## **Section 5.1 Eigenvectors and Eigenvalues**

**Example 1:** Let  $A = \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix}$ ,  $\mathbf{u} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ ,  $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ . The images of  $\mathbf{u}$  and  $\mathbf{v}$  under multiplication by A are shown in Figure .



Note that,  $A\mathbf{v}$  is just  $2\mathbf{v}$ . So A only stretches  $\mathbf{v}$ .

**<u>Definition</u>**: An eigenvector of an  $n \times n$  matrix A is a <u>nonzero</u> vector  $\mathbf{x}$  such that  $A\mathbf{x} = \lambda \mathbf{x}$  for some scalar  $\lambda$ .

A scalar  $\lambda$  is called an eigenvalue of A if there is a nontrivial solution **x** of A**x** =  $\lambda$ **x**, such an **x** is called an eigenvector corresponding to  $\lambda$ .

**Example 2:** Let  $A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$ , show that 7 is an eigenvalue of A and find the corresponding eigenvectors.

 $A \times = \lambda \times$   $A \times - \lambda I \times = 0, I \text{ is the identify multix}$   $(A - \lambda I) \times = 0$ eligendectory exists, if the

.

obst 
$$(A - \lambda I) = 0$$
  
G characteristic egn of  $A$ .

Glep2. The eigen vectors of  $\lambda$ we just non-trival sol of  $(A - \lambda I) \times = 0$ .

we just the eig-build of A.

eg: A: 
$$\binom{1}{5}\binom{1}{2}$$
 Glepz.  
Uet  $(A - AI) = 0$  (d)  
Step 1, we need to find  $\lambda$   
sind that  $(A)$  is true.  
Ull non-zero solutions of  $(A)$   
 $(A - 7I) \cdot X = 0$   $XA$   
 $(A - 7I) \cdot X = 0$   $A - 20$   
 $(A - 7I) \cdot X = 0$   $A - 20$   
 $(A - 7I) \cdot X = 0$   
 $(A - 7I) \cdot X = 0$   $A - 20$   
 $(A - 7I) \cdot X = 0$   
 $(A - 7I) \cdot X = 0$   $A - 7I = (-6 - 6)$   
 $(A - 7I) \cdot (A - 4) = 0$   
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 $(A - 7I) \cdot (A - 4) = 0$   
 $(A - 7I) - (A - 7I) =$ 

ey: 
$$A = \begin{pmatrix} 3 & 0 \\ 2 & 1 \end{pmatrix}$$

slep 1.  
solve for 
$$\lambda$$
  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$   
 $det (A - \lambda I) = 0$   
 $det \begin{pmatrix} 3 - \lambda & 0 \\ 2 & 1 - \lambda \end{pmatrix} = 0$ 

$$(\lambda - 3) (\lambda - 1) = 0$$
  
 $\Rightarrow \lambda_1 = 1, \lambda_2 = 3$   
are eig-val of A.

step 2.  

$$\lambda_{1} = 1$$

$$T_{ind} \times (\neq 0) \quad \text{such that}$$

$$(A - \lambda_{1}I) \times = 0$$

$$A - \lambda_{1}I = \begin{pmatrix} 3 - 1 \\ 2 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$

set 
$$x_{1} = 5$$
 to be fire  
=)  $x_{1} = 0$   
sol  $\{x = s \begin{pmatrix} 0 \\ 1 \end{pmatrix}, s \in Ik\}$   
 $\therefore$  eigen space of  $\lambda_{1} = 1$ .  
 $\lambda_{2} = 3$   
 $T = Ind \times sch$ .  
 $(A - \lambda_{2}I) \times = 0$   
 $A - \lambda_{2}I = \begin{pmatrix} 3-3 & 0 \\ 2 & 1-3 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 2+3 \end{pmatrix}$   
 $x_{1} = s, \Rightarrow x_{1} = s$   
 $\begin{cases} x = s \begin{pmatrix} 1 \\ 1 \end{pmatrix}, s \in Ik \\ \vdots \\ s \in y - space of \lambda_{2} = 3. \end{cases}$ 

**Remark:**  $\lambda$  is an eigenvalue of an  $n \times n$  matrix A if and only if the equation

$$(A - \lambda I)\mathbf{x} = \mathbf{0} \tag{1}$$

has a nontrivial solution.

The set of all solutions of (1) is just the null space of the matrix  $A - \lambda I$ , so this set is a subspace of  $\mathbb{R}^n$ .

It is called the eigenspace of A corresponding to  $\lambda$ , which consists of the zero vector and all the eigenvectors corresponding to  $\lambda$ .  $e^{-1}_{1}$  space - null space of  $(A - \lambda I)$ 

**Example 3:** Let  $A = \begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix}$ . The eigenvalues of A are 1 and 3. Find the eigenspace corresponding to each eigenvalue.

 $\left(\begin{array}{c} \pm 0 \end{array}\right) B = \left(\begin{array}{c} \pm 0 \end{array}\right)$ 

$$A\mathbf{x} = 0\mathbf{x} \tag{2}$$

has a nontrivial solution. But (2) is equivalent to  $A\mathbf{x} = \mathbf{0}$ , which has a nontrivial solution if and only if A is not invertible. Thus

0 is an eigenvalue of A if and only if A is not invertible.



of an  $n \times n$  matrix A, then the set  $\{\mathbf{v}_1, \dots, \mathbf{v}_r\}$  is linearly independent.