

## Section 1.2 Row Reduction And Echelon Forms

### Definitions

1. A nonzero row or column in a matrix means a row or column that contains at least one nonzero entry; a leading entry of a row refers to the leftmost nonzero entry (in a nonzero row).

2. A rectangular matrix is in row echelon form or row echelon form if it has the following three properties:

- All nonzero rows are above any rows of all zeros.
- Each leading entry of a row is in a column to the right of the leading entry of the row above it.
- All entries in a column below a leading entry are zeros. (Property 3 is a simple consequence of property 2, but we include it for emphasis.)

3. If a matrix in echelon form satisfies the following additional conditions, then it is in **reduced echelon form** (or reduced row echelon form, we usually call it rref):

- 3.1 • The leading entry in each nonzero row is 1.
- 3.2 • Each leading 1 is the only nonzero entry in its column.

Example 1:

$\circ \rightarrow \neq 0$   
 $* \rightarrow \text{any number}$

RREF

$$\begin{bmatrix} \blacksquare & * & * & * \\ 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * \end{bmatrix}$$

RREF

$$\begin{bmatrix} 1 & 0 & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & * & 0 & 0 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 1 & 0 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 1 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 1 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & * \end{bmatrix}$$

**Theorem:** Uniqueness of the Reduced Echelon Form

Each matrix is row equivalent to one and only one reduced echelon matrix.

**Definitions**

**pivot position** in a matrix  $A$  is a location in  $A$  that corresponds to a leading 1 in the reduced echelon form of  $A$ .

A **pivot column** is a column of  $A$  that contains a pivot position.

**The Row Reduction Algorithm** ( algo will give us REF or RREF of the original matrix)

- STEP 1: Begin with the leftmost nonzero column. This is a **pivot column**. The **pivot position** is at the top.
- STEP 2: Select a nonzero entry in the pivot column as a **pivot**. If necessary, interchange rows to move this entry into the pivot position.
- STEP 3: Use **row replacement operations** to create zeros in all positions below the pivot.

STEP 4: Cover (or ignore) the row containing the pivot position and cover all rows, if any, above it. Apply steps 1 to 3 to the submatrix that remains. **Repeat** the process until there are no more nonzero rows to modify.

STEP 5: **Backward phase**. Beginning with the rightmost pivot and working upward and to the left, create zeros above each pivot. If a pivot is not 1, make it 1 by a scaling operation.

Example 2: Row reduce the matrix A below to echelon form, and locate the pivot columns of A.

$$\begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 3 & 4 & 8 \end{pmatrix} \xrightarrow[\substack{\text{interchange} \\ R_1 \leftrightarrow R_2}]{\text{replacement}} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 3 & 4 & 8 \end{pmatrix} \xrightarrow[\substack{\text{replacement} \\ R_3 = R_3 - 3R_1}]{\text{replacement}} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & -2 & -1 \end{pmatrix}$$

$$\xrightarrow[\substack{\text{replacement} \\ R_3 = R_3 + 2 \cdot R_2}]{\text{replacement}} \begin{pmatrix} \boxed{1} & 2 & 3 \\ 0 & \boxed{1} & 2 \\ 0 & 0 & \boxed{3} \end{pmatrix} \begin{matrix} \text{leading entries} \\ \downarrow \text{RREF} \end{matrix}$$

3rd is satisfied.

Go to RREF

$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 3 \end{pmatrix} \xrightarrow[\substack{R_3 = \frac{1}{3} \cdot R_3}]{\text{replacement}} \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & \boxed{2} \\ 0 & 0 & 1 \end{pmatrix}$$

make 2 in the 2nd row 3rd col = 0

$$\begin{pmatrix} 1 & 2 & \boxed{3} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

make 3 in the 1st row 3rd col = 0

$$\begin{pmatrix} 1 & \boxed{2} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow[\substack{R_1 = R_1 - 2 \cdot R_2}]{\text{replacement}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ (RREF)}$$

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 6 & 7 & 8 & 9 \\ 0 & 2 & 3 & 4 \end{pmatrix} \begin{matrix} x_1 \\ x_2 \\ x_3 \end{matrix}$$

3 eqns = # of rows

$$R_2 = R_2 - 3R_1$$

6 → 0

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & -2 & -4 & -6 \\ 0 & 2 & 3 & 4 \end{pmatrix}$$

$R_3 = R_3 + R_2$   
2 → 0

(REF)

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & -2 & -4 & -6 \\ 0 & 0 & -1 & -2 \end{pmatrix}$$

$$R_2 = R_2 \cdot \frac{1}{2}$$

$$R_3 = R_3 \cdot (-1)$$

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$R_2 = R_2 - 2R_3$   
2 → 0

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_1 = R_1 - 4R_3$$

4 → 0

$$\begin{pmatrix} 2 & 3 & 0 & -3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$R_1 = R_1 - 3R_2$   
3 → 0

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_1 = \frac{1}{2}R_1$$

2 → 1

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

RRF.

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 6 & 7 & 8 & 9 \\ 0 & 2 & 3 & 4 \end{pmatrix} \xrightarrow{R_2 = R_2 - 3R_1} \begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & -2 & -4 & -6 \\ 0 & 2 & 3 & 4 \end{pmatrix}$$

$6 \rightarrow 0$

(REF)

$$R_3 = R_3 + R_2$$

$2 \rightarrow 0$

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & -2 & -4 & -6 \\ 0 & 0 & -1 & -2 \end{pmatrix}$$

$$R_2 = -\frac{1}{2}R_2$$

$$R_3 = -1 \cdot R_3$$

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_2 = R_2 - 2R_3$$

$2 \rightarrow 0$

$$\begin{pmatrix} 2 & 3 & 4 & 5 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_1 = R_1 - 4R_3$$

$4 \rightarrow 0$

$$\begin{pmatrix} 2 & 3 & 0 & -3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_1 = R_1 - 3R_2$$

$3 \rightarrow 0$

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

$$R_1 = \frac{1}{2}R_1$$

$2 \rightarrow 1$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{pmatrix}$$

## Solutions of Linear Systems

### Definition:

Basic variable: the variables corresponding to pivot columns in the matrix

Free variable: the other variables

(leading entry  $\leftrightarrow$  basic variable)

acts as the parameter, determines the solution of the system.

Example 3: The augmented matrix of a linear system has been written in the reduced echelon form as follows

$$\begin{array}{ccc|c} x_1 & x_2 & x_3 & \\ \hline 1 & 0 & -5 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{array}$$

(1) Determine the basic variable and free variable.

leading entries  $\Rightarrow$   $\begin{cases} x_1 \\ x_2 \end{cases}$  basic variables  $\begin{cases} 3 \\ 3 \end{cases}$  variables equations  
 $x_3 \rightarrow$  free variable.

(2) Find the general solution of the above system.

set  $x_3 = s$ ,  $s$  can be any number.

from the 2<sup>nd</sup> row  $x_2 + x_3 = 4$   
 $\Rightarrow x_2 = 4 - x_3 = 4 - s$

from the 1<sup>st</sup> row  $\Rightarrow x_1 - 5x_3 = 1$   
 $x_1 = 1 + 5x_3 = 1 + 5s$

parametric form of the solution

$$\begin{cases} x_1 = 1 + 5s \\ x_2 = 4 - s \\ x_3 = s \end{cases}, s \text{ is the parameter \& can be any number.}$$

**Remark 1** *We have some remarks:*

1. Each different choice of  $x_3$  determines a (different) solution of the system, and every solution of the system is determined by a choice of  $x_3$ .
2. Parametric descriptions of solution sets. The free variables act as parameters. Solving a system amounts to finding a parametric description of the solution set or determining that the solution set is empty.
3. Whenever a system is consistent and has free variables, the solution set has many parametric descriptions. Whenever a system is inconsistent, the solution set is empty, even when the system has free variables. In this case, the solution set has no parametric representation.

**Theorem: Existence and Uniqueness Theorem**

A linear system is consistent if and only if the rightmost column of the augmented matrix is not a pivot column —that is, if and only if an echelon form of the augmented matrix has no row of the form

$$[0 \quad \dots \quad 0 \quad b]$$

↓ constant in the equation  
b ≠ 0

$$[0 \quad 0 \quad 0 \quad 1]$$

↓  
 $0 \cdot x_1 + 0 \cdot x_2 + 0 \cdot x_3 = 1$

with  $b$  nonzero.

If a linear system is consistent, then the solution set contains either  $\Rightarrow$  no solution  $\Rightarrow$  inconsistent.

- unique solution, when there is no free variable, or,
- infinitely many solutions, when there is at least one free variable.

Using Row Reduction To Solve A Linear System

free variable determines the solution, it's parameter.

Step 1: Write the **augmented matrix** of the system.

Step 2: Use the **row reduction algorithm** to obtain an equivalent augmented matrix in **echelon form**. Decide whether the system is **consistent**. If there is no solution, stop; otherwise, go to the next step.

Step 3: Continue row reduction to obtain the **reduced echelon form**.

Step 4: Write the **system of equations** corresponding to the matrix obtained in step 3.

Step 5: **Rewrite** each nonzero equation from step 4 so that its one basic variable is expressed in terms of any free variables appearing in the equation.

solve

$$\left( \begin{array}{cccc|c} 1 & -2 & -1 & 3 & 0 \\ -2 & 4 & 5 & -5 & 3 \\ 3 & -6 & -6 & 8 & -3 \end{array} \right)$$

4 variables  
3 equations.

$R_2 = R_2 + 2R_1$   
 $-2 \rightarrow 0$

$$\left( \begin{array}{cccc|c} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 3 & -6 & -6 & 8 & -3 \end{array} \right)$$

$R_3 = R_3 - 3R_1$   
 $3 \rightarrow 0$

$$\left( \begin{array}{cccc|c} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & -3 & -1 & -3 \end{array} \right)$$

$R_3 = R_3 + R_2$   
 $-3 \rightarrow 0$

$$\left( \begin{array}{cccc|c} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$x_1$   
 $x_2$   
 $x_3$   
 $x_4$  free variable.

$x_2$  &  $x_4$  are free, set

$$\begin{cases} x_2 = s \\ x_4 = t \end{cases}$$

$$\begin{cases} x_1 = 2s - \frac{10}{3}t + 1 \\ x_2 = s \\ x_3 = 1 - \frac{t}{3} \\ x_4 = t \end{cases}$$

from row 2,  $3x_3 + x_4 = 3 \Rightarrow x_3 = \frac{1}{3}(3 - x_4) = 1 - \frac{t}{3}$

from row 1,  $x_1 - 2x_2 - x_3 + 3x_4 = 0$

$$\Rightarrow x_1 = 2s + 1 - \frac{t}{3} - 3t = 2s - \frac{10}{3}t + 1$$