

① Change of Coordinate Matrix

V has two ordered bases β and γ

$Q = [I]_{\beta}^{\gamma}$ changes $[v]_{\beta}$ to $[v]_{\gamma}$:

$$[v]_{\gamma} = [I(v)]_{\gamma} = [I]_{\beta}^{\gamma} [v]_{\beta} = Q [v]_{\beta}$$

Theorem: If $Q = [I]_{\beta}^{\gamma}$, then Q is invertible and

$$Q^{-1} = [I]_{\gamma}^{\beta}$$

Proof: $\begin{cases} [v]_{\beta} = [I(v)]_{\beta} = [I]_{\gamma}^{\beta} [v]_{\gamma} & I: \gamma \rightarrow \beta \\ [v]_{\gamma} = [I]_{\beta}^{\gamma} [v]_{\beta} \end{cases}$

$$\Rightarrow I[v]_{\beta} = \underline{[I]_{\gamma}^{\beta}} \underline{[I]_{\beta}^{\gamma}} [v]_{\beta}, \quad \forall v \in V.$$

(Lemma) $\Rightarrow [I]_{\gamma}^{\beta} [I]_{\beta}^{\gamma}$ is identity matrix.

Lemma: $A, B \in F^{n \times n}$, if $\underline{Ax} = \underline{Bx}$, for any $\underline{x} \in F^n$
then $A = B$.

Proof: set $x = \underline{e_i}$, then $Ae_i = \begin{bmatrix} | & | & | & | & | \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} = \text{i-th col of } A$

\Rightarrow i-th col of A = i-th col of B .

Remark: 1) Given β, γ , $Q = [I]_{\beta}^{\gamma}$ is invertible

2) Given β , and invertible Q , then $\exists \gamma$

$$\text{s.t. } Q = [I]_{\beta}^{\gamma}$$

Proof: $\beta = \{v_1, \dots, v_n\} \quad Q = [q_{ij}]_{n \times n}$

$\gamma = \{u_1, \dots, u_n\} \quad Q^{-1} = [q_{ij}^{-1}]_{n \times n}$

$$[u_j]_{\beta} = [I]_{\beta}^{\gamma} [u_j]_{\gamma} = Q^{-1} \underline{[u_j]_{\gamma}} = Q^{-1} e_j = \text{j-th col of } Q^{-1}$$

$$= \begin{bmatrix} q_{1j} \\ q_{2j} \\ \vdots \\ q_{nj} \end{bmatrix}$$

$$\Rightarrow u_j = q_{1j} v_1 + q_{2j} v_2 + \dots + q_{nj} v_n.$$

Theorem 2.23 (in Section 2.5)

$$T: V \xrightarrow{\beta} V \quad [T]_\beta$$

$$T: V \xrightarrow{\gamma} V \quad [T]_\gamma$$

$$[T]_\beta = Q^{-1} [T]_\gamma Q \quad \text{where } Q = [I]_\beta^\gamma$$

$$\text{Proof: } \left\{ \begin{array}{l} T: V \xrightarrow{\gamma} V \\ v \mapsto T(v) \\ [v]_\gamma \mapsto [T(v)]_\gamma = [T]_\gamma [v]_\gamma \end{array} \right. \quad \left. \begin{array}{l} [v]_\gamma = [I]_\beta^\gamma [v]_\beta \\ [v]_\beta \mapsto [T(v)]_\beta = [T]_\beta [v]_\beta \end{array} \right. \quad (*)$$

$$\left\{ \begin{array}{l} T: V \xrightarrow{\beta} V \\ v \mapsto T(v) \\ [v]_\beta \mapsto [T(v)]_\beta = [T]_\beta [v]_\beta \end{array} \right. \quad (**)$$

$$\left. \begin{array}{l} [v]_\gamma = Q [v]_\beta \\ [v]_\beta = [T]_\beta [v]_\beta \end{array} \right\} \Rightarrow Q [T(v)]_\beta = [T]_\gamma Q [v]_\beta \quad (**)$$

$$\Rightarrow Q [T]_\beta [v]_\beta = [T]_\gamma Q [v]_\beta \quad \forall v \in V.$$

$$(\text{Lemma}) \Rightarrow Q [T]_\beta = [T]_\gamma Q \Rightarrow [T]_\beta = Q^{-1} [T]_\gamma Q.$$

Def If $A = Q^{-1} B Q$ for some invertible Q , then we say A is similar to B .

② Def $T: V \rightarrow V$ (for finite dim V)

is called diagonalizable if $\exists \beta$ s.t. $[T]_\beta$ is diagonal.

Def A matrix $A \in F^{n \times n}$ is diagonalizable if L_A is diagonalizable.

$$1) L_A : F^n \rightarrow F^n \quad \gamma = \{e_1, \dots, e_n\}$$

$$\begin{matrix} x \\ \| \end{matrix} \rightarrow Ax \quad \begin{matrix} x \\ \| \end{matrix}$$

$$[x]_\gamma \quad [L_A(x)]_\gamma = [L_A]_\gamma [x]_\gamma = [L_A]_\gamma x$$

$$\text{So } [L_A]_\gamma = A.$$

$$\beta = \{v_1, \dots, v_n\} \subseteq F^n$$

$$[x]_\beta \rightarrow [L_A(x)]_\beta = [L_A]_\beta [x]_\beta$$

$$Q = [I]_\beta^\gamma \Rightarrow [L_A]_\beta = Q^{-1} [L_A]_\gamma Q \\ = Q^{-1} A Q$$

a) L_A being diagonalizable means $[Q^{-1} A Q]$ is diagonal
where $Q = [I]_\beta^\gamma \Rightarrow \gamma = \{e_1, \dots, e_n\}$
 β is the one in def.

b) A diagonalizable matrix is similar to a diagonal matrix.

c) What is Q ? $Q = [v_1 \ v_2 \ \dots \ v_n]$

$v_i = [v_i]_\gamma = Q \underbrace{[v_i]_\beta}_{= \{v_1, \dots, v_n\}} = Q e_i = i\text{-th col of } Q$.

③ Theorem 5.1

(a) $T: V \rightarrow V$ is diagonalizable if and only if

\exists a basis β consisting of eigenvectors of T .

(b) If T is diagonalizable under β ($[T]_\beta$ is diagonal)

then v_i are eigenvectors of T and

$$[T]_\beta = \begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_n & \end{bmatrix} \text{ with } T(v_i) = \lambda_i v_i.$$

Proof: T is diagonalizable $\Leftrightarrow [T]_{\beta} = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix}$

for some $\beta = \{v_1, \dots, v_n\}$

$$\Leftrightarrow [T(v_i)]_{\beta} = [T]_{\beta}[v_i]_{\beta} = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ d_i \end{pmatrix}$$

$$\Leftrightarrow T(v_i) = 0 \cdot v_1 + 0 \cdot v_2 + \dots + 0 \cdot v_{i-1} + d_i v_i + 0 \cdot v_{i+1} \dots \\ = d_i v_i$$

$$\text{Ex: } A = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \in \mathbb{C}^{2 \times 2} \quad \det(A-tI) = \left| \begin{pmatrix} \cos\theta-t & -\sin\theta \\ \sin\theta & \cos\theta-t \end{pmatrix} \right| \\ = (\cos\theta-t)^2 + \sin^2\theta \\ = t^2 - 2\cos\theta t + 1 = 0$$

$$t = \frac{\cos\theta \pm i\sin\theta}{2}$$

$\boxed{LA: \mathbb{C}^2 \rightarrow \mathbb{C}^2 \text{ over } \mathbb{C}}$ is diagonalizable

$\boxed{LA: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ over } \mathbb{R}}$ is NOT diagonalizable

Remark: A matrix A is diagonalizable means:

$\exists Q$ s.t. $Q^{-1}AQ$ is diagonal
and cols of Q are eigenvectors of A
diagonal entries of $Q^{-1}AQ$ are eigenvalues

④ Def $f(t) = \det([T]_{\beta} - tI)$ is called characteristic polynomial of T

$\det([T]_{\beta})$ is called det of T .

Theorem ① det and $f(t)$ are the same for T

under different bases.

② \det and $f(t)$ are the same for similar matrices

Proof: Only need to prove ② because $[T]_{\beta} = Q^{-1}[T]_{\gamma}Q$ where $Q = [I]_{\beta}^{\gamma}$.

Lemma: $\det(AB) = \det(BA) \quad A, B, C \in F^{n \times n}$
 $\det(ABC) = \det(BCA) = \det(CAB)$

Proof: $\det(AB) = \det(A)\det(B) = \det(BA)$
 $\det(ABC) = \det(AB)\det(C) = \frac{\det(A)\det(B)}{\det(C)}$.

If $A = Q^{-1}BQ$, then

$$\begin{aligned}\det(A) &= \det(Q^{-1}BQ) \\ &= \det(BQQ^{-1}) \\ &= \det(B)\end{aligned}$$

$$\begin{aligned}\det(A - tI) &= \det(Q^{-1}BQ - tI) \\ &= \det(Q^{-1}BQ - Q^{-1}(tI)Q) \\ &= \det[Q^{-1}(B - tI)Q] \\ &= \det(B - tI).\end{aligned}$$

⑤ Theorem 5.5 $T: V \rightarrow V \quad \dim(V) = n$

$\lambda_1, \dots, \lambda_k$ are distinct eigenvalues

For each λ_i , S_i is an independent set of eigenvectors of λ_i .

then $S = S_1 \cup S_2 \cup \dots \cup S_k$ is independent.

Proof: By Induction

1) If $k=1$, nothing to prove.

2) Assume it is true for $k-1$. (Induction Hypothesis)

Let $S_i = \{v_1^i, \dots, v_{n_i}^i\}$ for λ_i .

$$\sum_{i=1}^k \sum_{j=1}^{n_i} a_{ij} v_j^i = \vec{0} \quad \text{linear comb of vectors in } S_i.$$

$a_{ij} \in F$

Apply $(T - \lambda_k I)$ for both sides

$$\sum_{i=1}^k \sum_{j=1}^{n_i} a_{ij} [T(v_j^i) - \lambda_k v_j^i] = \vec{0}$$

$$\Rightarrow \sum_{i=1}^{k-1} \sum_{j=1}^{n_i} a_{ij} [\lambda_i v_j^i - \lambda_k v_j^i] = \vec{0}$$

$$\Rightarrow \underbrace{\sum_{i=1}^{k-1} \sum_{j=1}^{n_i} a_{ij}}_{\times 0} (\lambda_i - \lambda_k) v_j^i = \vec{0}$$

linear comb in union of $(k-1)$ sets

Induction Hypothesis $\Rightarrow a_{ij}(\lambda_i - \lambda_k) = 0$

$\Rightarrow a_{ij}, 1 \leq i \leq k-1$

$$\Rightarrow \sum_{j=1}^{n_k} a_{kj} v_j^k = \vec{0}$$

S_k is independent $\Rightarrow a_{kj} = 0,$