ ,  $a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ a \\ a \end{bmatrix}$  is an eigenvector of  $A$  for the eigenvalue  $\lambda = z$ .

②  $A \in \mathbb{R}^{3 \times 3}$ ,  $V = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3]$ ,  $D = \begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix}$

diagonalization  $A = V D V^{-1}$

$\Leftrightarrow A V = V D$  for an invertible  $V$

$\Leftrightarrow A [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] \begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix}$

$\Leftrightarrow \begin{cases} A \vec{v}_1 = d_1 \vec{v}_1 \\ A \vec{v}_2 = d_2 \vec{v}_2 \\ A \vec{v}_3 = d_3 \vec{v}_3 \end{cases}$

$\Leftrightarrow A$  has  $n$  linearly independent eigenvectors

$\Leftrightarrow \begin{cases} A \text{ has } n \text{ eigenvalues including repeated ones} \\ \text{For all eigenspace: Geo Mul} = \text{Alg Mul} \end{cases}$

③ If  $A$  is diagonalizable, then there are many matrices  $V, D$  satisfying  $A = VDV^{-1}$

$$A [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3] \begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix}$$

$$A [\vec{v}_2 \ \vec{v}_3 \ \vec{v}_1] = [\vec{v}_2 \ \vec{v}_3 \ \vec{v}_1] \begin{bmatrix} d_2 & 0 & 0 \\ 0 & d_3 & 0 \\ 0 & 0 & d_1 \end{bmatrix}$$

$$A [\vec{v}_2 \ \vec{v}_3 \ \vec{v}_1] = [\vec{v}_2 \ \vec{v}_3 \ \vec{v}_1] \begin{bmatrix} d_2 & 0 & 0 \\ 0 & d_3 & 0 \\ 0 & 0 & d_1 \end{bmatrix}$$

④ Basis vectors for each eigen-space are not unique

⑤ Any nonzero vector in eigen-space is an eigenvector.

The following real matrices are always diagonalizable:

① Real Symmetric Matrix  $A = A^T$

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 5 & 6 & 7 \\ 3 & 6 & 8 & 9 \\ 4 & 7 & 9 & 10 \end{pmatrix}$$

② Real Skew-Symmetric  $A^T = -A$

$$\begin{pmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{pmatrix}$$

③ Normal Matrix  $AA^T = A^T A$

Theorem If  $A \in \mathbb{R}^{n \times n}$  satisfies  $A = A^T$ , then

- ①  $A$  has  $n$  real eigenvalues including repeated ones
- ②  $A$  has  $n$  orthogonal real eigenvectors, i.e., all eigenspaces are orthogonal to one another.

Proof: ①  $\det(A - \lambda I)$  has  $n$  complex roots including repeated ones.

Each distinct eigenvalue  $\lambda = a + ib$  has at least one eigenvector  $\vec{v}$

$$A \vec{v} = \lambda \vec{v} \quad \overline{a + ib} = a - ib$$

Take conjugate:

$$\overline{A \vec{v}} = \overline{\lambda \vec{v}} \quad \square \square = \square \square$$

$$\overline{A} \overline{\vec{v}} = \overline{\lambda} \overline{\vec{v}}$$

$$(\overline{A} = A) \quad A \overline{\vec{v}} = \overline{\lambda} \overline{\vec{v}}$$

$$(A B)^T = B^T A^T$$

Take transpose:

$$\overline{\vec{v}}^T A^T = \overline{\vec{v}}^T \overline{\lambda} \quad \square = \square \square$$

$$(A^T = A) \quad \overline{\vec{v}}^T A = \overline{\vec{v}}^T \overline{\lambda}$$

$$\overline{\vec{v}}^T A \vec{v} = \overline{\vec{v}}^T \overline{\lambda} \vec{v} \quad (*)$$

$$\square \square = \square \square$$

$$A\vec{v} = \lambda\vec{v} \Rightarrow \overline{\vec{v}}^T A \vec{v} = \overline{\vec{v}}^T \lambda \vec{v} \quad (**)$$

$$\begin{matrix} (*) \\ (**) \end{matrix} \left. \vphantom{\begin{matrix} (*) \\ (**) \end{matrix}} \right\} \Rightarrow \overline{\vec{v}}^T \overline{\lambda} \vec{v} = \overline{\vec{v}}^T \lambda \vec{v}$$

$$\Rightarrow \overline{\lambda} \overline{\vec{v}}^T \vec{v} = \lambda \overline{\vec{v}}^T \vec{v}$$

$$\Rightarrow (\overline{\lambda} - \lambda) \underbrace{\overline{\vec{v}}^T \vec{v}} = 0$$

$$\downarrow$$

$$[\overline{v}_1 \ \overline{v}_2 \ \overline{v}_3] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \overline{v}_1 v_1 + \overline{v}_2 v_2 + \overline{v}_3 v_3$$

$$= |v_1|^2 + |v_2|^2 + |v_3|^2 > 0$$

$$\Rightarrow \overline{\lambda} = \lambda \Rightarrow \lambda \in \mathbb{R}$$

② We already know  $n$  complex eigenvalues are real, so all eigenvectors are real.

$$\text{Want to show } \left. \begin{array}{l} A\vec{v}_1 = \lambda_1 \vec{v}_1 \\ A\vec{v}_2 = \lambda_2 \vec{v}_2 \\ \lambda_1 \neq \lambda_2 \end{array} \right\} \Rightarrow \vec{v}_1 \perp \vec{v}_2$$

$$A\vec{v}_1 = \lambda_1 \vec{v}_1$$

Take dot product with  $\vec{v}_2$

$$\langle A\vec{v}_1, \vec{v}_2 \rangle = \langle \lambda_1 \vec{v}_1, \vec{v}_2 \rangle$$

$$(\vec{v}_2^T A) \vec{v}_1 = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$(ABC)^T = C^T B^T A^T$$

$$(A^T \vec{v}_2)^T \vec{v}_1 = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$A^T = A$$

$$(A \vec{v}_2)^T \vec{v}_1 = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$(\lambda_2 \vec{v}_2)^T \vec{v}_1 = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$\lambda_2 \vec{v}_2^T \vec{v}_1 = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$\lambda_2 \langle \vec{v}_1, \vec{v}_2 \rangle = \lambda_1 \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$(\lambda_1 - \lambda_2) \langle \vec{v}_1, \vec{v}_2 \rangle = 0$$

$$\Rightarrow \langle \vec{v}_1, \vec{v}_2 \rangle = 0.$$

Example:  $A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$

Find 3 orthonormal eigenvectors of  $A$ .

Sol:  $|A - \lambda I| = \begin{vmatrix} -\lambda & 1 & 1 \\ 1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix}$

$$= -\lambda(\lambda^2 - 1) - (-\lambda - 1) + (1 + \lambda)$$

$$= -\lambda(\lambda + 1)(\lambda - 1) + \lambda + 1 + (\lambda + 1)$$

$$= (\lambda + 1)[- \lambda(\lambda - 1) + 1 + 1]$$

$$= (\lambda + 1)[- \lambda^2 + \lambda + 2]$$

$$= -(\lambda + 1)^2(\lambda - 2)$$

$$\lambda_1 = -1, \lambda_2 = 2$$

① Plug in  $\lambda_1 = -1$  into  $(A - \lambda I)\vec{v} = \vec{0}$

$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right]$$

$$\Rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left. \begin{array}{l} v_2 = s \\ v_3 = t \end{array} \right\} \Rightarrow v_1 = -s - t \Rightarrow \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} -s-t \\ s \\ t \end{pmatrix}$$

$$= s \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad \vec{u}_1 \quad \vec{u}_2$$

$$\Rightarrow \text{Eigen-Space is Span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

But two basis eigen-vectors are not orthogonal.

Apply Gram-Schmidt Procedure:

$$\vec{v}_1 = \vec{u}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \vec{v}_2 &= \vec{u}_2 - \frac{\langle \vec{v}_1, \vec{u}_2 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1 \\ &= \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \end{aligned}$$

Verify  $A\vec{v}_2 = (4)\vec{v}_2$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -1 \end{bmatrix}$$

② Plug in  $\lambda = 2$  into  $(A - \lambda I)\vec{v} = \vec{0}$

$$\text{to find } \vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

So we get orthogonal eigenvectors

$$\vec{v}_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix}, \vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

and orthonormal eigenvectors:

$$\vec{w}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \\ 0 \end{pmatrix} \quad \vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|}$$

$$\vec{w}_2 = \frac{1}{\sqrt{\frac{3}{2}}} \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \sqrt{\frac{2}{3}} \\ -\frac{1}{2} \sqrt{\frac{2}{3}} \\ \sqrt{\frac{2}{3}} \end{pmatrix}$$

$$\vec{w}_3 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{3} \\ \frac{\sqrt{3}}{3} \\ \frac{\sqrt{3}}{3} \end{pmatrix}$$

$$\text{Use } V = [\vec{w}_1 \ \vec{w}_2 \ \vec{w}_3] \quad D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$\text{Then } A = V D V^{-1}$$

$$\text{and } V^{-1} = V^T$$

$$V^T V = \begin{bmatrix} \square & \square & \square \\ \square & \square & \square \\ \square & \square & \square \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$